

Topics for Today

- 1.) Basic Growth Facts (from last time)
- 2.) Alternative Growth Models
- 3.) Problems with Solow
- 4.) The Cass-Koopmans Model
 - The Planner's Problem
 - Phase Diagram + Saddle path
 - Linearization / Local Convergence Rates

Leading Growth Models

1.) Solow Model

- everything exogenous (saving, labor, technology)

2.) Cass-Koopmans Model

- saving endogenous; labor + technology exogenous

3.) Diamond Model

- same as Cass-Koopmans except finite-lived OLG (incomplete mkt).

exogenous
growth

4.) Romer (JPE, 1986)

- externalities

5.) Lucas (JME, 1988)

- human capital accumulation

6.) Romer (JPE, 1990)

- R + D.

endogenous
growth

Solow

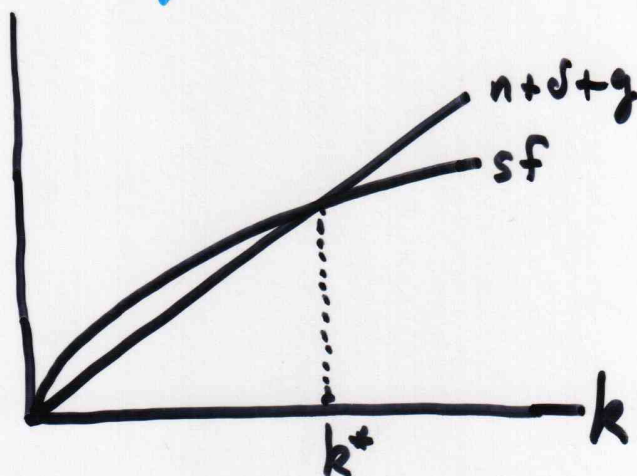
$$Y = K^{\alpha} (AL)^{1-\alpha}$$

$$\frac{\dot{A}}{A} = g \quad \left. \vphantom{\frac{\dot{A}}{A} = g} \right\} \text{Labor-augmenting tech. progress}$$

$$k = \frac{K}{LA} \quad \frac{\dot{L}}{L} = n$$

$$\dot{k} = s f(k) - (n + \delta + g)k$$

← saving rate



Problems with Solow

- 1.) Cannot explain long-run per capita growth.
 - Tech. assumed exogenous!
 - Changes in saving + investment affect steady state level of output, but not its growth rate

2.) Differences in savings rates cannot explain differences in international income levels.

Example

Suppose rich & poor have same technology.

$$y_r = Ak_r^\alpha \quad y_p = Ak_p^\alpha \Rightarrow \frac{y_r}{y_p} = \left(\frac{k_r}{k_p}\right)^{\frac{1}{3}}$$

$$\alpha = \frac{1}{3}$$

$$\Rightarrow \frac{k_r}{k_p} = \left(\frac{y_r}{y_p}\right)^3$$

$$\frac{y_r}{y_p} = 10 \Rightarrow \frac{k_r}{k_p} = 1000!$$

$$\text{Or, since } \frac{k_r}{k_p} = \left(\frac{s_r}{s_p}\right)^{\frac{1}{1-\alpha}} \Rightarrow \frac{y_r}{y_p} = \left(\frac{s_r}{s_p}\right)^{\frac{\alpha}{1-\alpha}} = \left(\frac{s_r}{s_p}\right)^2$$

$$\text{Therefore, } \frac{s_r}{s_p} = \left(\frac{y_r}{y_p}\right)^2 = 100!$$

$$\text{Or, since } r = \alpha k^{\alpha-1}, \quad \frac{r_p}{r_r} = \left(\frac{k_p}{k_r}\right)^{\alpha-1} = \left(\frac{y_r}{y_p}\right)^{\frac{1-\alpha}{\alpha}}$$

$$\Rightarrow \frac{r_p}{r_r} = \left(\frac{y_r}{y_p}\right)^2 = 100!$$

3.) Predicted Convergence Rates Too High

Example

Assume $g = 0$

Linearize the Solow diff. eq. (around steady state)

$$\dot{k} = s\alpha(k^*)^{\alpha-1}(k-k^*) - (\delta+n)(k-k^*)$$

Note: $(k^*)^{\alpha-1} = \frac{\delta+n}{s}$

$$\Rightarrow \dot{k} = (\delta+n)(\alpha-1)(k-k^*)$$

$$\alpha = 1/3 \quad \delta = .05 \quad n = .01$$

$$\Rightarrow (\delta+n)(\alpha-1) \approx .04 - .05$$

Observed: .02 (Barro + Sala-i-Martin (1992)).

