STAT 830 Likelihood Asymptotics

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Purposes of These Notes

- Discuss the behaviour of mles in large samples.
- Show log-likelihood is nearly quadratic.
- Emphasize local rather than global behaviour.
- Give sequence of examples.



Large Sample Theory

- Study approximate behaviour of $\hat{\theta}$ by studying the function U.
- Notice U is sum of independent random variables.

If Y_1, Y_2, \ldots are iid with mean μ then

$$\frac{\sum Y_i}{n} \to \mu$$

Law of large numbers. Strong law

$$P(\lim \frac{\sum Y_i}{n} = \mu) = 1$$

and the weak law that

$$\lim P(|\frac{\sum Y_i}{n} - \mu| > \epsilon) = 0$$

• For iid Y_i the stronger conclusion holds; for our heuristics ignore differences between these notions.



Score function at true value of θ

- Now suppose θ_0 is true value of θ .
- Then

$$U(\theta)/n \to \mu(\theta)$$

where

$$\mu(\theta) = E_{\theta_0} \left[\frac{\partial \log f}{\partial \theta} (X_i, \theta) \right]$$
$$= \int \frac{\partial \log f}{\partial \theta} (x, \theta) f(x, \theta_0) dx$$



Normal example

• Example: $N(\mu, 1)$ data:

$$U(\mu)/n = \sum (X_i - \mu)/n = \bar{X} - \mu$$

ullet If the true mean is μ_0 then $ar X o \mu_0$ and

$$U(\mu)/n \to \mu_0 - \mu$$

- Consider $\mu < \mu_0$: derivative of $\ell(\mu)$ is likely to be positive so that ℓ increases as μ increases.
- For $\mu > \mu_0$: derivative is probably negative and so ℓ tends to be decreasing for $\mu > 0$.
- Hence: ℓ is likely to be maximized close to μ_0 .



Same ideas in more general case

Study rv

$$\log[f(X_i,\theta)/f(X_i,\theta_0)].$$

You know the inequality

$$E(X)^2 \leq E(X^2)$$

(difference is $Var(X) \ge 0$.)

• Generalization: Jensen's inequality: for g a convex function ($g'' \ge 0$ roughly) then

$$g(E(X)) \leq E(g(X))$$



- Inequality above has $g(x) = x^2$.
- Use $g(x) = -\log(x)$: convex because $g''(x) = x^{-2} > 0$. We get

$$-\log(E_{\theta_0}[f(X_i,\theta)/f(X_i,\theta_0)] \leq E_{\theta_0}[-\log\{f(X_i,\theta)/f(X_i,\theta_0)\}]$$

But

$$E_{\theta_0} \left[\frac{f(X_i, \theta)}{f(X_i, \theta_0)} \right] = \int \frac{f(x, \theta)}{f(x, \theta_0)} f(x, \theta_0) dx$$
$$= \int f(x, \theta) dx$$
$$= 1$$

• Reassemble the inequality and this calculation to get

$$E_{\theta_0}[\log\{f(X_i,\theta)/f(X_i,\theta_0)\}] \leq 0$$



- Fact: inequality is strict unless the θ and θ_0 densities are actually the same.
- Let $\mu(\theta) < 0$ be this expected value.
- Then for each θ we find

$$\frac{\ell(\theta) - \ell(\theta_0)}{n} = \frac{\sum \log[f(X_i, \theta) / f(X_i, \theta_0)]}{n} \to \mu(\theta)$$

- ullet This proves likelihood probably higher at $heta_0$ than at any other single heta.
- Idea can often be stretched to prove that the mle is **consistent**; need **uniform** convergence in θ .



- **Definition** A sequence $\hat{\theta}_n$ of estimators of θ is consistent if $\hat{\theta}_n$ converges weakly (or strongly) to θ .
- **Proto theorem**: In regular problems the mle $\hat{\theta}$ is consistent.
- More precise statements of possible conclusions.
- Use notation

$$N(\epsilon) = \{\theta : |\theta - \theta_0| \le \epsilon\}.$$

- Suppose: $\hat{\theta}_n$ is global maximizer of ℓ .
- $\hat{\theta}_{n,\delta}$ maximizes ℓ over $N(\delta) = \{ |\theta \theta_0| \leq \delta \}$.

