

A Joint Symbol Detection Algorithm Efficient at Low SNR for a Multi-Device STBC-MIMO System

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Motivation

- The Optimal detector (maximum likelihood (ML) detector) for Multi-device STBC-MIMO is computationally expensive.
- The Sphere decoding algorithms operation at a low SNR requires inordinately high computation.
- There is need of low complexity algorithms for Multi-device STBC-MIMO systems.

Problem Formulation

- K = Number of Mobile devices/users
- N_B = Total number of transmitted symbols
- N_R = Number of receive antennas
- N_T = Number of receive antennas
- X_k = Symbols transmitted from the k th device
- Y = received signal
- M = Size of symbol constellation
- $b = \log_2(M)$
- m = Problem size

Problem Formulation

- Consider the case of single mobile device, $K=1$.
- For T time slots in the space-time code block, the relation between the input and output signal is

$$\tilde{Y} = S \cdot H + \tilde{Z}, \quad H \in \mathbb{C}^{N_T \times N_R}, \quad S \in \mathbb{C}^{T \times N_T}, \quad \tilde{Y} \in \mathbb{C}^{T \times N_R},$$

where

$$S = \sum_{q=1}^Q \left[(\alpha_q + j\beta_q) C_q + (\alpha_q - j\beta_q) D_q \right]$$

Q is the number of symbols in a space time code block.
 Q is complex.

- An alternative representation is

$$Y = X \Omega + Z, \quad \Omega \in \mathbb{R}^{2Q \times 2TN_R}$$

Problem Formulation

- For multiple mobile devices

$$\tilde{Y} = \sum_{k=1}^K S_k \cdot H_k + \tilde{Z}, S_k \in \mathbb{C}^{T \times N_T}, H_k \in \mathbb{C}^{N_T \times N_R}$$

- An alternative representation is

$$Y = \begin{bmatrix} X_1 & X_2 & \cdots & X_K \end{bmatrix} \begin{bmatrix} \Omega_1 \\ \Omega_2 \\ \vdots \\ \Omega_K \end{bmatrix} + Z$$

