

High-order Discretizations of a Linear Forced Wave Equation

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1. Background

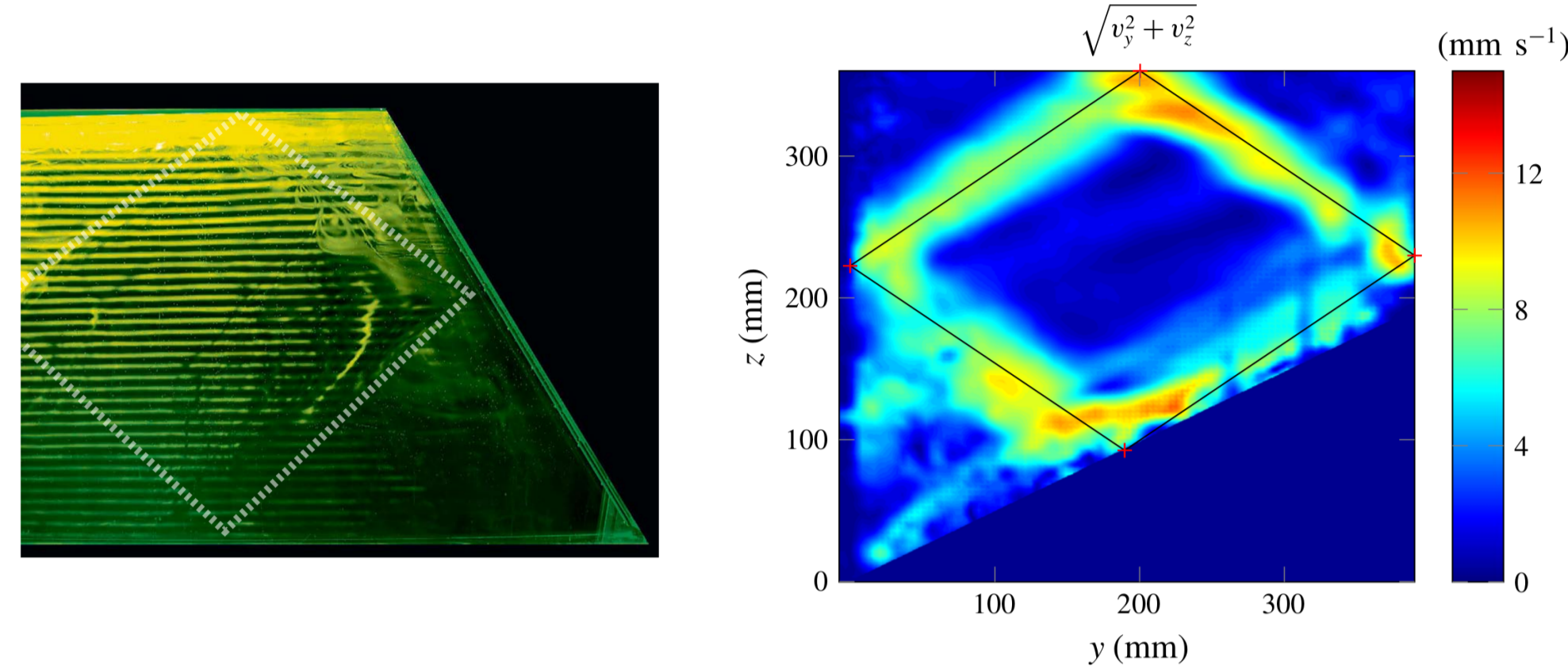


Figure 1: It has been observed that, in the presence of topography, forcing internal waves lead to the development of singular geometric patterns (called “attractors”). Source: [1, 2].

A simple model for the propagation of internal waves is to consider a non-rotating, stably stratified fluid with density ρ_0 , whose variation can be modeled using the Boussinesq approximation:

$$\frac{\partial \eta}{\partial t} + \mathbf{u} \cdot \nabla \rho_0 = 0, \quad \nabla \cdot \mathbf{u} = 0, \quad \rho_0 \frac{\partial \mathbf{u}}{\partial t} + \nabla p = -\eta g \mathbf{e}_3 + \mathbf{F} e^{-i\omega_0 t}, \quad \mathbf{u} \cdot \mathbf{n} = 0, \quad (1)$$

where η are fluctuations to the density $\rho = \rho_0 + \eta$, \mathbf{u} and p are velocity and pressure fields, g is the gravitational force, \mathbf{F} is a spatial source term and ω_0 is a forcing frequency.