$$A_{\epsilon} = \{|\hat{\theta}_n - \theta_0| \le \epsilon\}$$

$$B_{\delta,\epsilon} = \{|\hat{\theta}_{n,\delta} - \theta_0| \le \epsilon\}$$

$$C_L = \{\exists ! \theta \in N(L/n^{1/2}) : U(\theta) = 0, U'(\theta) < 0\}$$



Some precision

- **①** Under (unspecified) conditions **I** $P(A_{\epsilon})
 ightarrow 1$ for each $\epsilon > 0$.
- ② Under conditions II there is a $\delta > 0$ such that for all $\epsilon > 0$ we have $P(B_{\delta,\epsilon}) \to 1$.
- **3** Under conditions **III** for all $\delta > 0$ there is an L so large and an n_0 so large that for all $n \ge n_0$, $P(C_L) > 1 \delta$.
- **①** Under conditions **III** there is a sequence L_n tending to ∞ so slowly that $P(C_{L_n}) \to 1$.

Point: conditions get weaker as conclusions get weaker. Many possible conditions in literature. See book by Zacks for some precise conditions.



Asymptotic Normality

- Study shape of log likelihood near the true value of θ .
- Assume $\hat{\theta}$ is a root of the likelihood equations close to θ_0 .
- Taylor expansion (1 dimensional parameter θ):

$$U(\hat{\theta}) = 0$$

$$= U(\theta_0) + U'(\theta_0)(\hat{\theta} - \theta_0)$$

$$+ U''(\tilde{\theta})(\hat{\theta} - \theta_0)^2/2$$

for some $\tilde{\theta}$ between θ_0 and $\hat{\theta}$.

• WARNING: This form of the remainder in Taylor's theorem is not valid for multivariate θ .



Asymptotic normality continued

- Derivatives of *U* are sums of *n* terms.
- So each derivative should be proportional to *n* in size.
- Second derivative is multiplied by the square of the small number $\hat{\theta} \theta_0$ so should be negligible compared to the first derivative term.
- Ignoring second derivative term get

$$-U'(\theta_0)(\hat{\theta}-\theta_0)\approx U(\theta_0)$$

• Now look at terms U and U'.



Asymptotic normality continued

Normal case:

$$U(\theta_0) = \sum (X_i - \mu_0)$$

has a normal distribution with mean 0 and variance n (SD \sqrt{n}).

Derivative is

$$U'(\mu)=-n$$
.

- Next derivative U" is 0.
- Notice: both U and U' are sums of iid random variables.
- Let

$$U_i = \frac{\partial \log f}{\partial \theta}(X_i, \theta_0)$$

and

$$V_i = -\frac{\partial^2 \log f}{\partial \theta^2}(X_i, \theta)$$



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- In general, $U(\theta_0) = \sum U_i$ has mean 0 and approximately a normal distribution.
- Here is how we check that:

$$E_{\theta_0}(U(\theta_0)) = nE_{\theta_0}(U_1)$$

$$= n \int \frac{\partial \log(f(x,\theta_0))}{\partial \theta} f(x,\theta_0) dx$$

$$= n \int \frac{\partial f(x,\theta_0)/\partial \theta}{f(x,\theta_0)} f(x,\theta_0) dx$$

$$= n \int \frac{\partial f}{\partial \theta} (x,\theta_0) dx$$

$$= n \frac{\partial}{\partial \theta} \int f(x,\theta) dx \Big|_{\theta=\theta_0}$$

$$= n \frac{\partial}{\partial \theta} 1$$

$$= 0$$



- Notice: interchanged order of differentiation and integration at one point.
- This step is usually justified by applying the dominated convergence theorem to the definition of the derivative.
- Differentiate identity just proved:

$$\int \frac{\partial \log f}{\partial \theta}(x,\theta) f(x,\theta) dx = 0$$

ullet Take derivative of both sides wrt heta; pull derivative under integral sign:

$$\int \frac{\partial}{\partial \theta} \left[\frac{\partial \log f}{\partial \theta} (x, \theta) f(x, \theta) \right] dx = 0$$

• Do the derivative and get

$$-\int \frac{\partial^2 \log(f)}{\partial \theta^2} f(x, \theta) dx = \int \frac{\partial \log f}{\partial \theta} (x, \theta) \frac{\partial f}{\partial \theta} (x, \theta) dx$$
$$= \int \left[\frac{\partial \log f}{\partial \theta} (x, \theta) \right]^2 f(x, \theta) dx$$



