

# STAT 830

## Non-parametric Inference Basics

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# The Empirical Distribution Function – EDF pp 97-99

- Suppose we have sample  $X_1, \dots, X_n$  of iid real valued rvs.
- The empirical distribution function is

$$\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n 1(X_i \leq x)$$

- This is a cdf and is an estimate of  $F$ , the cdf of the  $X$ s.
- People also speak of the empirical distribution:

$$\hat{P}(A) = \frac{1}{n} \sum_{i=1}^n 1(X_i \in A)$$

- This is the probability distribution corresponding to  $\hat{F}_n$ .
- Now we consider the qualities of  $\hat{F}_n$  as an estimate, the standard error of the estimate, the estimated standard error, confidence intervals, simultaneous confidence intervals and so on.



## Bias, variance and mean squared error

- Judge estimates in many ways; focus is distribution of error  $\hat{\theta} - \theta$ .
- Distribution computed when  $\theta$  is *true* value of parameter.
- For our non-parametric iid sampling model we are interested in

$$\hat{F}(x) - F(x)$$

when  $F$  is the true distribution function of the  $X$ s.

- Simplest summary of size of a variable is root mean squared error:

$$RMSE = \sqrt{E_{\theta} [(\hat{\theta} - \theta)^2]}$$

- Subscript  $\theta$  on  $E$  is important – specifies true value of  $\theta$  and matches  $\theta$  in the error!



## MSE decomposition & variance-bias trade-off

- The MSE of any estimate is

$$\begin{aligned}MSE &= E_{\theta} \left[ (\hat{\theta} - \theta)^2 \right] \\&= E_{\theta} \left[ (\hat{\theta} - E_{\theta}(\hat{\theta}) + E_{\theta}(\hat{\theta}) - \theta)^2 \right] \\&= E_{\theta} \left[ (\hat{\theta} - E_{\theta}(\hat{\theta}))^2 \right] + \left\{ E_{\theta}(\hat{\theta}) - \theta \right\}^2\end{aligned}$$

- In making this calculation there was a cross product term which is 0.
- The two terms each have names: the first is the variance of  $\hat{\theta}$  while the second is the square of the bias.
- **Def'n:** The **bias** of an estimator  $\hat{\theta}$  is

$$\text{bias}_{\hat{\theta}}(\theta) = E_{\theta}(\hat{\theta}) - \theta$$

- So our decomposition is

$$MSE = \text{Variance} + (\text{bias})^2.$$

- In practice often find a trade-off. Trying to make the variance small increases the bias.



## Applied to the EDF

- The EDF is an *unbiased* estimate of  $F$ . That is:

$$\begin{aligned} E[\hat{F}_n(x)] &= \frac{1}{n} \sum_{i=1}^n E[1(X_i \leq x)] \\ &= \frac{1}{n} \sum_{i=1}^n F(x) = F(x) \end{aligned}$$

so the bias is 0.

- The mean squared error is then

$$\text{MSE} = \text{Var}(\hat{F}_n(x)) = \frac{1}{n^2} \sum_{i=1}^n \text{Var}[1(X_i \leq x)] = \frac{1}{n} F(x)[1 - F(x)].$$

- This is very much the most common situation: the MSE is proportional to  $1/n$  in large samples.
- So the RMSE is proportional to  $1/\sqrt{n}$ .
- RMSE is measured in same units as  $\hat{\theta}$  so is scientifically right.



## Biased estimates

- Many estimates exactly or approximately averages or ftns of averages.
- So, for example,

$$\bar{X} = \frac{1}{n}X_i \quad \text{and} \quad \bar{X}^2 = \frac{1}{n}X_i^2$$

are unbiased estimates of  $E(X)$  and  $E(X^2)$ .

- We might combine these to get a natural estimate of  $\sigma^2$ :

$$\hat{\sigma}^2 = \bar{X}^2 - \bar{X}^2$$

- This estimate is biased:

$$E[(\bar{X})^2] = \text{Var}(\bar{X}) + [E(\bar{X})]^2 = \sigma^2/n + \mu^2.$$

So the bias of  $\hat{\sigma}^2$  is

$$E[\bar{X}^2] - E[(\bar{X})^2] - \sigma^2 = \mu'_2 - \mu^2 - \sigma^2/n - \sigma^2 = -\sigma^2/n.$$



## Relative sizes of bias and variance

- In this case and many others the bias is proportional to  $1/n$ .
- The variance is proportional to  $1/n$ .
- The squared bias is proportional to  $1/n^2$ .
- So in large samples the variance is more important!
- The biased estimate  $\hat{\sigma}^2$  is traditionally changed to the usual sample variance  $s^2 = n\hat{\sigma}^2/(n-1)$  to remove the bias.
- WARNING: the MSE of  $s^2$  is larger than that of  $\hat{\sigma}^2$ .