4.) Normative Analysis Not Possible

- How fast should an economy grow?

Cass-Koopmans Model

Assumptions

- 1.) Representative ∞ -horizon agent/dynastic family
- complete mkt.s.
- 2.) Perfect Comp. / Constant Returns
- 3.) Exogenous Labor + Technology

Planner's Problem

- 2nd Welfare Theorem (P.O $\Rightarrow$ Comp. Equil.)
- Later we'll discuss market decentralization

$$\max_c \int_0^{\infty} u(c) e^{-(\rho+n)t} dt$$

$$\text{s.t. } \dot{k} = f(k) - (\delta+n)k - c$$

Current-Valued Hamiltonian

$$H^c = u(c) + \lambda [f(k) - (\delta+n)k - c]$$

FOCs

$$1.) H_c = 0 : \quad u'(c) - \lambda = 0$$

$$2.) \dot{k} = H_k : \quad k' = f(k) - (\delta+n)k - c$$

$$3.) \dot{\lambda} = (\rho+n)\lambda - H_{kk} : \quad \dot{\lambda} = (\rho+n)\lambda - \lambda [f'(k) - (\delta+n)]$$

$$\text{From (1)} \quad \dot{\lambda} = u''(c) \dot{c}$$

Sub into (3)

$$u''(c) \dot{c} = u'(c) [\rho + \delta - f'(k)]$$

$$\text{Or} \quad \frac{\dot{c}}{c} = \frac{-u'(c)}{cu''(c)} [f'(k) - (\rho + \delta)]$$

$$\text{Assume } u = \frac{c^{1-\theta}}{1-\theta} \Rightarrow \frac{-u'}{cu''} = \frac{1}{\theta}$$

θ = Constant Relative Risk Aversion

$\frac{1}{\theta}$ = Intertemporal Marginal Rate of Substitution

- Hence, the optimal path is characterized by the following first-order (nonlinear) system

$$\dot{k} = f(k) - (\delta + n)k - c$$

$$\frac{\dot{c}}{c} = \frac{1}{\theta} [f'(k) - (\rho + \delta)]$$

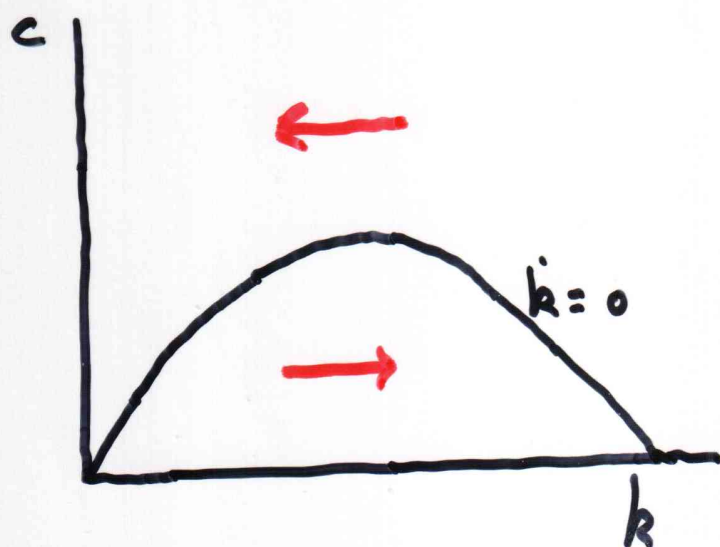
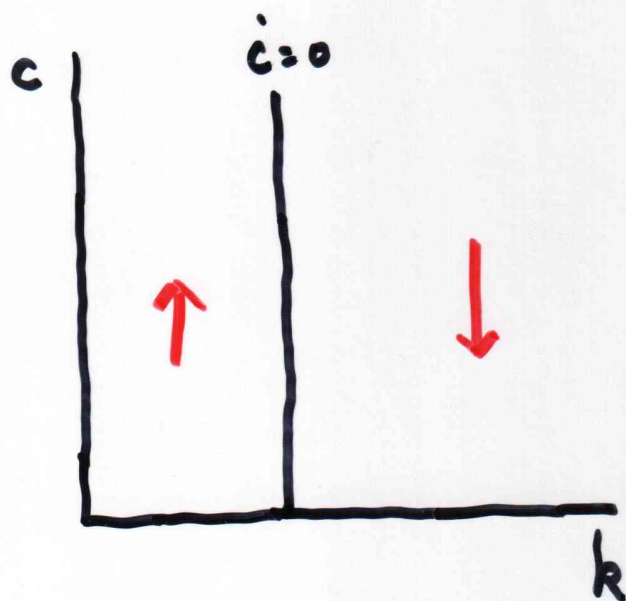
Cass-Koopmans

