

Internal Wave Attractors and Spectra of Zeroth-order Pseudo-differential Operators

M.Sc. Thesis Defence | Mathematics

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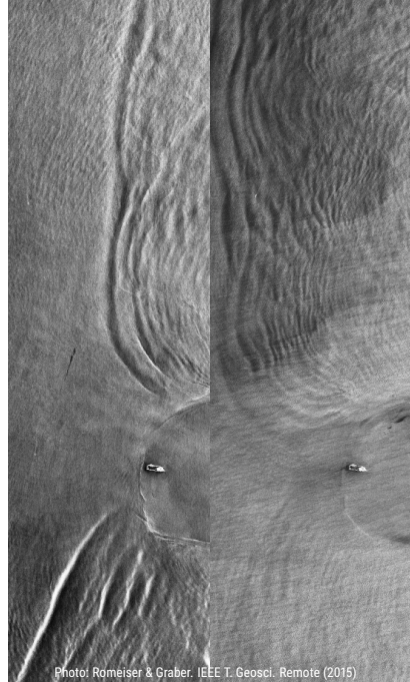


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| **Motivation: Internal Waves
in Stratified Media**

Internal Waves in a Stratified Medium

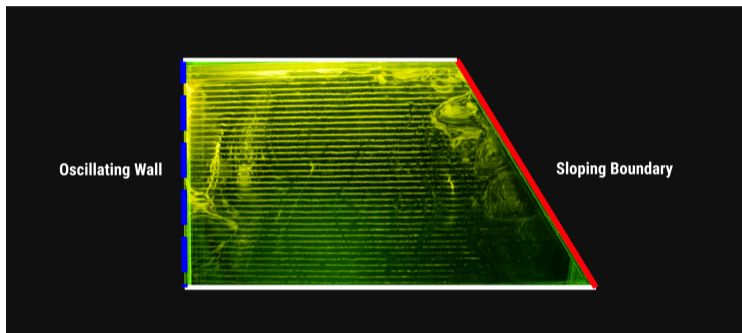


Figure: Benchmark experiment¹ for capturing internal waves. Video: [Local](#) | [YouTube](#)

¹G. Davis. et al. *Phys. Rev. Lett.* 124.20 (2020).

A pseudo-differential approach

- Fluid assumed to be incompressible, stably-stratified, non-rotating.
- Base model: conservation of mass and momentum + Boussinesq approximation.
- Density ρ and pressure Π evolve as perturbations of a hydrostatic state:

$$\begin{aligned}\rho(x, t) &= \bar{\rho}(x_3) + \rho'(x, t), \\ \Pi(x, t) &= \bar{\Pi}(x_3) + \Pi'(x, t).\end{aligned}$$

$$\frac{\partial \mathbf{u}}{\partial t} = -\frac{1}{\rho_0} \nabla \Pi' - \frac{\rho' g}{\rho_0} \mathbf{e}_3 \quad / \quad \nabla \cdot$$

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$$\Pi' = (-\Delta)^{-1} \partial_{x_3} \rho'$$

Diagonalization

$$\partial_t \begin{pmatrix} \hat{\rho}' \\ \hat{u}_3 \end{pmatrix} + \begin{bmatrix} 0 & -\frac{d\bar{\rho}}{dx_3} \\ -\frac{g}{\rho_0} \left(1 - \frac{\xi_3^2}{|\xi|^2}\right) & 0 \end{bmatrix} \begin{pmatrix} \hat{\rho}' \\ \hat{u}_3 \end{pmatrix} = 0$$

Here $\mathbf{u} = (\mathbf{u}_H, u_3)$. Assume: $\mathbf{u} = u_+ \mathbf{e}_+ + u_- \mathbf{e}_-$. Then, u_{\pm} solve

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$$i\partial_t u_{\pm} \mp \mathcal{P}(D)u_{\pm} = 0,$$

where $\mathcal{P}(D)$ is the **zeroth-order** pseudo-differential operator of symbol

$$p(\xi) = \sqrt{-\frac{g}{\rho_0} \frac{d\bar{\rho}}{dx_3} \frac{\xi_3}{|\xi|}}, \quad \xi \in \mathbb{R}^3.$$

Microlocal Analysis of Linear Forced Waves

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- Physics observations² suggest that internal wave attractors make the fluid flow **highly singular**.
- The fact that they develop for a wide range of frequencies suggests the existence of a **continuous spectrum**.