2. Goals

- To numerically approximate solutions to a linear wave equation arising from (1),
- To verify predicted convergence rates,
- To portray the intrinsic characteristics of these solutions.

3. Simplified Mathematical Model

Recent work [3] shows that these attractors can be captured by solving a diagonalized version of (1). In particular, this process involves solving:

$$i\partial_t u - P(x, D)u = f e^{-i\omega_0 t} \quad \text{in } \mathbb{T}^2 \times (0, T], \quad u|_{t=0} = u_0 \quad \text{in } \mathbb{T}^2, \quad (2)$$

where $f \in C^\infty(\mathbb{T}^2)$ and P is the nonlocal, self-adjoint, zero-th order pseudo-differential operator

$$P(x, D) = (1 + D_{x_1}^2 + D_{x_2}^2)^{-1/2} D_{x_2} - r\beta(x), \quad (3)$$

where $D = -i\partial$, $\beta \in C^\infty(\mathbb{T}^2)$ and $r \geq 0$.

Some examples of more recognizable pseudo-differential operators (Ψ DO) include

- Ψ DO of order 0: $P(x, D) := -3x_2 \implies P(x, D)u = -3x_2 u$,
- Ψ DO of order 1: $P(x, D) := iD_{x_1} \implies P(x, D)u = \partial_{x_1} u$,
- Ψ DO of order $2s$, $0 < s < 1$: $P(x, D) := (D_{x_1}^2 + D_{x_2}^2)^s \implies P(x, D)u = (-\Delta)^s u$.

4. What to expect

- Attractors are related to singularities in the solution. Indeed, for $r \neq 0$ and $\beta(x) = \cos(x_1)$, we expect the appearance of blow-up singularities along the lines $x_1 = -\pi/2$ and $x_1 = \pi/2$.
- Numerical experiments have been performed in [4] showing these singularities by taking, in particular, $\omega_0 = 0$, $u_0 \equiv 0$ and

$$f(x) = -5 \exp \left(-3[(x_1 + 0.9)^2 + (x_2 + 0.8)^2] + i(2x_1 + x_2) \right).$$

5. Numerical methods

- Spatial discretization: Fourier collocation method. Equation (2) can be written in Fourier space as

$$\partial_t \hat{u} = \mathbf{L}(\hat{u}) + \mathbf{N}(\hat{u}, t), \quad \hat{u}|_{t=0} = \hat{u}_0,$$

where

$$\mathbf{L}(\hat{u})(k_1, k_2) := -\frac{ik_2}{\sqrt{1 + k_1^2 + k_2^2}} \hat{u}, \quad \mathbf{N}(\hat{u}, t) = ir \mathcal{F} \left(\beta(x) \mathcal{F}^{-1}(\hat{u}) \right) - i \hat{f} e^{-i\omega_0 t},$$

with \mathcal{F} being the discrete Fourier transform. Notice that now our problem is local and nonlinear (for $r \neq 0$).

- Temporal discretization:
 - Classical fourth-order Runge-Kutta (RK4),
 - RK4-based exponential time-differencing method (ETDRK4) from [5].

6. Convergence studies

First, we perform a spatial convergence study using the ETDRK4 method and several source terms:

$$f_1(x) = \sin(x_1) \cos(2x_2), \quad f_2(x) = f_1(x) + \sin(5x_1) \cos(2x_2) + i \sin(5x_1) \cos(4x_2),$$

$$f_3(x) = 0.5 \exp \left(-2x_1^2 - 2x_2^2 \right),$$

and f_4 as in Section 4. In addition, we consider $\omega_0 = 0.5$, $T = 2$, $u_0 \equiv 0$ and $\beta(x) = \cos(x_1)$. We see in Figure that spectral accuracy is achieved in all scenarios.