Optimum Detector

Maximum Likelihood (ML) Detection

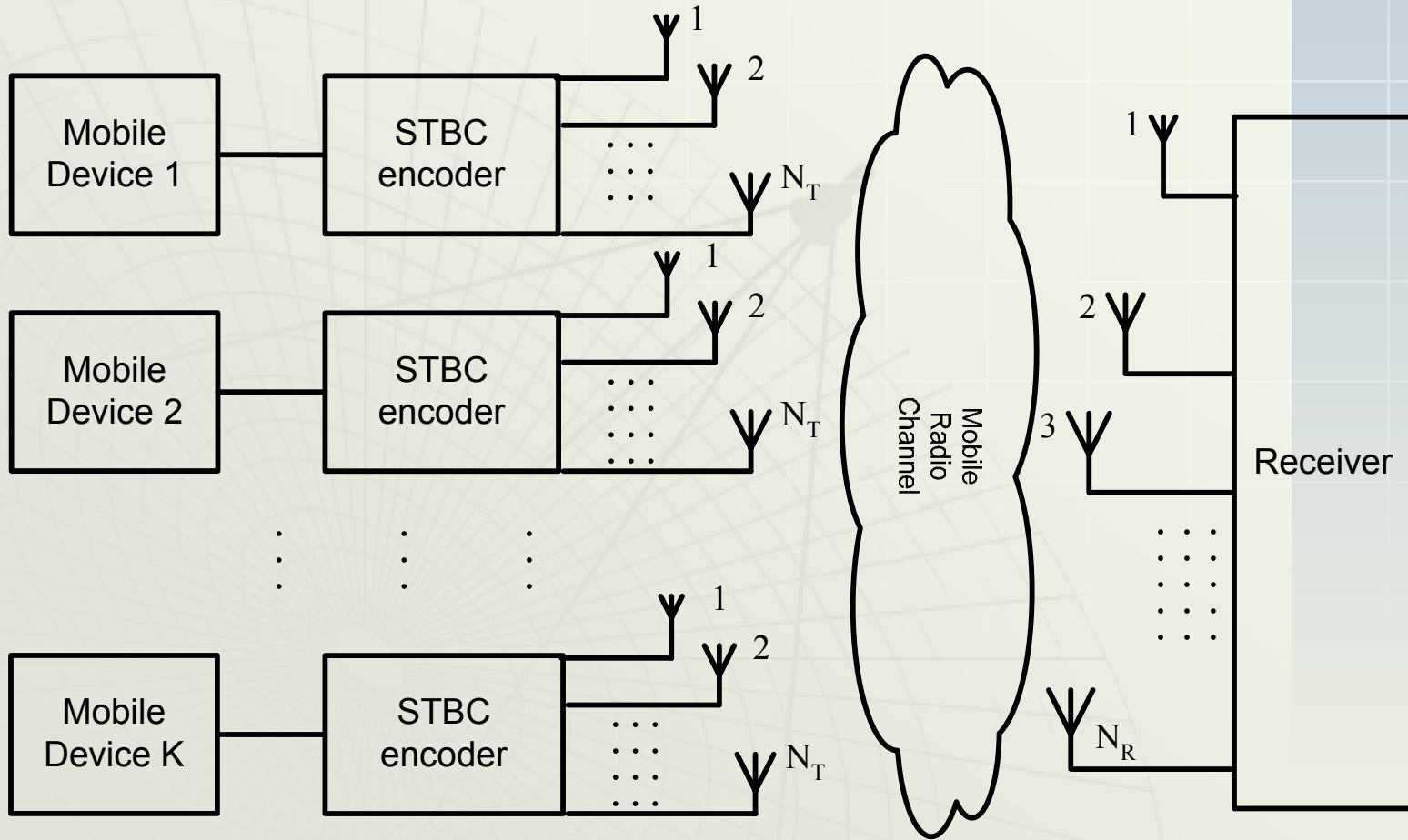
$$\arg \min \left\| Y - \sum_{k=1}^K X_k \Omega_k \right\|$$

ML Complexity

- Exponential Complexity (NP-Hard Problem i.e. Can not solve in polynomial time)

- Exhaustive Search with Search Space exponent

$$M^{N_B} = 2^{bN_B}$$



Cross Entropy Optimization

- The Cross-Entropy optimization is a generalized Monte Carlo technique to solve combinatorial optimization problems
- In general the CEO first associates the target combinatorial optimization problem with a rare-event estimation problem, and then solves the problem iteratively in two phases.
- In first phase the CEO generates a sample of random data according to a specified random mechanism.
- In the second phase it updates the parameters of the random mechanism, typically parameters of probability distribution, on the basis of the data, to produce a better sample in the next iteration.

Cross Entropy Optimization

- Consider a maximization problem: $\underset{x \in \mathcal{X}}{\text{maximize}} \quad F(x)$
- Let us denote a maximum by x^* and the maximal function value by γ^* .
- $f(x; u), x \in \mathcal{X}$ is an arbitrary probability mass function used in at a stage in iterations.
- Hypothetically, if pmf

$$g(x; \gamma, u) = \frac{I_{\{F(x) \geq \gamma\}} f(x; u)}{\sum_{x \in \mathcal{X}} I_{\{F(x) \geq \gamma\}} f(x; u)} \equiv \frac{I_{\{F(x) \geq \gamma\}} f(x; u)}{l(u, \gamma)}$$

is used as the pmf at the next iteration, then every sample generated from this distribution will be a high-quality candidate.