⁴L.R.M. Maas. *Int. J. Bifurcat. Chaos* 15.9 (2005).

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- Colin de Verdière & Saint-Raymond³ (2018) give—for the first time—a mathematical explanation of these phenomena.
- They analyze equations of the form

$$iu_t - Pu = f \quad \text{in } \mathbb{T}^2 \times (0, \infty),$$

where P is a zeroth-order pseudo-differential operator, e.g.,

$$P(x, D) = \langle D \rangle^{-1} D_{x_2} - \frac{1}{2} \cos(x_1).$$

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Main Questions

Let $D_{x_j} := -i\partial_{x_j}$ and $\langle \xi \rangle := (1 + |\xi|^2)^{1/2}$. For a particular class of operators P acting on elements of $L^2(\mathbb{T}^2)$:

$$P(x, D) = \langle D \rangle^{-1} D_{x_2} - r\beta(x), \quad r > 0, \quad \beta \in C^\infty(\mathbb{T}^2),$$

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We will answer these questions using **numerical techniques**.

Up Next | **The Evolution Problem**

The Evolution Problem

Problem 1

Find a complex function $u = u(x, t)$, $x = (x_1, x_2) \in \mathbb{T}^2$, $t \geq 0$ such that

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$$P(x, D)v(x) = \langle D \rangle^{-1} D_{x_2} v(x) - r\beta(x)v(x) = \mathcal{F}^{-1} \left\{ \langle \xi \rangle^{-1} \xi_2 \widehat{v}(\xi) \right\} - r\beta(x)v(x),$$

where $\mathcal{F}\{v\} \equiv \widehat{v}$ is the Fourier transform.

What to expect?

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Theorem (Colin de Verdière & Saint-Raymond (2018), Dyatlov & Zworski (2019))

Let $f \in C^\infty(\mathbb{T}^2)$, 0 not an eigenvalue of P . Then, the solution to the evolution problem can be uniquely decomposed as

$$u(t) = u_\infty + b(t) + \epsilon(t),$$

where

- 1 $\lim_{\epsilon \rightarrow 0} (P - i\epsilon)^{-1} f =: u_\infty \in H^s(\mathbb{T}^2)$ for any $s < -1/2$ and is not in $L^2(\mathbb{T}^2)$ unless it vanishes,
- 2 $b \in L^2(\mathbb{T}^2)$ and is bounded,
- 3 ϵ vanishes as $t \rightarrow \infty$ in the $H^s(\mathbb{T}^2)$ -norm, for any $s < -1/2$.

Moreover, the energy $\|u(t)\|_0^2$ grows linearly except if u_∞ vanishes.

Discretization

- Pseudo-spectral method in space: (F = discrete Fourier transform)

$$i\hat{u}_t - \langle \xi \rangle^{-1} \xi_2 \hat{u} + rF\{\beta F^{-1}\hat{u}\} = \hat{f}, \quad \xi_j = -\frac{N}{2}, \dots, \frac{N}{2} - 1, \quad t > 0.$$

- Runge-Kutta-type schemes in time:

- 1 Classical RK4: yields a time-step restriction $\Delta t \leq 2.8$,
- 2 ETDRK4: no time-step restriction, but a large Δt will make aliasing errors are noticeable.

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- The presence of attractors makes a study of convergence challenging.

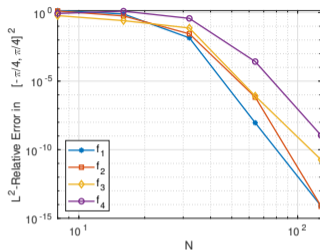
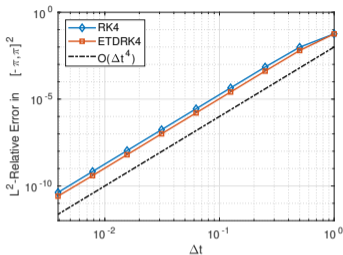
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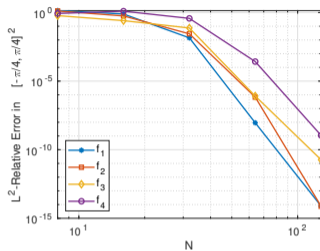
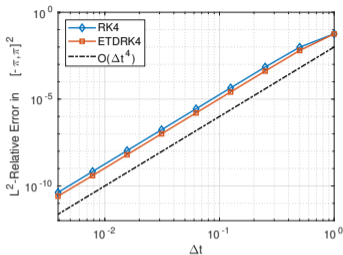
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 - 2 ETDRK4: no time-step restriction, but a large Δt will make aliasing errors are noticeable.
- The presence of attractors makes a study of convergence challenging.
- No numerical methods have been previously constructed for this equation.

