

What to do today (Oct 19, 2020)?

1. *Introduction*

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3. Essential Topics in Mathematical Statistics

3.1 Elementary Statistical Inferences (Chp 4)

▶ **3.1.1 Sampling and Statistics**

▶ **3.1.2 Confidence Interval**

▶ *3.1.3 Order Statistics*

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3.2 Consistency and Limiting Distributions (Chp 5)

3.3 Maximum Likelihood Methods (Chp 6)

3.1 Elementary Statistical Inferences

3.1.1 Sampling and Statistics

In the information age, statistics are everywhere, since

- ▶ data are everywhere, and
- ▶ always resources are limited and our observation abilities are limited.

Various statistical methods.

- ▶ *to efficiently collect meaningful and sufficient information:*
Survey Sampling and Experimental Design
- ▶ *to process the available information by tabulating/plotting the data:* **Descriptive Analysis**
- ▶ *to make inference about the target population, beyond what the information is directly on:* **Inferential Analysis**

Plus **Probability and Distribution:** *inferential reasoning with probability theory*

3.1.1 Sampling and Statistics

Consider rv $X \sim F(\cdot)$, the population distn:

- ▶ A sample on X with size n : rvs X_1, \dots, X_n
its observations x_1, \dots, x_n from a study are **realizations** of the sample.
- ▶ If X_1, \dots, X_n are *independent and identically distributed (iid)* with the same distn $F(\cdot)$, the sample $\{X_1, \dots, X_n\}$ is a **random sample** on X with size n .
- ▶ A function of X_1, \dots, X_n , say, $T = T(X_1, \dots, X_n)$, is called a **statistic**.
- ▶ A statistic that is used to estimate a population parameter θ is called a **point estimator** of θ .

Definition. Let X_1, \dots, X_n be a sample on rv $X \sim F(x; \theta)$. A statistic $T = T(X_1, \dots, X_n)$ is an **unbiased** estimator of θ if $E(T) = \theta$.

Is \bar{X} a “good” (point) estimator of μ ? How to obtain a “good” estimator for θ in general?

3.1.1 Sampling and Statistics: Two Commonly Used Point Estimation Procedures

A. Method of Moments Estimation (MME)

Thinking ... Recall sample mean \bar{X} to estimate population mean μ .

Extend the idea to estimating k th population moment, with $k = 1, 2, \dots$?

Point estimation of population moments:

Suppose $X \sim F(\cdot; \theta_1, \dots, \theta_m)$ and iid observations X_1, \dots, X_n .

- ▶ k th population moment of X : $\mu_k = E(X^k)$
- ▶ k th sample moment with X_1, \dots, X_n :

$$\hat{\mu}_k = \frac{1}{n}(X_1^k + \dots + X_n^k)$$

- ▶ **Use $\hat{\mu}_k$ to estimate μ_k !** (*unbiased estimator*)

eg, $\mu_2 = E(X^2)$ is estimated by

$$\hat{\mu}_2 = \frac{1}{n}(X_1^2 + \dots + X_n^2).$$

Further, what if $X \sim F(\cdot; \theta_1, \dots, \theta_m)$ with $\theta_1, \dots, \theta_m$ not all population moments? For example, $X \sim N(\mu, \sigma^2)$: $\theta_1 = \mu; \theta_2 = \sigma^2$. *How to estimate μ and σ^2 ?*

Recall that

$$\mu_2 = E(X^2) = \sigma^2 + \mu^2 = \theta_2 + \theta_1^2$$

How about use the following?

$$\begin{cases} \hat{\mu}_1 = \bar{X} \text{ to estimate } \mu_1 = \mu; \\ \hat{\mu}_2 \text{ to estimate } \sigma^2 + \mu^2 \end{cases}$$

If so, then

$$\begin{cases} \hat{\mu}_1 = \bar{X} \text{ as } \hat{\mu}, \\ \hat{\sigma}^2 = \hat{\mu}_2 - \bar{X}^2 \text{ to estimate } \sigma^2 \end{cases}$$

3.1.1 Sampling and Statistics: Method of Moments Estimation (MME)

MM Estimation Procedure:

- ▶ X_1, \dots, X_n are iid observations from the population $X \sim F(\cdot; \theta_1, \dots, \theta_m)$.
- ▶ Denote the k th population mean μ_k by $\mu_k = \mu_k(\theta_1, \dots, \theta_m)$ with $k = 1, 2, \dots$
- ▶ The **MM estimators** $\hat{\theta}_1, \dots, \hat{\theta}_m$ are the solution to the equations jointly:

$$\hat{\mu}_1 = \mu_1(\theta_1, \dots, \theta_m); \dots; \hat{\mu}_m = \mu_m(\theta_1, \dots, \theta_m)$$

Revisit to the example of estimating μ and σ^2 with $X \sim N(\mu, \sigma^2)$:

$$\text{Solve } \begin{cases} \bar{X} = \mu, \\ \hat{\mu}_2 = \sigma^2 + \mu^2 \end{cases}, \text{ and obtain } \hat{\mu} = \bar{X}, \quad \hat{\sigma}^2 = \hat{\mu}_2 - \bar{X}^2.$$

Are all MM estimators good? Is there any alternative estimation procedure?

3.1.1 Sampling and Statistics: B. Maximum Likelihood Estimation (MLE)

by R.A. Fisher (geneticist and statistician), 1920

Likelihood Function:

- ▶ Let the joint distribution (pmf, or pdf) of rvs X_1, \dots, X_n be $f(x_1, \dots, x_n; \theta_1, \dots, \theta_m)$.

When x_1, \dots, x_n are the observed values (realizations) of the rvs, the **likelihood function** of $\theta_1, \dots, \theta_m$ given the data is

$$L(\theta_1, \dots, \theta_m \mid \text{data}) = f(x_1, \dots, x_n; \theta_1, \dots, \theta_m)$$

- ▶ **interpretation:** a measure on how likely the observed sample is overall with the values of $\theta_1, \dots, \theta_m$.
- ▶ Often X_1, \dots, X_n are iid observations (a random sample) from the population with distribution $f(x; \theta)$. If the observed values are x_1, \dots, x_n , then the likelihood function is

$$L(\theta \mid \text{data}) = \prod_{i=1}^n f(x_i; \theta) = f(x_1; \theta) \dots f(x_n; \theta).$$

Maximum Likelihood Estimator (MLE):

- ▶ The **MLE** $\hat{\theta}_1, \dots, \hat{\theta}_m$ are the values of $\theta_1, \dots, \theta_m$ that maximize the likelihood function:

$$L(\hat{\theta}_1, \dots, \hat{\theta}_m \mid \text{data}) = \max L(\theta_1, \dots, \theta_m \mid \text{data}).$$

- ▶ **interpretation:** The MLE $\hat{\theta}_1, \dots, \hat{\theta}_m$ give the parameter values that agree most closely with the observed sample (the data).
- ▶ Often used **procedures:** (*Why?*)

(1) to maximize $\log L(\theta_1, \dots, \theta_m)$

(2) to obtain the solution to

$$\left\{ \begin{array}{l} \frac{\partial \ln L(\theta_1, \dots, \theta_m)}{\partial \theta_1} = 0, \\ \dots\dots \\ \frac{\partial \ln L(\theta_1, \dots, \theta_m)}{\partial \theta_m} = 0 \end{array} \right.$$

For example, iid $X_1, \dots, X_{100} \sim N(\mu, \sigma^2)$ with observed values x_1, \dots, x_{100} . The likelihood function of μ, σ^2 is

$$L(\mu, \sigma^2 | \text{data}) = \prod_{i=1}^{100} \frac{1}{\sqrt{2\pi\sigma^2}} \exp \left\{ -\frac{1}{2\sigma^2} (x_i - \mu)^2 \right\}$$

$$\log L(\mu, \sigma^2 | \text{data}) = \sum_{i=1}^{100} \left\{ \log \left(\frac{1}{\sqrt{2\pi}} \right) - \frac{1}{2} \log(\sigma^2) - \frac{1}{2\sigma^2} (x_i - \mu)^2 \right\}$$

$$\begin{cases} \frac{\partial \log L(\mu, \sigma^2)}{\partial \mu} = \sum_{i=1}^{100} \left\{ \frac{2}{2\sigma^2} (x_i - \mu) \right\} = 0 \\ \frac{\partial \log L(\mu, \sigma^2)}{\partial \sigma^2} = \sum_{i=1}^{100} \left\{ -\frac{1}{2\sigma^2} + \frac{1}{2(\sigma^2)^2} (x_i - \mu)^2 \right\} = 0 \end{cases}$$

Thus the MLE of μ, σ^2 are $\hat{\mu} = \bar{X}, \hat{\sigma}^2 = \sum_{i=1}^n (X_i - \bar{X})^2 / n$.