Definition: The **Fisher Information** is

$$I(\theta) = -E_{\theta}(U'(\theta)) = nE_{\theta_0}(V_1)$$

- We refer to $\mathcal{I}(\theta_0) = E_{\theta_0}(V_1)$ as the information in 1 observation.
- The idea is that I is a measure of how curved the log likelihood tends to be at the true value of θ .
- Big curvature means precise estimates.
- Our identity above is

$$I(heta) = Var_{ heta}(U(heta)) = n\mathcal{I}(heta)$$

Now we return to our Taylor expansion approximation

$$-U'(\theta_0)(\hat{\theta}-\theta_0)\approx U(\theta_0)$$

and study the two appearances of U.

- Have shown $U = \sum U_i$ is a sum of iid mean 0 random variables.
- The central limit theorem thus proves that

$$n^{-1/2}U(\theta_0) \Rightarrow N(0,\sigma^2)$$

where $\sigma^2 = \text{Var}(U_i) = E(V_i) = \mathcal{I}(\theta)$.



Next observe that

$$-U'(\theta)=\sum V_i$$

where again

$$V_i = -\frac{\partial U_i}{\partial \theta}$$

• The law of large numbers can be applied to show

$$-U'(\theta_0)/n \to E_{\theta_0}[V_1] = \mathcal{I}(\theta_0)$$

Now manipulate our Taylor expansion as follows

$$n^{1/2}(\hat{\theta}-\theta_0) \approx \left[\frac{\sum V_i}{n}\right]^{-1} \frac{\sum U_i}{\sqrt{n}}$$

• Apply Slutsky's Theorem to conclude that the right hand side of this converges in distribution to $N(0, \sigma^2/\mathcal{I}(\theta)^2)$ which simplifies, because of the identities, to $N\{0, 1/\mathcal{I}(\theta)\}$.

Summary

- In regular families: assuming $\hat{\theta} = \hat{\theta}_n$ is a consistent root of $U(\theta) = 0$.
- $n^{-1/2}U(\theta_0) \Rightarrow MVN(0,\mathcal{I})$ where

$$\mathcal{I}_{ij} = \mathrm{E}_{\theta_0} \left\{ V_{1,ij}(\theta_0) \right\}$$

and

$$V_{k,ij}(\theta) = -\frac{\partial^2 \log f(X_k, \theta)}{\partial \theta_i \partial \theta_j}$$

• If $V_k(\theta)$ is the matrix $[V_{k,ij}]$ then

$$\frac{\sum_{k=1}^{n} \mathbf{V}_{k}(\theta_{0})}{n} \to \mathcal{I}$$

• If $V(\theta) = \sum_k V_k(\theta)$ then

$$\{\mathbf{V}(\theta_0)/n\}n^{1/2}(\hat{\theta}-\theta_0)-n^{-1/2}U(\theta_0)\to 0$$

in probability as $n \to \infty$.



Summary Continued

Also

$$\{\mathbf{V}(\hat{\theta})/n\}n^{1/2}(\hat{\theta}-\theta_0)-n^{-1/2}U(\theta_0)\to 0$$

in probability as $n \to \infty$.

- $n^{1/2}(\hat{\theta}-\theta_0)-\{\mathcal{I}(\theta_0)\}^{-1}U(\theta_0)\to 0$ in probability as $n\to\infty$.
- $n^{1/2}(\hat{\theta}-\theta_0) \Rightarrow MVN(0,\mathcal{I}^{-1}).$
- In general (not just iid cases)

$$\sqrt{I(\theta_0)}(\hat{\theta} - \theta_0) \Rightarrow N(0, 1)$$

$$\sqrt{I(\hat{\theta})}(\hat{\theta} - \theta_0) \Rightarrow N(0, 1)$$

$$\sqrt{V(\theta_0)}(\hat{\theta} - \theta_0) \Rightarrow N(0, 1)$$

$$\sqrt{V(\hat{\theta})}(\hat{\theta} - \theta_0) \Rightarrow N(0, 1)$$

where $V=-\ell''$ is the so-called *observed information*, the negative second derivative of the log-likelihood.

• **Note**: If the square roots are replaced by matrix square roots we clet θ be vector valued and get MVN(0, I) as the limit law.

