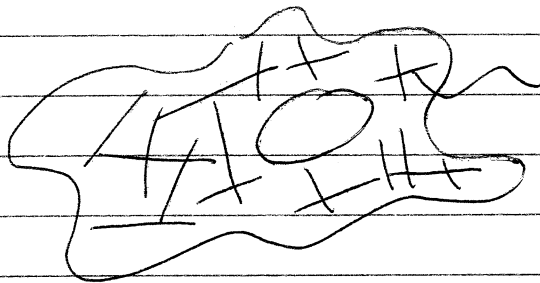


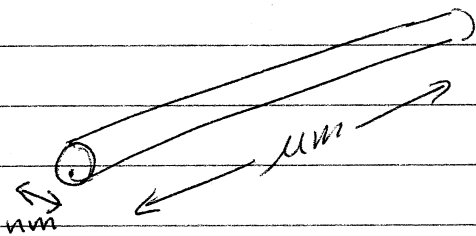
# Cellular Architecture: Biomolecular Beams

- Many biomolecules are filamentous: microtubules, actin, collagen, hair-cell bundles, DNA, flagellum



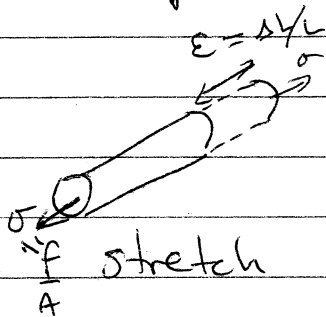
cytoskeleton,  $\equiv$  network of actin filaments

beam  $\equiv$  longitudinal length  $\gg$  lateral length



e.g. actin filament

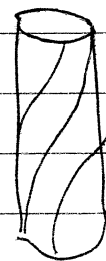
## Deforming beams



$\sigma = E \epsilon$



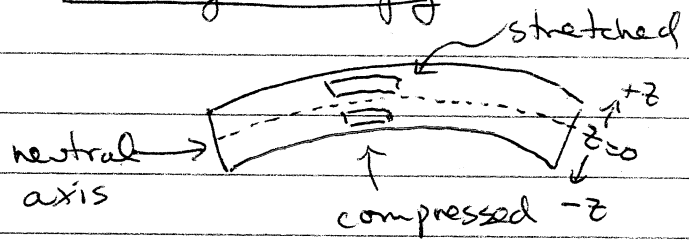
bend



twist

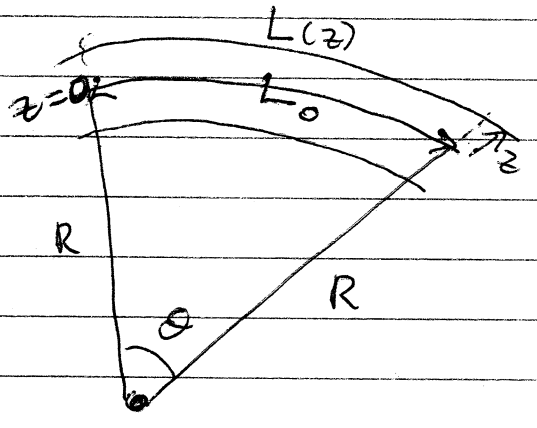
what is the energy cost for these deformations?

# Bending Energy



- The region above the neutral axis is stretched and below is compressed

- Locally, a bent region will fall on a circular arc of radius  $R$



- What is  $\Delta L(z) = L(z) - L_0$ ?