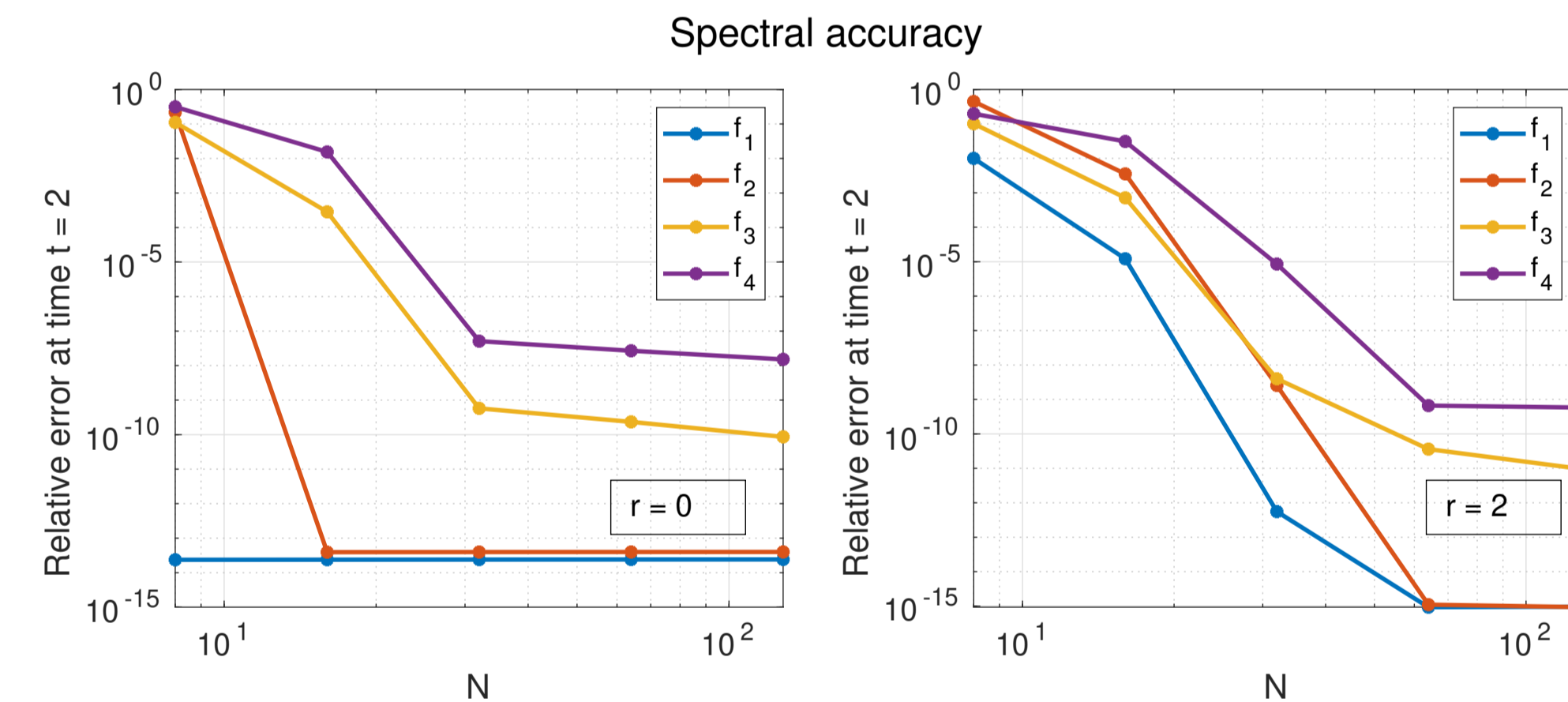


Figure 2: Relative error v/s number of nodes for the spectral discretization using a time step $\Delta t = 10^{-3}$ and the ETDRK4 method.

Next, we perform a temporal convergence study using the same parameters as before and source term taken as f_4 . We see in Figure 3 that both RK4 and ETDRK4 methods are fourth-order accurate, as expected.