Along with the Transversality Condition,

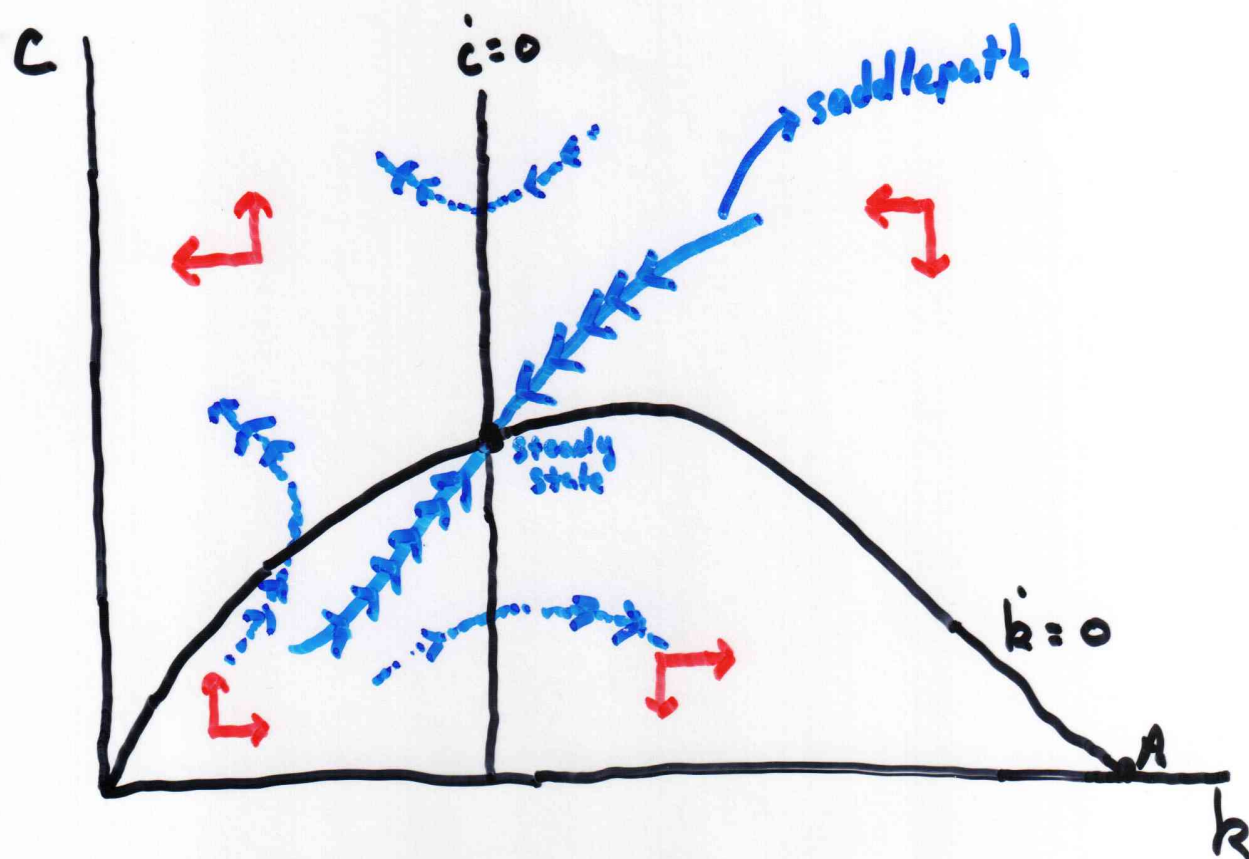
$$\lim_{t \rightarrow \infty} e^{-(\rho+n)t} \lambda(t) k(t) = 0$$