Convergence

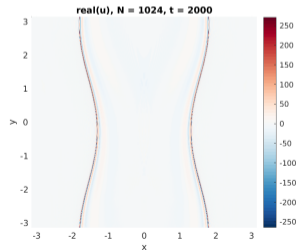


- Numerical methods are fourth-order accurate in time and **locally** spectrally accurate in space.

Convergence



- Numerical methods are fourth-order accurate in time and **locally** spectrally accurate in space.
- Global spectral accuracy cannot be expected, since there is no guarantee that u is smoother than $L^2(\mathbb{T}^2)$.



Solution to the Evolution Problem

$$P(x, D) = \langle D \rangle^{-1} D_{x_2} - 0.25 (\cos(x_1) + \sin(x_2))$$

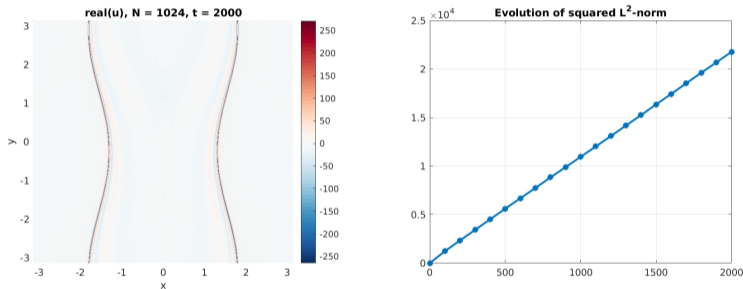


Figure: Development of attractors and linear evolution of the squared L^2 -norm. The forcing is a centered Gaussian. Video: [Local](#) | [YouTube](#)

Regularity of the solution

Definition

For a grid-function w , define the **radial energy density** (RED) E_s as

$$E_s[w](R) := \frac{1}{N^2} \sum_{k \in A_R \cap \mathbb{Z}^2} \langle k \rangle^{2s} |\widehat{w}(k)|^2,$$

where $A_R := \left\{ x \in \mathbb{R}^2 : R - 2 \leq |x| < R \right\}$.

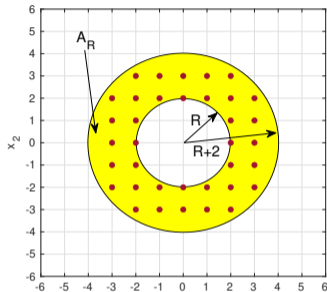


Figure: Annulus A_R

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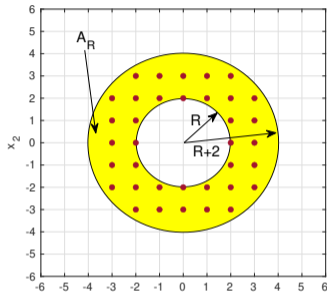


Figure: Annulus A_R

$$w \in H^s(\mathbb{T}^2) \implies \sum_{n=1}^{\infty} E_s[w](2n) < \infty.$$

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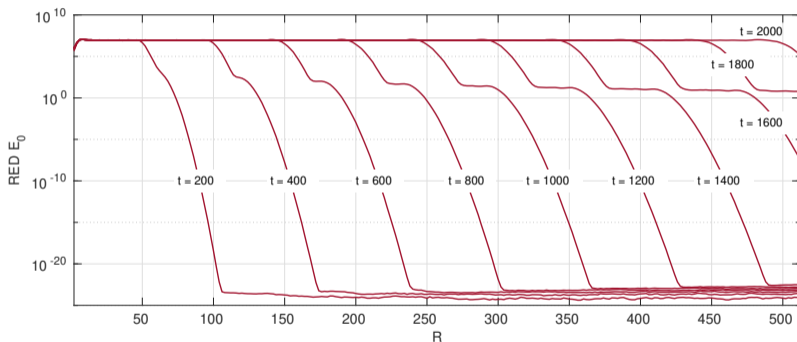


Figure: Radial energy density E_0 at different times. This shows that $u_\infty \notin L^2(\mathbb{T}^2)$.