- The CEO algorithm uses in place of $g(x; \gamma, u)$ the pmf that is closest to $g(x; \gamma, u)$ in terms of Kullback-Leibler (KL) distance (cross entropy). That is, the pmf v that minimizes

$$\begin{aligned} D(g(x; \gamma, u) \| f(x; v)) &= \sum_{x \in \mathcal{X}} g(x; \gamma, u) \ln \frac{g(x; \gamma, u)}{f(x; v)} \\ &= \sum_{x \in \mathcal{X}} g(x; \gamma, u) \ln g(x; \gamma, u) - \sum_{x \in \mathcal{X}} g(x; \gamma, u) \ln f(x; v) \end{aligned}$$

- Minimizing this KL-distance by choosing pmf v is equivalent to maximizing

$$\sum_{x \in \mathcal{X}} g(x; \gamma, u) \ln f(x; v),$$

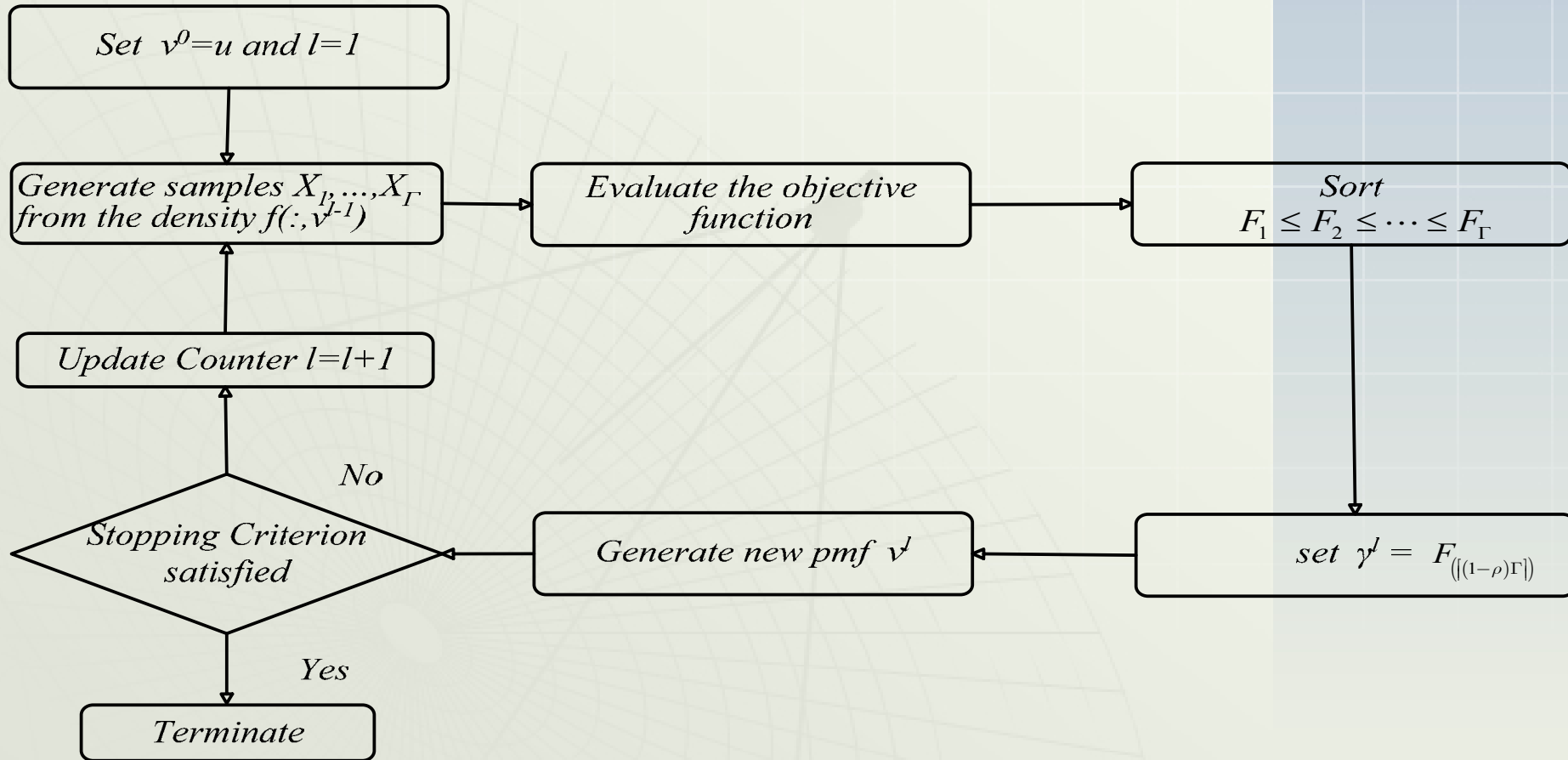
- This is also equivalent to maximizing

$$\sum_{x \in \mathcal{X}} I_{\{F(x) \geq \gamma\}} f(x; u) \ln f(x; v) = E_u \left[I_{\{F(X) \geq \gamma\}} \ln f(X; v) \right],$$

- In order to avoid computational complexity, a CE algorithm finds in the family of pmfs, a pmf v that results in the largest

$$\frac{1}{\Gamma} \sum_{i=1}^{\Gamma} I_{\{F(X_i) \geq \gamma\}} \ln f(X_i; v),$$

- In general, CE algorithm proceeds as:
1. Define $v^0=u$, Set $l=1$ (Iteration counter)
 2. Generate samples X_1, \dots, X_Γ from the density $f(:, v^{l-1})$
 3. Evaluate the objective function and order them from the smallest to largest: $F_1 \leq F_2 \leq \dots \leq F_\Gamma$ Then set the $(1-\rho)$ -quantile v^l as $v^l = F_{((1-\rho)\Gamma)}$
 4. Use the same samples X_1, \dots, X_Γ to obtain a new pmf that results in largest (10). Denote this pmf by index v^l .