Phase Diagram

- We can analyze this system using a "phase diagram"



- Putting them together,



- All paths except the saddlepath either hit the vertical axis and violate the Euler eq. (c jumps to 0 when $k=0$), or converge to pt. A, which violates the TVC (because $u'(c) = \lambda$ rises faster than $\rho - n$).

Comments

- 1.) Given an initial $k(0)$, $c(0)$ must jump up to the saddlepath. Along the saddlepath c & k move together until they converge to the steady state (i.e., $c = g(k)$, where $g(\cdot)$ is like a DP policy function).
- 2.) At the steady state, Y , K , and C all grow at rate n (balanced growth). Per capita output & consumption converge to constants unless there is (exogenous) tech. progress. Hence, like Solow, the CLC model fails to explain (sustained) growth in living standards.
- 3.) At the steady state, consumption is below the "Golden Rule"
- 4.) Depending on parameters, convergence rate to the steady state can be either slower or faster than Solow.

Steady State Saving Rate

- At steady state,

$$f(k^*) - (\delta + n)k^* - c^* = 0$$

$$s^* = 1 - \frac{c^*}{f(k^*)}$$

$$\Rightarrow \frac{c^*}{f(k^*)} = 1 - (\delta + n) \frac{k^*}{f(k^*)}$$

With Cobb-Douglas,

$$f' \cdot k = \alpha f \Rightarrow \frac{k^*}{f(k^*)} = \frac{\alpha}{f'(k^*)}$$

From s.s. Euler,

$$f'(k^*) = \rho + \delta$$

Therefore,

$$s^* = (\delta + n) \frac{k^*}{f(k^*)} = (\delta + n) \frac{\alpha}{f'(k^*)}$$

$$= \frac{(\delta + n) \alpha}{\delta + \rho} < \alpha$$

Golden
Rule
Saving
rate

Example

$$\delta = .05$$

$$\rho = .02$$

$$n = .01$$

$$\alpha = \frac{1}{3}$$

$$\Rightarrow s^* = 28.6\% \text{ (gross saving rate).}$$

- What about θ ? Influence s^* if $g = \dot{A}/A \neq 0$

$$s^* = \frac{\alpha(\delta + n + g)}{\delta + \rho + \theta g}$$

- However, main influence of θ is during transition
- Suppose $k(u) < k^*$. Two offsetting effects on saving:

1.) Income below s.s. } Income Effect
 $\Rightarrow$ want to borrow to smooth consumption

2.) Low $k \Rightarrow$ high MPK/high interest rate } Substitution Effect
 $\Rightarrow$ return on saving is high

High $\theta \Rightarrow$ Low intertemp. substitution
 $\Rightarrow$ Income effect $>$ Substitution effect
 $\Rightarrow$ Saving rate lower than s^*
 $\Rightarrow$ Slow convergence

Low $\theta \Rightarrow$ High intertemp. substitution
 $\Rightarrow$ Income effect $<$ Substitution effect
 $\Rightarrow$ Saving rate higher than at s^*
 $\Rightarrow$ Fast convergence