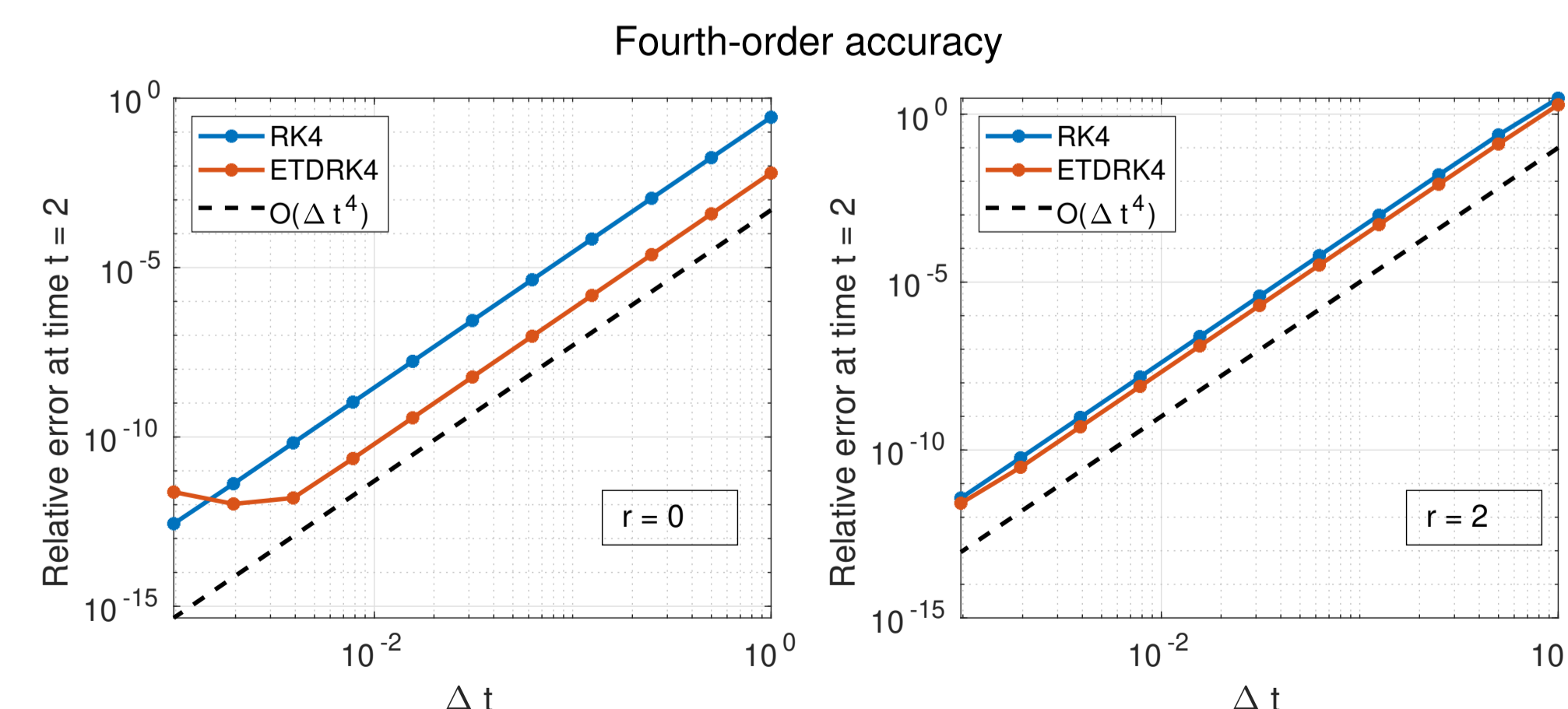


Figure 3: Relative error v/s time step for the two implemented time discretizations using a spatial discretization of 64×64 nodes.

In both cases, the relative error is computed on $[-\pi, \pi]^2$ with respect to an exact (analytical) solution when $r = 0$, and on $[-\pi/4, -\pi/4]^2$ with respect to a very refined solution when $r \neq 0$.