- Why all these different forms?
- Use limit laws to test hypotheses and compute confidence intervals.
- Test H_o : $\theta = \theta_0$ using one of the 4 quantities as test statistic.
- Find confidence intervals using quantities as pivots.
- E.g.: second and fourth limits lead to confidence intervals

$$\hat{\theta} \pm z_{\alpha/2}/\sqrt{I(\hat{\theta})}$$

and

$$\hat{\theta} \pm z_{\alpha/2} / \sqrt{V(\hat{\theta})}$$

respectively.

The other two are more complicated.



• For iid $N(0, \sigma^2)$ data we have

$$V(\sigma) = \frac{3\sum X_i^2}{\sigma^4} - \frac{n}{\sigma^2}$$

and

$$I(\sigma) = \frac{2n}{\sigma^2}$$

• The first line above then justifies confidence intervals for σ computed by finding all those σ for which

$$\left|\frac{\sqrt{2n}(\hat{\sigma}-\sigma)}{\sigma}\right| \leq z_{\alpha/2}$$

- Similar interval can be derived from 3rd expression, though this is much more complicated.
- Usual summary: mle is consistent and asymptotically normal with asymptotic variance which is the inverse of the Fisher information.



Problems with maximum likelihood

- Many parameters lead to poor approximations. MLEs can be far from right answer.
- See homework for Neyman Scott example where MLE is not consistent.
- Multiple roots of the likelihood equations: you must choose the right root.
- Start with different, consistent, estimator; apply iterative scheme like Newton Raphson to likelihood equations to find MLE.
- Not many steps of NR generally required if starting point is a reasonable estimate.



Finding (good) preliminary Point Estimates

- Method of Moments
- Basic strategy: set sample moments equal to population moments and solve for the parameters.
- **Definition**: The r^{th} sample moment (about the origin) is

$$\frac{1}{n} \sum_{i=1}^{n} X_i^r$$

• The rth population moment is

$$\mathrm{E}(X^r)$$

(Central moments are

$$\frac{1}{n}\sum_{i=1}^{n}(X_{i}-\bar{X})^{r}$$

and

$$E[(X-\mu)^r]$$
.



Method of moments continued

• If we have p parameters we can estimate the parameters $\theta_1, \dots, \theta_p$ by solving the system of p equations:

$$\mu_1 = \bar{X}$$

$$\mu_2' = \overline{X^2}$$

and so on to

$$\mu_p' = \overline{X^p}$$

• Remember that population moments μ_k' are formulas involving the parameters.



Gamma Example

• The Gamma (α, β) density is

$$f(x; \alpha, \beta) = \frac{1}{\beta \Gamma(\alpha)} \left(\frac{x}{\beta}\right)^{\alpha - 1} \exp\left[-\frac{x}{\beta}\right] 1(x > 0)$$

and has

$$\mu_1 = \alpha \beta$$

and

$$\mu_2' = \alpha(\alpha + 1)\beta^2.$$

This gives the equations

$$\alpha\beta = \overline{X}$$
$$\alpha(\alpha + 1)\beta^2 = \overline{X^2}$$

or

$$\alpha\beta = \overline{X}$$
$$\alpha\beta^2 = \overline{X^2} - \overline{X}^2.$$



Gamma continued

 \bullet Divide the second equation by the first to find the method of moments estimate of β is

$$\tilde{\beta} = (\overline{X^2} - \overline{X}^2)/\overline{X} \,.$$

Then from the first equation get

$$\tilde{\alpha} = \overline{X}/\tilde{\beta} = (\overline{X})^2/(\overline{X^2} - \overline{X}^2).$$

 Method of moments equations much easier to solve than likelihood equations which involve digamma ftn

$$\psi(\alpha) = \frac{d}{d\alpha} \log(\Gamma(\alpha))$$

Score function has components

$$U_{\beta} = \frac{\sum X_i}{\beta^2} - n\alpha/\beta$$

and

$$U_{\alpha} = -n\psi(\alpha) + \sum \log(X_i) - n\log(\beta)$$
.



Gamma continued

• You can solve for β in terms of α to leave you trying to find a root of the equation

$$-n\psi(\alpha) + \sum \log(X_i) - n\log(\sum X_i/(n\alpha)) = 0$$

 To use Newton Raphson on this you begin with the preliminary estimate $\hat{\alpha}_1 = \tilde{\alpha}$ and then compute iteratively

$$\hat{\alpha}_{k+1} = \frac{\overline{\log(X)} - \psi(\hat{\alpha}_k) - \log(\overline{X})/\hat{\alpha}_k}{1/\alpha - \psi'(\hat{\alpha}_k)}$$

until the sequence converges.