$$L_0 = R\theta \Rightarrow \theta = \frac{L_0}{R}$$

and

$$L(z) = (R+z)\theta = (R+z)\frac{L_0}{R}$$

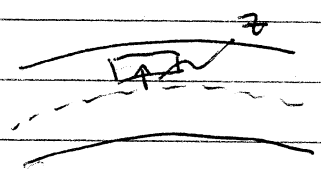
so

$$\Delta L(z) = (R+z)\frac{L_0}{R} - L_0 = \frac{zL_0}{R}$$

so

strain, 
$$\epsilon = \frac{\Delta L(z)}{L_0} = \frac{z}{R}$$

## Energetic cost for small volume element

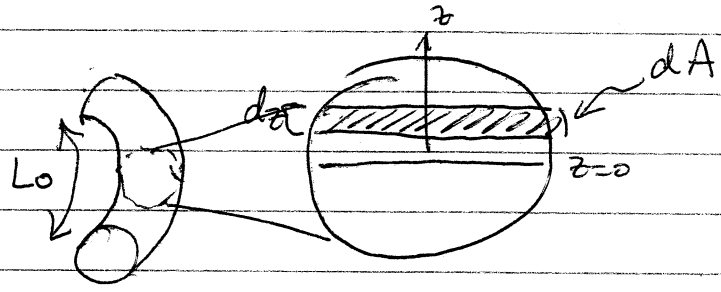


$$w(z) = \frac{1}{2} E \epsilon(z)^2 = \frac{1}{2} E \left( \frac{\Delta L(z)}{L_0} \right)^2$$

energy density

$$= \frac{1}{2} E \frac{z^2}{R}$$

Now need to integrate this:

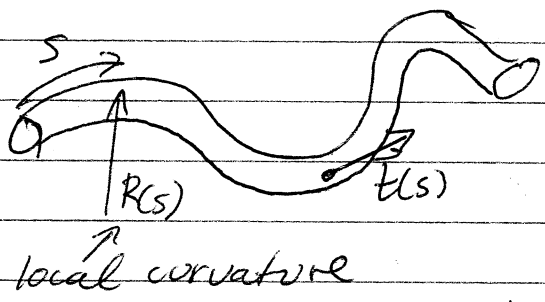


so

$$E_{\text{bend}} = L_0 \int dA \frac{E}{2R^2} z^2$$

or 
$$E_{\text{bend}} = L_0 \frac{EI}{2R^2} ; I = \underbrace{\int dA z^2}_{\text{moment of material}}$$

More generally, what if beam has an arbitrary bent shape



$$E_{\text{bend}} = \frac{K_{\text{eff}}}{2} \int_0^L ds \frac{1}{R(s)^2}$$

where  $K_{\text{eff}} = E \cdot I \equiv \text{material constant}$

• If we have  $\vec{t}(s) \equiv \text{tangent vector to the curve}$  then

$$K(s) = \frac{1}{R(s)} = \left| \frac{d\vec{t}}{ds} \right| \equiv \text{curvature}$$

### Connection to persistence length

- The bend degree of freedom will have  $k_B T$  of energy due to thermal kicks.
- Persistence length  $\equiv$  length @ which polymer loops back so  $L \approx R = \xi_p$

so  $k_B T = \frac{EIL}{2R^2} \approx \frac{EI}{2\xi_p^2}$  (estimate)

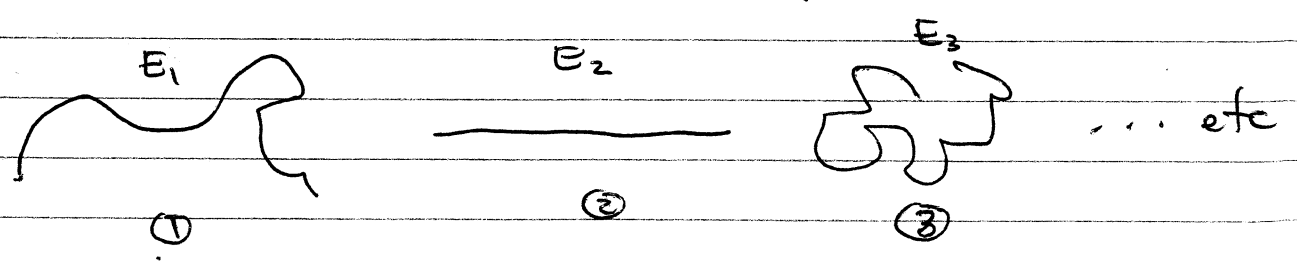
or  $\xi_p \approx \sqrt{\frac{EI}{k_B T}}$  (more sophisticated calculation)