 5. If stopping criterion satisfied then terminate otherwise set $l=l+1$ and reiterate from step 2.



Cross Entropy Optimization For STBC-MIMO

We define the following parameters

1. F denotes the fitness or objective function, which is the target function to be optimized.
2. Γ is the sample size, or population.
3. Parameter m is the dimension of each sample or individual.
4. P is the parameter vector, which indicates the pmf used to generate the random samples.
5. ρ is the rarity parameter. In each iteration, a threshold γ is set to select $\rho\Gamma$ best samples among Γ samples to update P .
6. α is the smoothing parameter.
7. ε is the tolerance. The iteration is stopped when F is within $\pm\varepsilon$ of the target value.
8. I is the maximum number of iterations. The iteration is stopped when I is reached.

Pseudo code of CEO For Sensor Selection

Phase 1:

Initialize ($P^{l=0}$, ρ , α , ϵ). Generate initial Γ data samples from Bernoulli probabilities using parameter vector $P^{l=0}$.

Phase 2:

while (tolerance $< \epsilon$ or $l < I$)

Evaluate fitness function F for these Γ data samples.

Get the current best value.

If (best fitness value $<$ current best value)

best fitness value = current best value

end

Sort the Γ data samples according to their fitness value.

Set $\gamma^l = F_{((1-\rho)\Gamma)}$.

Select the samples whose fitness values are greater than γ^l

Generate new parameter vector P^l from selected data samples.