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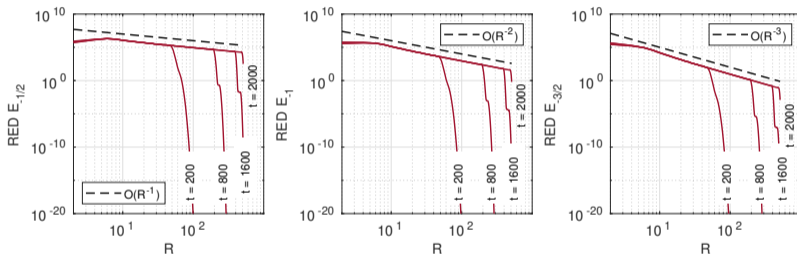


Figure: Radial energy density E_s at different times. If a distribution $v \in H^s(\mathbb{T}^2)$, then $E_s[v]$ should decay faster than $O(R^{-1})$.

In this section, we have:

- Constructed pseudo-spectral methods for the evolution problem,
- Developed a criterion to determine their convergence in the presence of non-smooth solutions,
- Determined a method to inspect the regularity of a computed approximation.

Up Next | **The Eigenvalue Problem**

The Eigenvalue Problem

Problem 2

Find pairs (u, λ) such that

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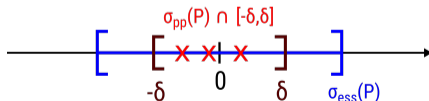
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- Eigenvalues can then be **embedded** in the essential spectrum.



Viscous Approximation

- Can the eigenvalues of $P + i\nu\Delta$ approximate those of P as $\nu \rightarrow 0^+$?

Viscous Approximation

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Theorem (Galkowski & Zworski (2019))

There exists an open neighbourhood U of 0 in \mathbb{C} , and a set $\mathcal{R}(P) \subset \{z \in \mathbb{C} : \operatorname{Im} z \leq 0\} \cap U$ such that for every $K \Subset U$, $\mathcal{R}(P) \cap K$ is discrete and

$$\sigma_{\text{pp}}(P + i\nu\Delta) \rightarrow \mathcal{R}(P) \quad \text{as } \nu \rightarrow 0^+,$$

uniformly on K . Furthermore,

$$\mathcal{R}(P) \cap \mathbb{R} = \sigma_{\text{pp}}(P) \cap U.$$

Discretization

Problem 3

Find pairs $(\lambda^{(\nu)}, u^{(\nu)})$ such that

$$(P + i\nu\Delta)u^{(\nu)} = \lambda^{(\nu)}u^{(\nu)} \quad \text{in } \mathbb{T}^2.$$

- Pseudo-spectral discretization (2D DFT) computes eigenvalues with spectral accuracy.

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- Computation is expensive: taking N grid-points per direction yields a **full** mass matrix of size $N^2 \times N^2$.
- Tracking trajectories $\nu \mapsto \lambda_j^{(\nu)}$ requires “tweaks” to the default “magnitude-then-phase” sorting of eigenvalues.

Viscous Eigenvalues

$$P = \langle D \rangle^{-1} D_{x_2} - 0.55 (\cos(x_1 - 2x_2) + \sin(x_2))$$

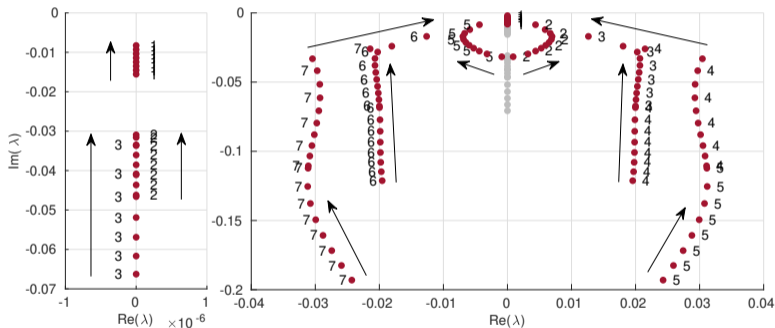


Figure: Eigenvalues of $P + i\nu\Delta$ as $\nu \rightarrow 0^+$. **L:** First three eigenvalues. **R:** All the eigenvalues.