- Computation of ψ' , the trigamma function, requires special software.
- Web sites like netlib and statlib are good sources for this sort of things

Estimating Equations

- Same large sample ideas arise whenever estimates derived by solving some equation.
- Example: large sample theory for **Generalized Linear Models**.
- Suppose Y_i is number of cancer cases in some group of people characterized by values x_i of some covariates.
- Think of x_i as containing variables like age, or a dummy for sex or average income or
- Possible parametric regression model: Y_i has a Poisson distribution with mean μ_i where the mean μ_i depends somehow on x_i .
- Typically assume $g(\mu_i) = \beta_0 + x_i \beta$; g is **link** function.
- Often $g(\mu) = \log(\mu)$ and $x_i\beta$ is a matrix product: x_i row vector, β column vector.

GLM: "Linear regression model with Poisson errors"

- Special case $log(\mu_i) = \beta x_i$ where x_i is a scalar.
- The log likelihood is simply (ignoring irrelevant factorials)

$$\ell(\beta) = \sum (Y_i \log(\mu_i) - \mu_i).$$

• The score function is, since $log(\mu_i) = \beta x_i$,

$$U(\beta) = \sum (Y_i x_i - x_i \mu_i) = \sum x_i (Y_i - \mu_i).$$

- Notice again that the score has mean 0 when you plug in the true parameter value.
- Key observation: no need to believe Y_i has Poisson distribution to make solving equation U = 0 sensible.
- Suppose only that $\log(E(Y_i)) = x_i \beta$.
- Then we have assumed that $E_{\beta}(U(\beta)) = 0$.
- Key condition to prove existence of consistent root of likelihood equations; here needed, roughly, to prove equation $U(\beta) = 0$ has consistent root $\hat{\beta}$.



• Ignoring higher order terms in a Taylor expansion will give

$$V(\beta)(\hat{\beta}-\beta)\approx U(\beta)$$

where V = -U'.

- ullet In mle case had identities relating expectation of V to variance of U.
- In general here we have

$$Var(U) = \sum x_i^2 Var(Y_i).$$

• If Y_i is Poisson with mean μ_i (and so $Var(Y_i) = \mu_i$) this is

$$Var(U) = \sum x_i^2 \mu_i.$$

Moreover we have

$$V_i = x_i^2 \mu_i$$

and so

$$V(\beta) = \sum x_i^2 \mu_i.$$



• The central limit theorem (the Lyapunov kind) will show that $U(\beta)$ has an approximate normal distribution with variance $\sigma_{II}^2 = \sum x_i^2 \text{Var}(Y_i)$ and so

$$\hat{\beta} - \beta \approx N(0, \sigma_U^2/(\sum x_i^2 \mu_i)^2)$$

• If $Var(Y_i) = \mu_i$, as it is for the Poisson case, the asymptotic variance simplifies to $1/\sum x_i^2 \mu_i$.



Other estimating equations

• If w_i is any set of deterministic weights (possibly depending on μ_i) then could define

$$U(\beta) = \sum w_i (Y_i - \mu_i).$$

- Can still conclude that U=0 probably has a consistent root which has an asymptotic normal distribution.
- Idea widely used:
- Example: Generalized Estimating Equations, Zeger and Liang.
- Abbreviation: GEE.
- Called by econometricians Generalized Method of Moments.

Def'n: An estimating equation is unbiased if

$$E_{\theta}(U(\theta)) = 0$$



Unbiased estimating equations

Suppose $\hat{ heta}$ is a consistent root of the unbiased estimating equation

$$U(\theta) = 0.$$

Let V = -U'. Suppose there is a sequence of constants $B(\theta)$ such that

$$V(\theta)/B(\theta) \rightarrow 1$$

and let

$$A(\theta) = Var_{\theta}(U(\theta))$$
 and $C(\theta) = B(\theta)A^{-1}(\theta)B(\theta)$.

Then

$$\sqrt{C(\theta_0)}(\hat{\theta} - \theta_0) \Rightarrow N(0, 1)$$

$$\sqrt{C(\hat{\theta})}(\hat{\theta} - \theta_0) \Rightarrow N(0, 1)$$

Extras

- Other ways to estimate A, B and C lead to same conclusions.
- There are multivariate extensions using matrix square roots.

