

Lecture 8 - Forces in three dimensions

Text: Fowles and Cassiday, Chap. 4

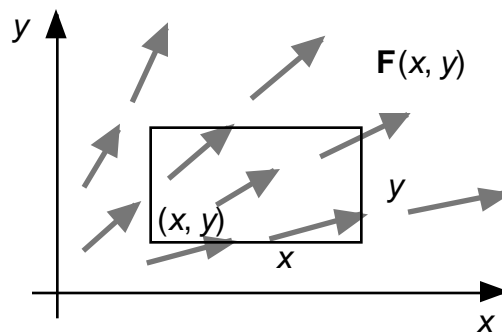
We now revisit some aspects of force in three dimensions. Forces are classified as conservative or nonconservative according to whether their integrals are path-dependent. For example, the force of friction is non-conservative, meaning that the total energy $E = K + V$ is not conserved. Where the path-dependence of a non-conservative force shows up is in the evaluation of a quantity like the work:

Conservative: W depends only on end-points of $\mathbf{F} \cdot d\mathbf{r}$

Nonconservative: W depends on integration path

Because the work associated with non-conservative forces is path-dependent, and because $W = -\Delta V$, then a potential energy cannot be defined for a non-conservative force: V would depend upon the history of a system, not just its configuration.

So how can we tell mathematically whether a force is conservative without having to evaluate $\mathbf{F} \cdot d\mathbf{r}$ for various paths? Consider a rectangular path in the xy -plane. Let the force be a function of x and y on this plane, as in



Around this closed integration loop, the work done on the system is

$$W = \oint \mathbf{F} \cdot d\mathbf{r}$$

Since the work is equal to the change in potential energy of a conservative force, then the work should vanish if the force is conservative. That is, if the potential energy is a well-defined, path-independent quantity, then a closed line integral around the force field should vanish.

We perform the integral as in the diagram

$$\oint \mathbf{F} \cdot d\mathbf{r} = \int_x^{x+\Delta x} F_x(y) dx + \int_y^{y+\Delta y} F_y(x+\Delta x) dy + \int_{x+\Delta x}^x F_x(y+\Delta y) dx + \int_{y+\Delta y}^y F_y(x) dy$$

or

$$\oint \mathbf{F} \cdot d\mathbf{r} = \int_x^{x+\Delta x} [F_x(y) - F_x(y+\Delta y)]dx + \int_y^{y+\Delta y} [F_y(x+\Delta x) - F_y(x)]dy \quad (8.1)$$

Assume that Δx and Δy are small enough that one can perform a Taylor series expansion about $\mathbf{F}(x, y)$. Note that both F_x and F_y both vary with x and y .

$$F_x(y+\Delta y) = F_x(y) + \Delta y [F_x(y) / \Delta y] \quad (8.2)$$

$$F_y(x+\Delta x) = F_y(x) + \Delta x [F_y(x) / \Delta x] \quad (8.3)$$

Substituting Eqs (8.2) and (8.3) into (8.1) gives

$$\oint \mathbf{F} \cdot d\mathbf{r} = - \int_x^{x+\Delta x} \Delta y [F_x(y) / \Delta y] dx + \int_y^{y+\Delta y} \Delta x [F_y(x) / \Delta x] dy$$

By the assumptions of the Taylor series, the terms inside the integrals are constant, leaving us to evaluate terms like

$$\int_x^{x+\Delta x} dx = \Delta x$$

Hence

$$\oint \mathbf{F} \cdot d\mathbf{r} = \Delta x \Delta y [F_y(x) / \Delta x - F_x(y) / \Delta y]$$

This integral is proportional to the enclosed area $\Delta x \Delta y$. Thus, the condition that the integral vanishes is then

$$F_y(x) / \Delta x - F_x(y) / \Delta y = 0$$

This result can be generalized to higher dimensions.

First, note that

- $\Delta x \Delta y \rightarrow da$ over the area a enclosed by the loop
- $F_y / \Delta x - F_x / \Delta y$ transforms like a component of a vector, and can be made to look like a vector using $[0, 0, F_y / \Delta x - F_x / \Delta y]$.

Writing this out for a general orientation of the area element becomes

$$[F_z / \Delta y - F_y / \Delta z, F_x / \Delta z - F_z / \Delta x, F_y / \Delta x - F_x / \Delta y] = \text{curl } \mathbf{F} = \nabla \times \mathbf{F}$$

where the del operator is

$$\nabla = (\partial / \partial x, \partial / \partial y, \partial / \partial z) = \mathbf{i}(\partial / \partial x) + \mathbf{j}(\partial / \partial y) + \mathbf{k}(\partial / \partial z)$$

and where $\mathbf{i}, \mathbf{j}, \mathbf{k}$ are unit vectors pointing along the Cartesian axes.

$\text{curl } \mathbf{F} = \nabla \times \mathbf{F}$ is a vector (from the cross product)
 $\text{grad } V = \nabla V$ is a vector (V is a scalar function)

Hence, $\oint \mathbf{F} \cdot d\mathbf{r} = \int (\text{curl } \mathbf{F}) \cdot \mathbf{n} da$, a result known as Stoke's theorem (\mathbf{n} is a unit vector normal to a surface bounded by the path of the line integral: $d\mathbf{r} \rightarrow \mathbf{n} da$)

OK, so $\text{curl } \mathbf{F}$ vanishes for a conservative force. What does this tell us about the potential energy V ? Back in first year, we showed that a non-dissipative force \mathbf{F} is related to a potential V through

$$F_i = - \partial V / \partial x_i$$

Does this satisfy $\text{curl } \mathbf{F} = 0$? Just take one component:

$$\frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} = - \frac{\partial^2 V}{\partial x \partial y} + \frac{\partial^2 V}{\partial y \partial x} = 0$$

If $\mathbf{F} = - \nabla V$, then it is easy to see that \mathbf{F} is a conservative force because

$$\int_A^B \mathbf{F} \cdot d\mathbf{r} = - \int_A^B \nabla V \cdot d\mathbf{r} = - \int_A^B dV = - (V_B - V_A)$$

Of course the work is also equal to the change in kinetic energy K , and so we have

$$K = - V \quad \text{or} \quad (K + V) = 0 \quad \text{or} \quad E = 0$$

Lastly, if the force is dissipative, one cannot write $\mathbf{F} = - \nabla V$. Then, the convention is to break up \mathbf{F} into two pieces,

$$\mathbf{F} = \mathbf{F}_{\text{cons}} + \mathbf{F}_{\text{non-cons}}$$

so that

$$\mathbf{F} \cdot d\mathbf{r} = \mathbf{F}_{\text{cons}} \cdot d\mathbf{r} + \mathbf{F}_{\text{non-cons}} \cdot d\mathbf{r}$$

for which

$$\int \mathbf{F}_{\text{non-cons}} \cdot d\mathbf{r} = E - 0.$$

Example Is $\mathbf{F} = i(ax + by^2) + jcx$ conservative?

1. Since there is no z - dependence to \mathbf{F} , then all $F_i / \partial z = 0$.
2. Since $F_z = 0$, then all $F_z / \partial x_i = 0$.
3. Thus, the only possible non-zero component of $\text{curl } \mathbf{F}$ is the z - component:

$$\begin{aligned} & \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \\ &= (cx) / \partial x - (ax + by^2) / \partial y \\ &= (c - 2b)y \end{aligned}$$

Hence, $\text{curl } \mathbf{F} = 0$ if $c = 2b$. The value of a is unimportant. Finding the curl is a much easier procedure than integrating $\mathbf{F} \cdot d\mathbf{r}$ over paths to find a consistent expression for $V(x, y)$.