In this section, we have:

- Described the spectrum P ,
- Determined a numerical strategy to approximate the embedded eigenvalues.
- Found proper ways to track the trajectories drawn by the viscous eigenvalues.

Up Next | **Eigenmodes, Long-term Evolution and Attractors**

Influence of Eigenmodes in the Long-term Evolution

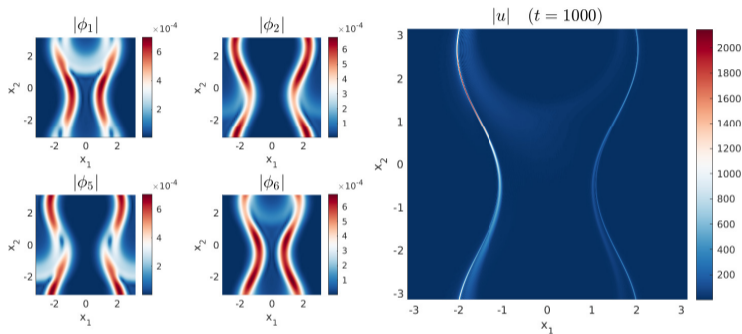


Figure: $P(x, D) = \langle D \rangle^{-1} D_{x_2} - 0.5 (\cos(x_1) + \sin(x_2))$. **L:** Low-viscosity approximation of some of the embedded eigenmodes of P . **R:** Long-term evolution.

The Picture in Fourier Space

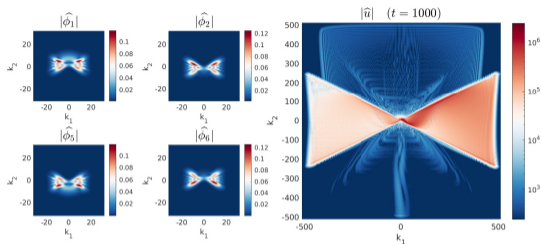


Figure: Magnitude of Fourier coefficients. **L**: Approximated embedded eigenmodes. **R**: Long-term evolution.

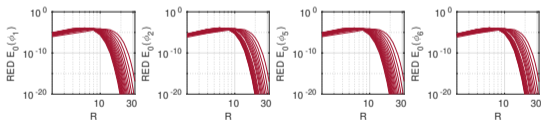


Figure: Radial energy density E_0 of the viscous eigenmodes. As $\nu \rightarrow 0^+$, the curves move to the right.

$$P(x,D) = \langle D \rangle^{-1} D_{x_2} - 0.5(\cos(x_1) + \sin(x_2))$$

Dynamical Aspects

- For $P(x, D) = \langle D \rangle^{-1} D_{x_2} - r\beta(x)$, its principal symbol is given by

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- The dynamics of the problem are dictated by the flow of

$$X := \kappa_*(|\xi|H_p) \quad \text{on} \quad \Sigma_0 := \kappa(p^{-1}(\{0\})) \subset \mathbb{T}^3,$$

where H_p is the Hamiltonian vector field, and κ is the quotient map of the \mathbb{R}^+ action

$$\kappa : \bar{T}^* \mathbb{T}^2 \setminus \{0\} \rightarrow \partial \bar{T}^* \mathbb{T}^2 \simeq \mathbb{T}^3, \quad (x, \xi) \mapsto (x, s\xi), \quad s > 0.$$

Dynamical Aspects

- For $P(x, D) = \langle D \rangle^{-1} D_{x_2} - r\beta(x)$, its principal symbol is given by

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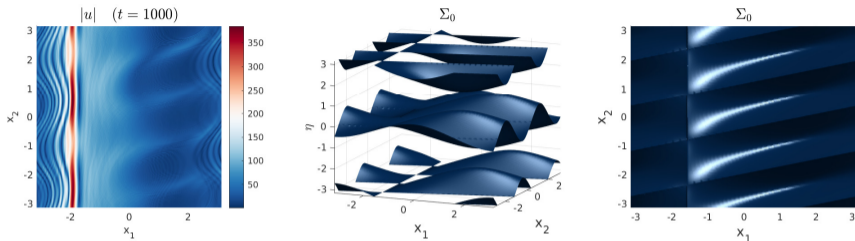
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- It is assumed that the flow is Morse-Smale with no fixed points (CdV-SR 18', D-Z 19'), and that Σ covers \mathbb{T}^2 (CdV-SR 18').