- gets smaller @ higher temperature (makes sense)
- gets larger as  $E$  gets bigger (makes sense)

also  $EI = \xi_p^2 k_B T = K_{eff}$

### Worm-like Chain:

- We can now compute the energy of a given bent shape
- What is the most likely shape?



Need to calculate the partition function

$$Z = \sum_{\text{shapes}} \exp\left(-\frac{E_{\text{band}}}{k_B T}\right) = \sum_{\text{shapes}} \exp\left(-\frac{\epsilon_p}{2} \int_0^L \left|\frac{d\vec{t}(s)}{ds}\right|^2 ds\right)$$

Now there are an infinite # of shapes so  $\sum_{\text{shapes}} \rightarrow \int$

so

$$Z = \int D\vec{t}(s) \exp\left(-\frac{\epsilon_p}{2} \int_0^L \left|\frac{d\vec{t}}{ds}\right|^2 ds\right)$$

- This includes the competition between entropy and energy, because some values of the energy will have many corresponding shapes  $\rightarrow$  high entropy
- The  $\int D\vec{t}(s)$  is a Feynman path integral
- Now imagine pulling on the polymer with a force,  $F_k$
- so the polymer does work  $-F \int_0^L t_z ds$  for a given shape
- What is  $\langle z \rangle$  for a given force  $F$ ?

$$\langle z \rangle = \frac{1}{Z} \int D\vec{t}(s) z \exp\left(-\frac{\epsilon_p}{2} \int_0^L \left|\frac{d\vec{t}}{ds}\right|^2 ds + \frac{F}{k_B T} \int_0^L t_z ds\right)$$

$$\left( = \int z p(z) \text{ just fancier way of writing it} \right)$$

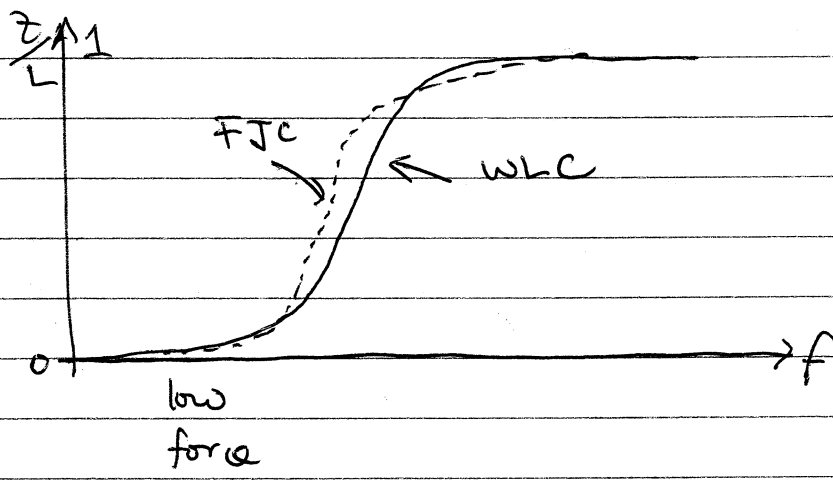
To evaluate this requires some fancy math.

In the low force limit:  $f \ll f_{zp} \ll 1 \rightarrow f_{zp} = \frac{3}{2} \frac{Lz}{L}$

which is the same as FJC

An interpolation formula (Marko & Siggia) results

$$f_{zp} \approx \frac{z}{L} + \frac{1}{4(1 - (\frac{z}{L})^2)} - \frac{1}{4}$$



Data from optical tweezers can be fit with WLC to find  $z_p$  &  $L$