Threshold Values

$$\frac{1}{\theta} = s^* \Rightarrow \text{constant saving rate}$$

empirically realistic case $\frac{1}{\theta} > s^* \Rightarrow$ higher saving rate when $k(t) < k^*$

$$\frac{1}{\theta} < s^* \Rightarrow \text{lower saving rate when } k(t) < k^*$$

Local Approximation (around s.s.) to Convergence Rate

$$\dot{k} \approx \frac{\partial \dot{k}}{\partial k} \cdot (k - k^*) + \frac{\partial \dot{k}}{\partial c} (c - c^*)$$

$$\dot{c} \approx \frac{\partial \dot{c}}{\partial k} \cdot (k - k^*) + \frac{\partial \dot{c}}{\partial c} \cdot (c - c^*)$$

$$\frac{\partial \dot{k}}{\partial k} = f'(k^*) - (n + \delta) = p + \delta - (n + \delta) = p - n$$

$$\frac{\partial \dot{k}}{\partial c} = -1$$

$$\frac{\partial \dot{c}}{\partial k} = \frac{c^*}{\theta} f''(k^*)$$

$$\frac{\partial \dot{c}}{\partial c} = \frac{1}{\theta} [f'(k^*) - (p + \delta)] = 0$$

• Write in matrix form,

$$\begin{pmatrix} \dot{k} \\ \dot{c} \end{pmatrix} = \begin{bmatrix} p-n & -1 \\ \frac{c^*}{\theta} f''(k^*) & 0 \end{bmatrix} \begin{pmatrix} k-k^* \\ c-c^* \end{pmatrix}$$

$\det = \frac{c^*}{\theta} f'' < 0$
 $\Rightarrow$ eigenvalues have opposite signs
 $\Rightarrow$ saddle point stability

Eigenvalues

$$\begin{vmatrix} p-n-\lambda & -1 \\ \frac{c^*}{\theta} f''(k^*) & -\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 - (p-n)\lambda + \frac{c^*}{\theta} f'' = 0$$

$$\Rightarrow \lambda_{1,2} = \frac{p-n \pm \sqrt{(p-n)^2 - 4 \frac{c^*}{\theta} f''}}{2}$$

Let $\lambda_1 < 0$, $\lambda_2 > 0$ $\lambda_1 = \frac{1}{2} \left[(p-n) - \sqrt{(p-n)^2 - 4 \frac{c^*}{\theta} f''} \right]$

$$\begin{pmatrix} \dot{k} \\ \dot{c} \end{pmatrix} = c_1 e^{\lambda_1 t} + c_2 e^{\lambda_2 t}$$

eigenvector associated with stable eigenvalue (saddle path)

eigenvector associated with unstable eigenvalue $= 0$ by TVC.

- Stable eigenvector / Saddlepath

$$\begin{bmatrix} p-n-\lambda_1 & -1 \\ \frac{c^*}{\theta} f''(k^*) & -\lambda_1 \end{bmatrix} \begin{pmatrix} c_{11} \\ c_{21} \end{pmatrix} = 0$$

From initial condition, $c_{11} = k(0) - k^*$ → jump to saddlepath

$$\Rightarrow c_{21} = (p-n-\lambda_1)(k(0) - k^*) = c(0) - c^*$$

$$\begin{aligned} \Rightarrow k(t) &= k^* + [k(0) - k^*] e^{\lambda_1 t} \\ c(t) &= c^* + [c(0) - c^*] e^{\lambda_1 t} \end{aligned} \quad \left. \vphantom{\begin{aligned} \Rightarrow k(t) &= k^* + [k(0) - k^*] e^{\lambda_1 t} \\ c(t) &= c^* + [c(0) - c^*] e^{\lambda_1 t} \end{aligned}} \right\} \text{Local Approx. to optimal time paths}$$

Convergence Rates

Sub in for k^*, c^*

$$\lambda_1 = \frac{1}{2} \left[(p-n) - \sqrt{(p-n)^2 + \frac{4}{\theta} \frac{1-\alpha}{\alpha} (p+\delta) [p+\delta - \alpha(\delta+n)]} \right]$$

Remember Solow: $\lambda_1 = -(1-\alpha)(n+\delta)$

$$p = .02$$

$$n = .01$$

$$\theta = 1$$

$$\alpha = \frac{1}{3}$$

$$\delta = .05$$

$$\Rightarrow \lambda_1 = -.079$$

$$\text{Solow} = -.04$$

However, if $\theta = 8$
then $\lambda_1 = -.025$