7. Capturing blow-up singularities

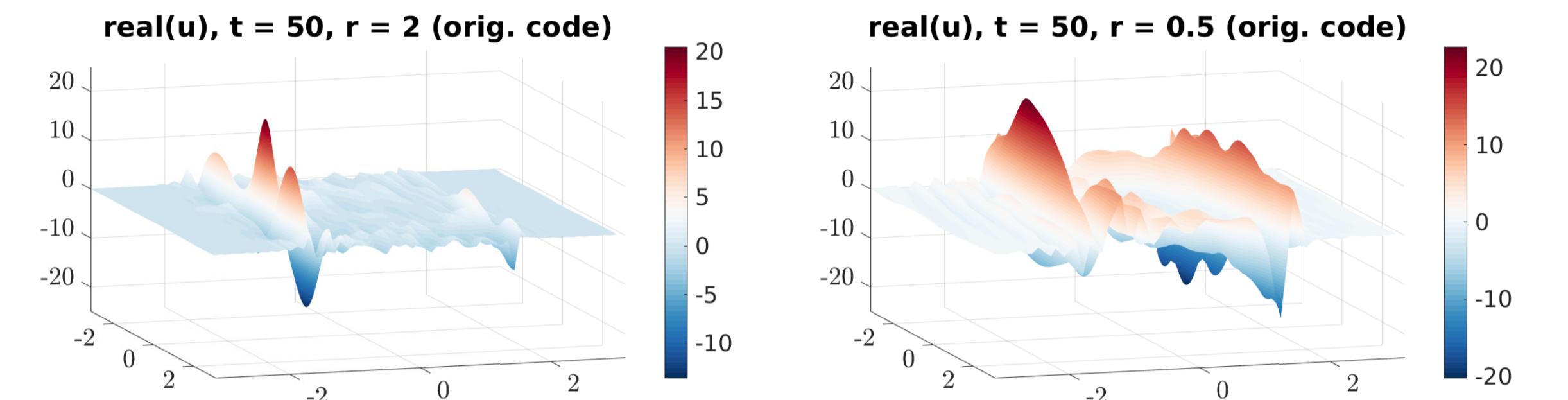


Figure 4: Figures from [4] depicting the inherent singularities in this problem. Their computation includes the use of matrix exponentials and an Euler time-stepping scheme.