Energy surfaces and development of attractors



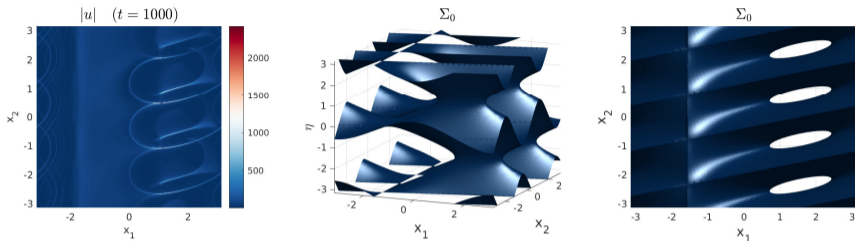
$$P(x, D) = \langle D \rangle^{-1} D_{x_2} - 0.45 (\cos(x_1 - 2x_2) + \sin(x_2)),$$

$$p(x, \xi) = |\xi|^{-1} \xi_2 - 0.45 (\cos(x_1 - 2x_2) + \sin(x_2)),$$

$$(x_1, x_2, \xi_1, \xi_2) \xrightarrow{K} (x_1, x_2, \eta),$$

$$\Sigma_0 = \left\{ (x_1, x_2, \eta) \in \mathbb{T}^3 : 0.45 (\cos(x_1 - 2x_2) + \sin(x_2)) = \sin(\eta) \right\}$$

Energy surfaces and development of attractors



$$P(x, D) = \langle D \rangle^{-1} D_{x_2} - 0.55 (\cos(x_1 - 2x_2) + \sin(x_2)),$$

$$p(x, \xi) = |\xi|^{-1} \xi_2 - 0.55 (\cos(x_1 - 2x_2) + \sin(x_2)),$$

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In this section, we have:

- Applied the developed numerical methods to help shed insight into this phenomenon. This gives tools to analysts to study this problem in depth.

Up Next | **Conclusions and Future Work**

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Conclusion

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- We developed convergent, high-order numerical methods for the evolution and eigenvalue problems,
- We showed how the methods reflect the expected analytical behaviour of the solution,
- We provided numerical evidence of the influence of the embedded eigenmodes in the evolution at long times.

Future Work

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- Work with more involved versions of the operator P ,
- Construct the mass matrix of the eigenvalue problem using a more efficient implementation of the FFT,
- Develop de-aliasing techniques.

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Thank you!

Addendum

- 28 Discretization of the Eigenvalue Problem
- 29 Propagation of Round-off Errors: Example
- 31 Propagation of Round-off Errors: Lost Sparsity
- 32 Default Sorting Strategy of Eigenvalues
- 34 Second Step in the Sorting Process: Example
- 35 Fibre-radial Compactification
- 36 Description of the Energy Surface
- 37 Morse-Smale Flow

Discretization of the Eigenvalue Problem

- Let \mathbf{F}_1 denote the 1-dimensional DFT Matrix. Then, the 2-dimensional DFT matrix is given by $\mathbf{F}_2 = \mathbf{F}_1 \otimes \mathbf{F}_1$.
- Denote by \mathbf{D}_ν the diagonal matrix of evaluations of the modified symbol

$$\tilde{p}(k; \nu) := \langle \xi \rangle^{-1} \xi_2 - i\nu |\xi|^2,$$

at wave numbers $k_j = -\frac{N}{2}, \dots, \frac{N}{2} - 1$. Similarly, denote by \mathbf{B} the diagonal matrix of evaluations of $\beta(x)$ at the grid points.