Why MLE?

Large Sample Behavior of MLE $\hat{\theta}$:

With a random sample of size n , as $n \rightarrow \infty$

- ▶ $E(\hat{\theta}_n) \rightarrow \theta$: approximately unbiased
- ▶ $Var(\hat{\theta}_n) \rightarrow \sigma^{*2} = \min Var(\tilde{\theta})$ with unbiased $\tilde{\theta}$
- ▶ The distribution of $\hat{\theta}_n$ is approximately $N(\theta, \sigma^{*2})$

Remarks: MLE is widely used, because

- ▶ given the underlying population distribution, it is mechanically derived by calculus-based techniques
- ▶ is almost the best estimator that can be attained,
- ▶ is convenient to use to make statistical inferences.

3.1.2 Confidence Interval

Goal: Suppose $X \sim F(\cdot; \theta)$ and X_1, \dots, X_n iid observations from the population. To obtain a 'good' interval estimator of θ ?

Definition. $\hat{\theta}_L$ and $\hat{\theta}_U$ are two statistics. The random interval $(\hat{\theta}_L, \hat{\theta}_U)$ is a $100(1 - \alpha)\%$ **confidence interval (CI)** of θ is

$$P(\theta \in (\hat{\theta}_L, \hat{\theta}_U)) = 100(1 - \alpha)\%.$$

Here, $(1 - \alpha)$ is called the confidence level of the CI.

- ▶ eg, $\alpha = 0.05$, a $100(1 - \alpha)\%$ CI of θ is a CI with confidence level of 95%.

3.1.2 Confidence Interval

- ▶ **Interpretation.** (frequentist)

With 100 experiments' outcomes, there're at least $100(1 - \alpha)$ out of the 100 CI realizations containing the true value of θ .

Bayesian interpretation: different!

- ▶ **Confidence Level, Precision, and Sample Size:**

- ▶ $100(1 - \alpha)\%$ CI $(\hat{\theta}_L, \hat{\theta}_U)$: the confidence level is $1 - \alpha$.

$$P(\theta \in (\hat{\theta}_L, \hat{\theta}_U)) = 1 - \alpha$$

- ▶ Length (Width) of CI: $\hat{\theta}_U - \hat{\theta}_L$, about CI's **precision/accuracy**.
- ▶ Often to determine the sample size n such that a $1 - \alpha$ CI has a desired precision \Rightarrow **Study Design**

Example 3.1

- ▶ *Study:* To determine the true average response time of a new operating system. What sample size is necessary to ensure the resulting 95% CI has a width of (at most) 10? Assume $\sigma = 25$.
- ▶ *Stats formulation:* Assuming a response time $X \sim N(\mu, \sigma^2)$ with $\sigma = 25$. To obtain a 95% CI of μ with length ≤ 10
- ▶ *Interval estimator:* $(\bar{X} - 1.96 \frac{25}{\sqrt{n}}, \bar{X} + 1.96 \frac{25}{\sqrt{n}})$.
- ▶ *Sample size determination:* The length $2(1.96)(25/\sqrt{n})$ is to be at most 10:

$$2(1.96)(25/\sqrt{n}) \leq 10.$$

Thus $\sqrt{n} \geq 2(1.96)(25)/10 = 9.80$. So, n should be at least 97 ($9.80^2 = 96.04$).

Deriving a CI: a general procedure

to find $\hat{\theta}_L = l(X_1, \dots, X_n)$ and $\hat{\theta}_U = u(X_1, \dots, X_n)$ to satisfy

$$P(l(X_1, \dots, X_n) < \theta < u(X_1, \dots, X_n)) = 1 - \alpha$$

How? not easy! See a few examples. ...

3.1.2 Confidence Interval: to estimate μ

Consider rv X with $\mu = E(X)$, and a random sample $\{X_1, \dots, X_n\}$ from the population.