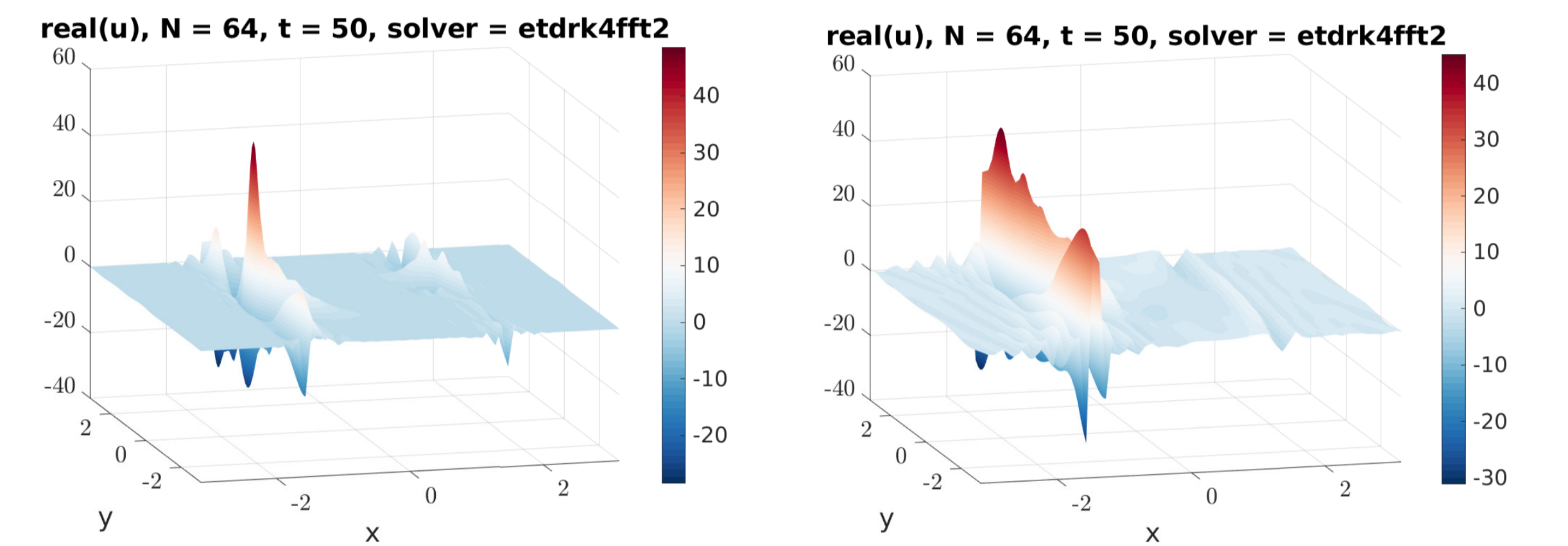


Figure 5: Solutions to (2) with $r = 2$ (to the left) and $r = 0.5$ (to the right). Here, parameters are taken as in Section 4.

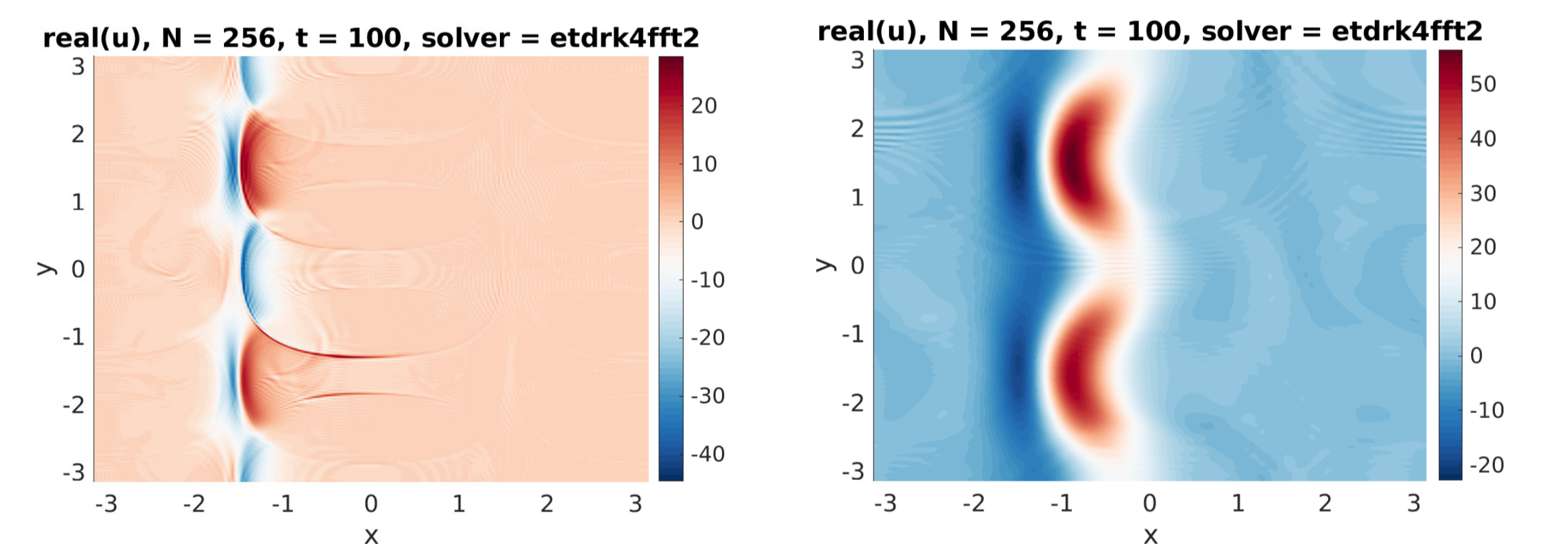


Figure 6: Solutions to (2) with $r = 2$ (to the left) and $r = 0.5$ (to the right) using the same parameters as in Section 4, but this time with $\beta(x) = \cos(x_1) \sin(2x_2)$.

8. Concluding Remarks

- The numerical methods are shown to be fourth-order accurate in time and spectrally accurate in space, both in the linear and nonlinear cases,
- Blow-up singularities are captured accordingly.

References

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