Discrete Eigenvalue Problem

$$\left(\mathbf{D}_\nu - \frac{r}{N^2} \mathbf{F}_2 \mathbf{B} \mathbf{F}_2^* \right) \hat{\mathbf{u}}_N^{(\nu)} = \lambda^{(\nu)} \hat{\mathbf{u}}_N^{(\nu)}.$$

Propagation of Round-off Errors: Example

- The function $\beta(x) = \cos(x_1) + \sin(x_2)$ sampled at $x_1, x_2 = -\pi, -\frac{\pi}{2}, 0, \frac{\pi}{2}$ can be written as:

$$B_n = \begin{bmatrix} -1 & -6.12 \cdot 10^{-17} & 1 & -6.12 \cdot 10^{-17} \\ -2 & -1 & 0 & -1 \\ -1 & 6.12 \cdot 10^{-17} & 1 & 6.12 \cdot 10^{-17} \\ 0 & 1 & 2 & 1 \end{bmatrix}, \quad B_e = \begin{bmatrix} -1 & 0 & 1 & 0 \\ -2 & -1 & 0 & -1 \\ -1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 1 \end{bmatrix},$$

where the computations in B_n have been done **numerically**, and in **exact** arithmetic for B_e .

Propagation of Round-off Errors: Example

- The construction of \mathbf{B} in the eigenvalue problem requires the computation of the 1D DFT of the columns of B_n (or B_e).
- Using the 1D FFT for B_n and 1D DFT (exactly) for B_e , yields

$$\widehat{B}_n = \begin{bmatrix} -4 & 1.11 \cdot 10^{-16} & 4 & 1.11 \cdot 10^{-16} \\ -2.22 \cdot 10^{-16} + 2i & -1.22 \cdot 10^{-16} + 2i & -1.11 \cdot 10^{-16} + 2i & -1.22 \cdot 10^{-16} + 2i \\ 0 & -1.11 \cdot 10^{-16} & 0 & -1.11 \cdot 10^{-16} \\ -2.22 \cdot 10^{-16} - 2i & -1.22 \cdot 10^{-16} - 2i & -1.11 \cdot 10^{-16} - 2i & -1.22 \cdot 10^{-16} - 2i \end{bmatrix},$$

$$\widehat{B}_e = \begin{bmatrix} -4 & 0 & -4 & 0 \\ 2i & 2i & 2i & 2i \\ 0 & 0 & 0 & 0 \\ -2i & -2i & -2i & -2i \end{bmatrix}.$$

Propagation of Round-off Errors: Lost Sparsity

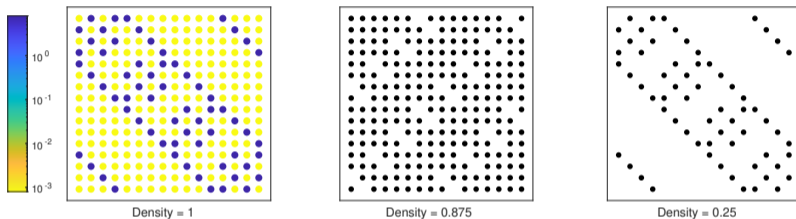


Figure: Visualization of the density of $\mathbf{F}_2\mathbf{B}\mathbf{F}_2^* \in \mathbb{C}^{16 \times 16}$ when computed using the two-dimensional DFT (left), one-dimensional FFTs (center) and one-dimensional DFTs but computed in exact arithmetic (right).

Default Sorting Strategy of Eigenvalues

- 1 Magnitude-then-phase: eigenvalues are ordered in increasing magnitude. If two eigenvalues have the same magnitude, the one with smallest phase (in $[-\pi, \pi)$) appears first.
- 2 Reorder so that eigenvalues with non-negative real part appear first.

Default Sorting Strategy of Eigenvalues

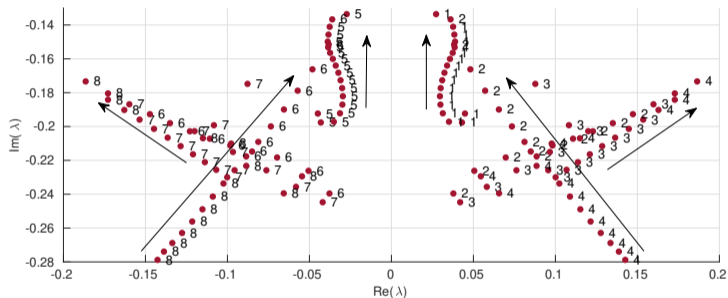


Figure: Evolution of the first 8 eigenvalues for $r = 0.5$, $\beta(x) = \cos(x_1) + \sin(x_2)$ as ν decreases.