Setting 1. $X \sim N(\mu, \sigma^2)$ with σ^2 known.

- ▶ **Point Estimator.** $\hat{\theta} = \bar{X} = \frac{1}{n}(X_1 + \dots + X_n)$: with the following “good” properties
 - ▶ $E(\bar{X}) = \mu$, unbiased
 - ▶ $V(\bar{X}) = \frac{\sigma^2}{n}$, converging to zero as $n \rightarrow \infty$
 - ▶ $\bar{X} \sim N(\mu, \frac{\sigma^2}{n})$
- ▶ **Confidence Interval.** $(\hat{\theta}_L, \hat{\theta}_U)$ with

$$\hat{\theta}_L = \bar{X} - 1.96 \frac{\sigma}{\sqrt{n}}, \quad \hat{\theta}_U = \bar{X} + 1.96 \frac{\sigma}{\sqrt{n}}$$

- ▶ $P((\hat{\theta}_L, \hat{\theta}_U) \ni \mu) = 95\%$,
since $P(\hat{\theta}_L \geq \mu) = 2.5\%$ and $P(\hat{\theta}_U \geq \mu) = 97.5\%$.
- ▶ for a general α ?

3.1.2 Confidence Interval: to estimate μ

Consider rv X with $\mu = E(X)$, and a random sample $\{X_1, \dots, X_n\}$ from the population.

Setting 2. $X \sim N(\mu, \sigma^2)$ with σ^2 unknown.

► **Point Estimator.** $\hat{\mu} = \bar{X}$ with “Good” properties:

► $E(\bar{X}) = \mu$; $V(\bar{X}) = \frac{\sigma^2}{n}$; $\bar{X} \sim N(\mu, \frac{\sigma^2}{n})$

How about the unknown σ^2 ?

$$\hat{\sigma}^2 = S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$$

► $E(S^2) = \sigma^2$; distn of S^2 ?

Proposition. (1) $\frac{(n-1)S^2}{\sigma^2} \sim \chi^2(n-1)$. (2) S^2 and \bar{X} are indpt. (3)

$T = \frac{\bar{X} - \mu}{\hat{\sigma}/\sqrt{n}} \sim t(n-1)$.

► **Confidence Interval.** $(\hat{\theta}_L, \hat{\theta}_U)$ with

$$\hat{\theta}_L = \bar{X} - (t_{1-\frac{\alpha}{2}}(n-1)) \frac{\hat{\sigma}}{\sqrt{n}}, \quad \hat{\theta}_U = \bar{X} + (t_{1-\frac{\alpha}{2}}(n-1)) \frac{\hat{\sigma}}{\sqrt{n}}$$

► $P((\hat{\theta}_L, \hat{\theta}_U) \ni \mu) = 1 - \alpha$, since $P(\hat{\theta}_L \geq \mu) = \alpha/2$ and $P(\hat{\theta}_U \leq \mu) = \alpha/2$.

3.1.2 Confidence Interval: to estimate μ

Consider rv X with $\mu = E(X)$, and a random sample $\{X_1, \dots, X_n\}$ from the population.

Setting 3. $X \sim F(x; \theta)$ with $\theta = \mu$, the population mean. To estimate $\theta = \mu$ when $n \gg 1$.

▶ **Point Estimator.** $\hat{\mu} = \bar{X}$ with “good” properties:

- ▶ $E(\bar{X}) = \mu$; $V(\bar{X}) = \frac{\sigma^2}{n}$;
- ▶ By the CLT, $\bar{X} \sim N(\mu, \frac{\sigma^2}{n})$ approximately.

▶ $1 - \alpha$ **Confidence Interval.**

- ▶ an approximate CI of $(1 - \alpha)$ level when σ^2 is known:

$$\bar{X} \pm z_{1-\frac{\alpha}{2}} \sqrt{\frac{\sigma^2}{n}}$$

because $\frac{\bar{X}-\mu}{\sqrt{\sigma^2/n}} \sim N(0, 1)$ approximately.