Update parameter vector using the relation

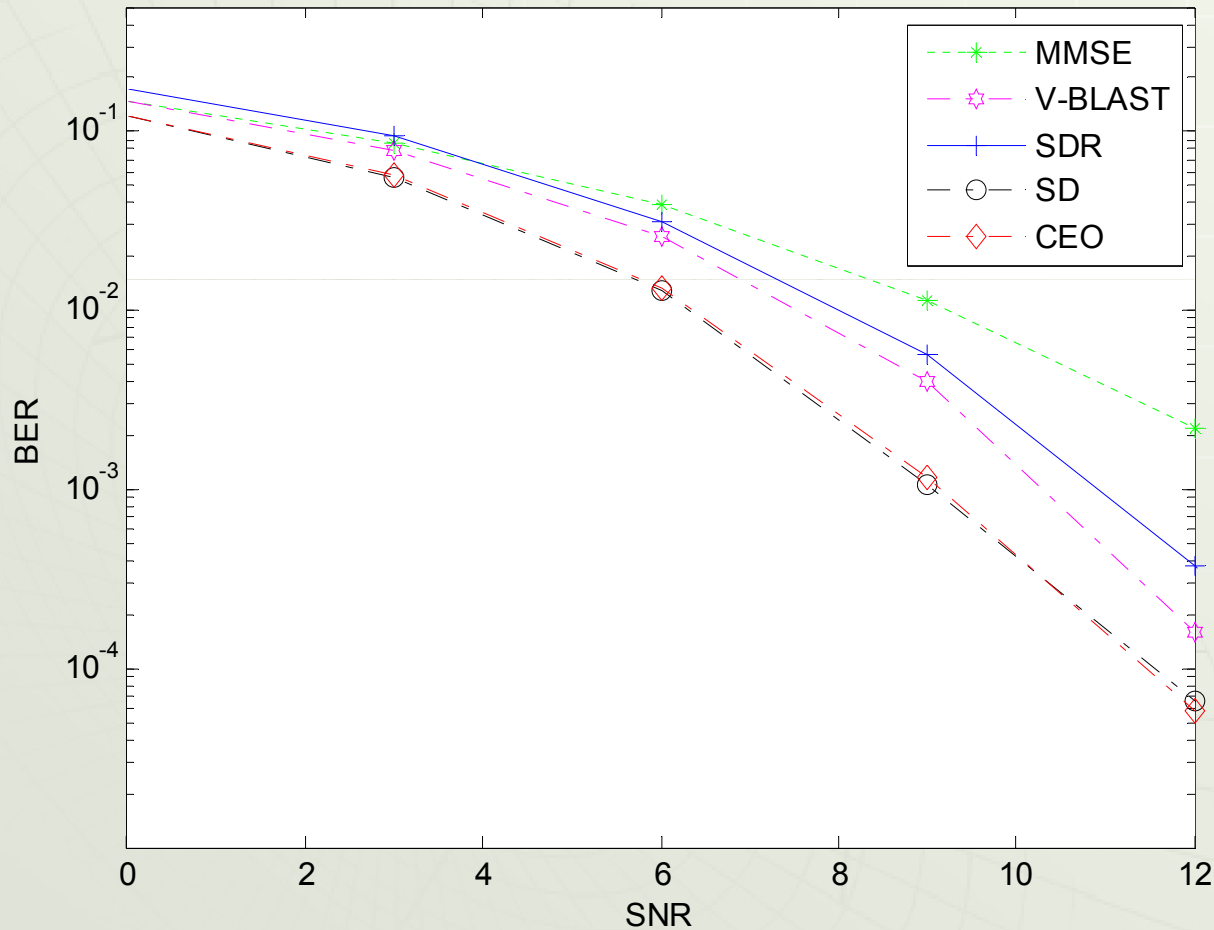
$$P^l = (1 - \alpha)P^{l-1} + \alpha P^l$$

Generate new $(1-\rho)\Gamma$ samples on the basis of this updated parameter vector P .

