

# Problem Set #8 Answer Key

Economics 435: Quantitative Methods

Fall 2011

Please use WebCT to turn in both the Word document and R code for question (1) and turn in your answer to question (2) in class.

## 1 Public sector unionization and the size of government: Part V

Please see the file <http://www.sfu.ca/~bkrauth/econ435/restricted/psu5.pdf>. The R code used to generate these results is available at <http://www.sfu.ca/~bkrauth/econ435/restricted/qunionization5.r>

## 2 Fixed effects with measurement error

a)

$$\begin{aligned}\text{plim } \hat{\beta}^{OLS} &= \text{plim } \frac{\text{cov}(y_{it}, \tilde{x}_{it})}{\text{var}(\tilde{x}_{it})} \\ &= \frac{\text{cov}(y_{it}, \tilde{x}_{it})}{\text{var}(\tilde{x}_{it})} \\ &= \frac{\text{cov}(a_i + \beta x_i + \beta v_{it} + u_{it}, x_i + v_{it} + \epsilon_{it})}{\text{var}(x_i + v_{it} + \epsilon_{it})} \\ &= \frac{\text{cov}(a_i, x_i) + \beta \text{var}(x_i) + \beta \text{var}(v_{it})}{\text{var}(x_i) + \text{var}(v_{it}) + \text{var}(\epsilon_{it})} \\ &= \frac{\beta(\sigma_x^2 + \sigma_v^2) + \sigma_x \sigma_a \rho_{a,x}}{(\sigma_x^2 + \sigma_v^2) + \sigma_\epsilon^2}\end{aligned}$$

b)

$$\begin{aligned}\text{plim } \hat{\beta}^{FD} &= \text{plim } \frac{\text{cov}(\Delta y_{it}, \Delta \tilde{x}_{it})}{\text{var}(\Delta \tilde{x}_{it})} \\ &= \frac{\text{cov}(\Delta y_{it}, \Delta \tilde{x}_{it})}{\text{var}(\Delta \tilde{x}_{it})} \\ &= \frac{\text{cov}(\beta \Delta v_{it} + \Delta u_{it}, \Delta v_{it} + \Delta \epsilon_{it})}{\text{var}(\Delta v_{it} + \Delta \epsilon_{it})} \\ &= \frac{\beta \text{var}(\Delta v_{it})}{\text{var}(\Delta v_{it}) + \text{var}(\Delta \epsilon_{it})} \\ &= \beta \frac{\sigma_v^2}{\sigma_v^2 + \sigma_\epsilon^2}\end{aligned}$$

c) If there is no fixed effect, then the probability limit of the OLS estimator is:

$$\text{plim } \hat{\beta}^{OLS} = \beta \frac{(\sigma_x^2 + \sigma_v^2)}{(\sigma_x^2 + \sigma_v^2) + \sigma_\epsilon^2}$$

Since  $\frac{(\sigma_x^2 + \sigma_v^2)}{(\sigma_x^2 + \sigma_v^2) + \sigma_\epsilon^2}$  is closer to one than  $\frac{\sigma_v^2}{\sigma_v^2 + \sigma_\epsilon^2}$  is, the OLS estimator has smaller asymptotic bias.

d) If the fixed effect is uncorrelated with  $x_i$ , then the probability limit of the OLS estimator is:

$$\text{plim } \hat{\beta}^{OLS} = \beta \frac{(\sigma_x^2 + \sigma_v^2)}{(\sigma_x^2 + \sigma_v^2) + \sigma_\epsilon^2}$$

Since  $\frac{(\sigma_x^2 + \sigma_v^2)}{(\sigma_x^2 + \sigma_v^2) + \sigma_\epsilon^2}$  is closer to one than  $\frac{\sigma_v^2}{\sigma_v^2 + \sigma_\epsilon^2}$  is, the OLS estimator has smaller asymptotic bias.

e) If there is no measurement error, then the probability limit of the OLS estimator is:

$$\text{plim } \hat{\beta}^{OLS} = \frac{\beta(\sigma_x^2 + \sigma_v^2) + \sigma_x \sigma_a \rho_{a,x}}{(\sigma_x^2 + \sigma_v^2)}$$

and the probability limit of the FD estimator is

$$\text{plim } \hat{\beta}^{FD} = \beta$$

Since the FD estimator is consistent and the OLS estimator is not, the FD estimator obviously has smaller asymptotic bias.

f) The first statement is the correct one.