- ▶ an approximate CI of $(1 - \alpha)$ level when σ^2 is unknown:

$$\bar{X} \pm t_{1-\frac{\alpha}{2}} \sqrt{\frac{S^2}{n}} \approx \bar{X} \pm z_{1-\frac{\alpha}{2}} \sqrt{\frac{S^2}{n}}$$

because $\frac{\bar{X}-\mu}{\sqrt{S^2/n}} \sim t(n-1)$ approximately, close to $N(0, 1)$ if

Example. r.v. $X \sim \text{Bernoulli}(p)$: $X = \begin{cases} 1 \\ 0, \end{cases}$ with $P(X = 1) = p$.

To estimate p with a random sample $\{X_1, \dots, X_n\}$ when $n \gg 1$.

- ▶ Firstly, $\mu = E(X) = p$ and $\sigma^2 = V(X) = p(1 - p)$.
- ▶ Thus, a point estimator of p : $\hat{p} = \bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$.
- ▶ Because $n \gg 1$, an approximate $1 - \alpha$ CI of p :

$$\hat{p} \pm z_{1-\frac{\alpha}{2}} \sqrt{\frac{S^2}{n}},$$

$$\text{similar to } \hat{p} \pm z_{1-\frac{\alpha}{2}} \sqrt{\frac{\hat{p}(1-\hat{p})}{n}},$$

$$\text{since } S^2 = \frac{1}{n-1} (\sum X_i^2 - n\bar{X}^2) = \frac{n}{n-1} \hat{p}(1 - \hat{p}) \approx \hat{p}(1 - \hat{p})$$

Example 3.2 From a sample of 1250 BC voters, 420 of them indicate that they support the NDP. Obtain an approximate 95% CI for the proportion of BC voters who support the NDP. [(.310, .362)]

- ▶ Population: r.v. $X=1$ or 0 to indicate a vote for NDP in BC. $X \sim (1, p)$.
- ▶ Random sample: iid r.v.s $X_1, X_2, \dots, X_{1250}$ (votes from BC). with $\bar{X}_{obs} = \bar{x} = 420/1250$ (\hat{p}).
- ▶ 95% Confidence Interval of $\theta = \mu = E(X) = p$:

$$\hat{\theta}_L = \bar{x} - 1.96 \frac{s}{\sqrt{1250}}, \quad \hat{\theta}_U = \bar{x} + 1.96 \frac{s}{\sqrt{1250}}$$

$s^2 = \frac{n}{n-1} \hat{p}(1 - \hat{p}) \approx \hat{p}(1 - \hat{p}) = 0.223 \implies$ an approximate 95% CI: (.310, .362).

Remarks:

- ▶ The result is usually reported in *news* as “33.5% \pm 2.6% support for NDP”
- ▶ An alternative solution:
 - ▶ $Y = \#$ of NDP supporters out of 1250 BC voters
 $\sim \text{Bin}(1250, p)$, approximately $N(1250p, 1250p(1 - p))$.
 - ▶ $Z = \frac{Y - 1250p}{\sqrt{1250p(1-p)}} = \frac{\frac{Y}{1250} - p}{\sqrt{p(1-p)/1250}} \sim N(0, 1)$ approximately.

So, an approximate 95% CI of p is

$$\frac{Y}{1250} \pm (1.96)\sqrt{\hat{p}(1 - \hat{p})/1250} = .336 \pm .026.$$

$$\hat{p} = \frac{Y}{1250} = \bar{X}$$

3.1.2 Confidence Interval: to estimate other population parameter

Consider the following topics:

- ▶ How to estimate $\sigma^2 = \text{Var}(X)$?
- ▶ How to estimate $\mu_X - \mu_Y$ for the two populations, say, X, Y ?
- ▶ How about to estimate θ when $X \sim F(x; \theta)$ in general?

What will we study next?

1. *Introduction*

2. *Probability and Distribution (Chp 1-3)*

3. Important Topics in Mathematical Statistics (Chp 4-6)

▶ **3.1 Elementary Statistical Inferences**

▶ *3.1.1 Sampling and Statistics*

▶ *3.1.2 Confidence Interval*

▶ **3.1.3 Order Statistics**

▶ **3.1.4 Hypothesis Testing**

▶ *3.1.5 Statistical Simulation and Bootstrap*

▶ *3.2 Consistency and Limiting Distributions*

▶ *3.3 Maximum Likelihood Methods*

4. *Further Topics, Selected from Chp 7-11*