Second Step in the Sorting Process: Example

- Consider $N = 40, \nu = 0.015, r = 0.5, \beta(x) = \cos(x_1) + \sin(x_2)$.
- The first 8 eigenvalues (ordered using Step 1 only) and their magnitudes are:

$$(\lambda_j)_{j=1}^8 = \begin{pmatrix} 0.0166 - 0.1905i \\ -0.0166 - 0.1905i \\ -0.0369 - 0.2734i \\ 0.0369 - 0.2734i \\ -0.0401 - 0.3252i \\ 0.0401 - 0.3252i \\ 0.2518 - 0.2424i \\ -0.2518 - 0.2424i \end{pmatrix}, \quad (|\lambda_j|)_{j=1}^8 = \begin{pmatrix} 0.191246980677908 \\ 0.191246980677910 \\ 0.275887857562819 \\ 0.275887857562819 \\ 0.327685703948980 \\ 0.327685703948985 \\ 0.349551258136058 \\ 0.349551258136059 \end{pmatrix}.$$

- It appears that both λ and $-\bar{\lambda}$ are eigenvalues. The second step in the sorting process fixes the order in which they appear.

Fibre-radial Compactification

- The bundle $\bar{T}^*\mathbb{T}^2$ is a manifold with interior $T^*\mathbb{T}^2$ and a boundary $\partial\bar{T}^*\mathbb{T}^2$.
- What is $\partial\bar{T}^*\mathbb{T}^2$? Consider an equivalence relation on $T^*\mathbb{T}^2 \setminus \{0\}$:

$$(x, \xi) \sim (y, \varphi) \iff x = y \quad \text{and} \quad \xi = s\varphi, \text{ for some } s > 0.$$

Then, $\partial\bar{T}^*\mathbb{T}^2$ is the set of equivalence classes arising from this relation.

- The natural quotient map is

$$\kappa : T^*\mathbb{T}^2 \setminus \{0\} \rightarrow \partial\bar{T}^*\mathbb{T}^2,$$

defined as follows: for each $(x, \xi) \in T^*\mathbb{T}^2 \setminus \{0\}$, the ray $\{(x, s\xi) : s > 0\}$ intersects $\partial\bar{T}^*\mathbb{T}^2$ at $\kappa(x, \xi)$, i.e.,

$$\lim_{s \rightarrow \infty} (x, s\xi) = \kappa(x, \xi) \in \partial\bar{T}^*\mathbb{T}^2.$$

Description of the Energy Surface

- $\Sigma_0 = \kappa(p^{-1}(\{0\}))$.
- $p(x, \xi) = 0 \iff r\beta(x) = |\xi|^{-1}\xi_2$.
- Since $(x, \xi) \in \bar{T}^*\mathbb{T}^2$, we may parametrize ξ as $(s \cos \eta, s \sin \eta)$ for $\eta \in [-\pi, \pi)$ and some $s > 0$.
- Replacing this into the previous equation, we have

$$\Sigma_0 = \{ (x, \eta) \in \mathbb{T}^3 : r\beta(x) = \sin(\eta) \}.$$

Morse-Smale Flow

A flow f^t is called “Morse-Smale” if the following properties hold:

- 1 There are only a finite number of equilibria, each one of them hyperbolic with smooth stable and unstable manifolds.
- 2 There are only a finite number of periodic orbits, each of them hyperbolic with smooth stable and unstable manifolds.
- 3 Stable and unstable manifolds of equilibria and periodic orbits intersect transversally, that is, for any $x \in W^u(\Lambda_1) \cap W^s(\Lambda_2)$ (with Λ_1, Λ_2 being either an equilibrium point or a periodic orbit), there holds

$$T_x M = T_x W^u(\Lambda_1) + T_x W^s(\Lambda_2),$$

where $T_x M$ denotes the tangent space of M at x .

- 4 The union of equilibria and periodic orbits coincides with the non-wandering set $\Omega(f)$, defined as

$$\Omega(f) := \left\{ x \in M : \forall \text{ neighbourhood } V \text{ of } x, \forall t_0 \in \mathbb{R}^+, \right. \\ \left. \exists t \in \mathbb{R}^+ \cap (t_0, +\infty) \text{ with } f^t(V) \cap V \neq \emptyset \right\}.$$