End % end while loop

Simulation Results

Bit Error Rate (BER) Performance



Parameters

$$N_T=4$$

$$K=3$$

4-QAM

$$N_R=4$$

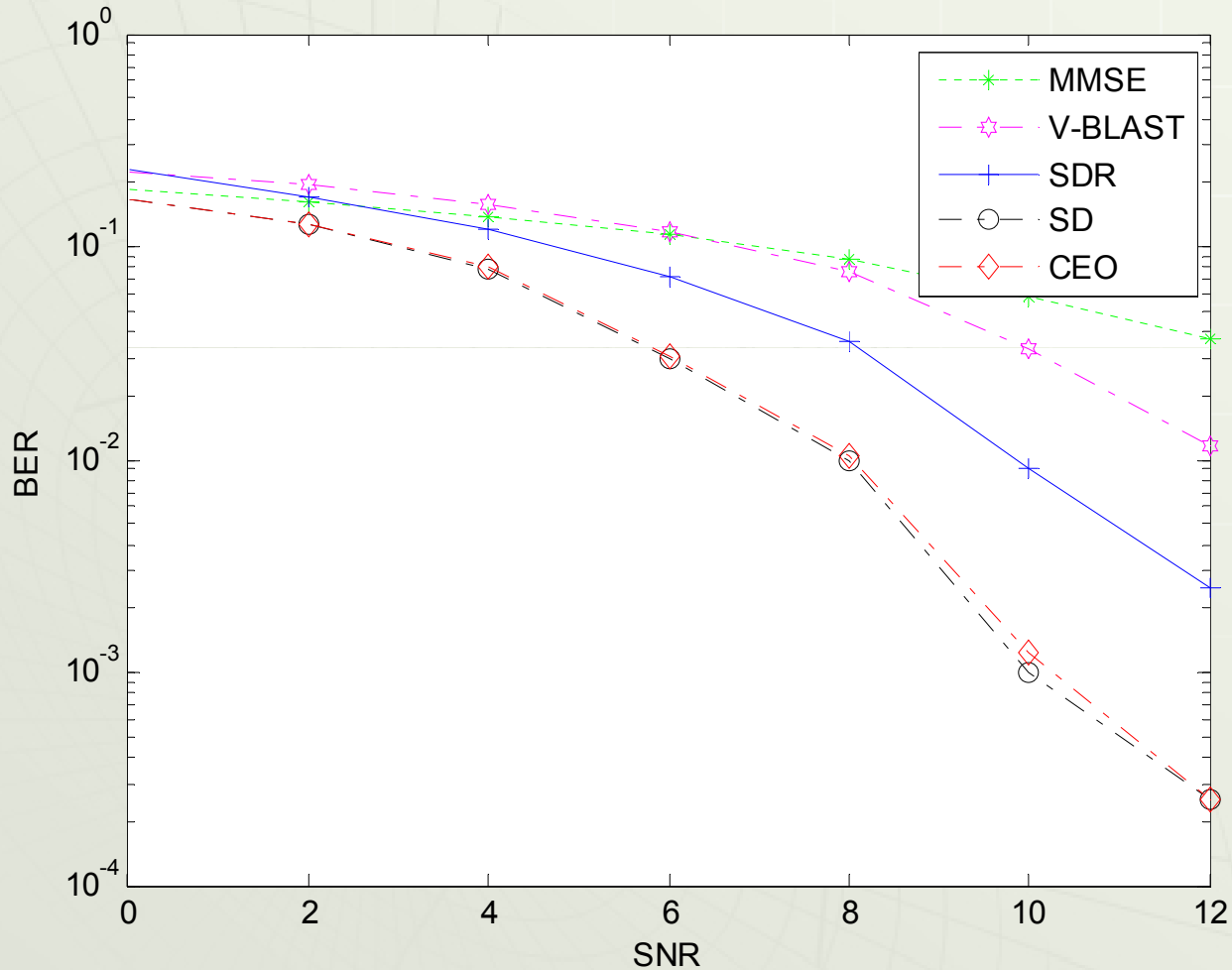
$$\Gamma = 100$$

$$\alpha = 0.7$$

$$\rho = 0.3$$

$$m = 24$$

Bit Error Rate (BER) Performance



Parameters

$$N_T = 2$$

$$K = 5$$

4-QAM

$$N_R = 5$$

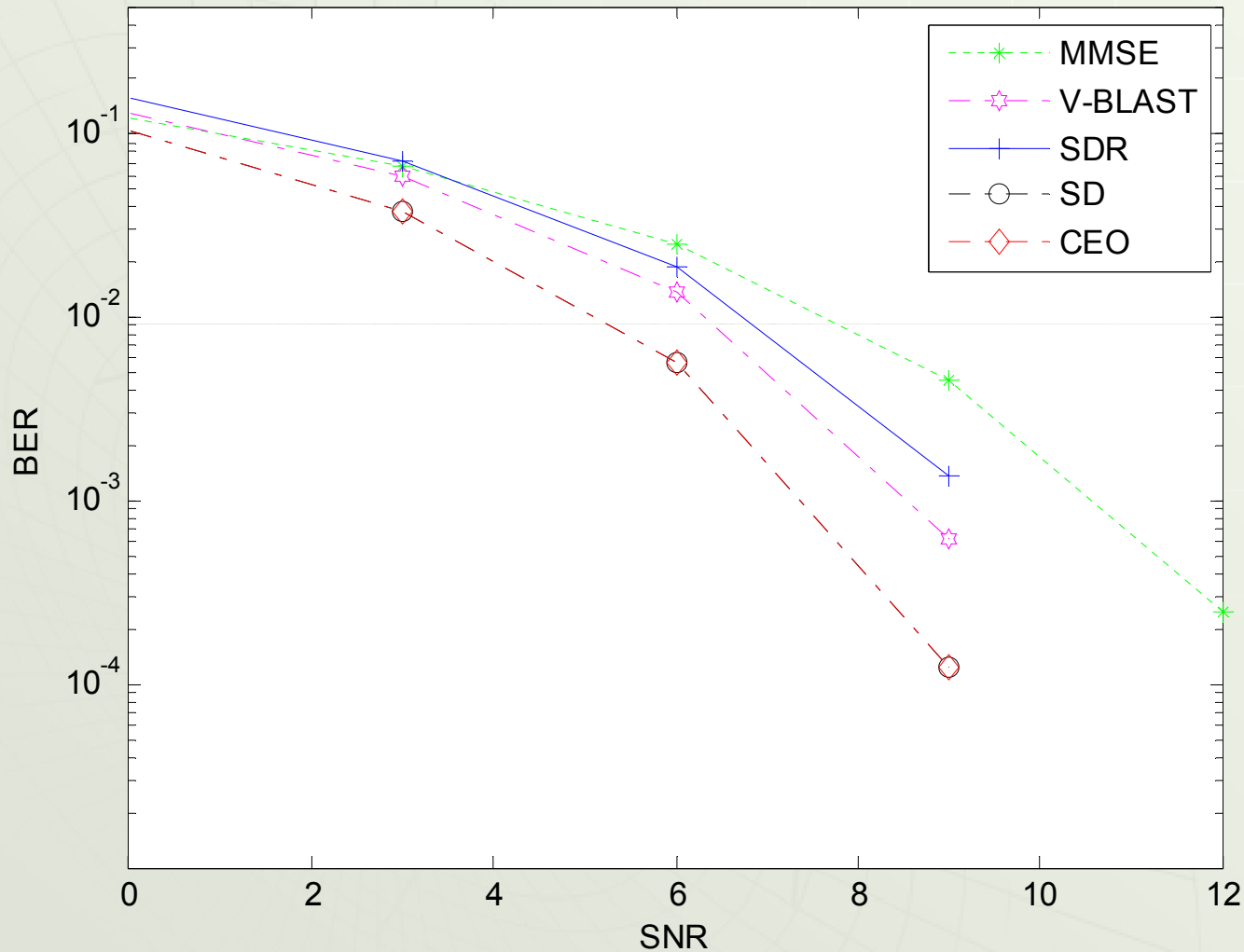
$$\Gamma = 200$$

$$\alpha = 0.7$$

$$\rho = 0.3$$

$$m = 20$$

Bit Error Rate (BER) Performance



Parameters

$$N_T = 2$$

$$K = 4$$

4-QAM

$$N_R = 6$$

$$\Gamma = 80$$

$$\alpha = 0.7$$

$$\rho = 0.3$$

$$m = 16$$

Complexity Comparison

Problem Dimension $m \equiv N_B \log_2 M$

- ML $O(2^m)$
- MMSE $O(m^3)$
- V-BLAST $O(m^3)$
- Sphere Decoder $O(m^6)$
- CEO $O(\Gamma I)$

Conclusions

- The Optimal detector (maximum likelihood (ML) detector) for Multi-device STBC-MIMO is computationally expensive.
- The performance of CEO algorithm is close to the Sphere decoder and better than SDR.
- Complexity of CEO is less than sphere decoder and SDR.

Questions ?