# Standard Errors and Interval Estimation

- In any case point estimation is a silly exercise.
- Assessment of likely size of error of estimate is essential.
- A confidence interval is one way to provide that assessment.
- The most common kind is approximate:

estimate  $\pm 2$  estimated **standard error**

- This is an interval of values  $L(X) < \text{parameter} < U(X)$  where  $U$  and  $L$  are random.
- Justification for the two se interval above?
- Notation  $\hat{\phi}$  is the estimate of  $\phi$ .  $\hat{\sigma}_{\hat{\phi}}$  is the estimated standard error.
- Use central limit theorem, delta method, Slutsky's theorem to prove

$$\lim_{n \rightarrow \infty} P_F \left( \frac{\hat{\phi} - \phi}{\hat{\sigma}_{\hat{\phi}}} \leq x \right) = \Phi(x)$$





## Pointwise limits for $F(x)$

- Define, as usual  $z_\alpha$  by  $\Phi(z_\alpha) = 1 - \alpha$  and approximate

$$P_F \left( -z_{\alpha/2} \leq \frac{\hat{\phi} - \phi}{\hat{\sigma}_{\hat{\phi}}} \leq z_{\alpha/2} \right) \approx 1 - \alpha.$$

- Solve inequalities to get usual interval.
- Now we apply this to  $\phi = F(x)$  for one fixed  $x$ .
- Our estimate is  $\hat{\phi} \equiv \hat{F}_n(x)$ .
- The random variable  $n\hat{\phi}$  has a Binomial distribution.
- So  $\text{Var}(\hat{F}_n(x)) = F(x)(1 - F(x))/n$ . The standard error is

$$\sigma_{\hat{\phi}} \equiv \sigma_{\hat{F}_n(x)} \equiv \text{SE} \equiv \frac{\sqrt{F(x)[1 - F(x)]}}{\sqrt{n}}.$$

- According to the central limit theorem

$$\frac{\hat{F}_n(x) - F(x)}{\sigma_{\hat{F}_n(x)}} \xrightarrow{d} N(0, 1)$$

- See homework to turn this into a confidence interval.



## Plug-in estimates

- Now to estimate the standard error.
- It is easier to solve the inequality

$$\left| \frac{\hat{F}_n(x) - F(x)}{\text{SE}} \right| \leq z_{\alpha/2}$$

if the term SE does not contain the unknown quantity  $F(x)$ .

- This is why we use an estimated standard error.
- In our example we will estimate  $\sqrt{F(x)[1 - F(x)]/n}$  by replacing  $F(x)$  by  $\hat{F}_n(x)$ :

$$\hat{\sigma}_{F_n(x)} = \sqrt{\frac{\hat{F}_n(x)[1 - \hat{F}_n(x)]}{n}}.$$

- This is an example of a general strategy: *plug-in*.
- Start with estimator, confidence interval or test whose formula depends on other parameter; plug-in estimate of that other parameter.
- Sometimes the method changes the behaviour of our procedure and sometimes, at least in large samples, it doesn't.



# Pointwise versus Simultaneous Confidence Limits

- In our example Slutsky's theorem shows

$$\frac{\hat{F}_n(x) - F(x)}{\hat{\sigma}_{F_n(x)}} \xrightarrow{d} N(0, 1).$$

- So there was no change in the limit law (alternative jargon for distribution).
- We now have two pointwise 95% confidence intervals:

$$\hat{F}_n(x) \pm z_{0.025} \sqrt{\hat{F}_n(x)[1 - \hat{F}_n(x)]/n}$$

or

$$\left\{ F(x) : \left| \frac{\sqrt{n}(\hat{F}_n(x) - F(x))}{\sqrt{F(x)[1 - F(x)]}} \right| \leq z_{0.025} \right\}$$

- When we use these intervals they depend on  $x$ .
- And we usually look at a plot of the results against  $x$ .
- If we pick out an  $x$  for which the confidence interval is surprising to us we may well be picking one of the  $x$  values for which the confidence interval misses its target.



## Simultaneous intervals

- So we really want

$$P_F(L(X, x) \leq F(x) \leq U(X, x) \text{ for all } x) \geq 1 - \alpha.$$

- In that case the confidence intervals are called *simultaneous*.
- Two possible methods: one exact, but conservative, one approximate, less conservative.
- Dvoretzky-Kiefer-Wolfowitz inequality:

$$P_F(\exists x : |\hat{F}_n(x) - F(x)| > \sqrt{\frac{-\log(\alpha/2)}{2n}}) \leq \alpha$$

- Limit theory:

$$P_F(\exists x : |\sqrt{n}(\hat{F}_n(x) - F(x))| > y) \rightarrow P(\exists x : |B_0(x)| > y)$$

where  $B_0$  is a *Brownian Bridge* (special Gaussian process).



# Statistical Functionals

- Not all parameters are created equal.
- In the Weibull model density

$$f(x; \alpha, \beta) = \frac{1}{\beta} \left(\frac{x}{\beta}\right)^{\alpha-1} \exp\{-(x/\beta)^\alpha\} \mathbf{1}(x > 0).$$

there are two parameters: shape  $\alpha$  and scale  $\beta$ .

- These parameters have no meaning in other densities.
- But every distribution has a median and other quantiles:

$$p^{\text{th}}\text{-quantile} = \inf\{x : F(x) \geq p\}.$$

- If  $r$  is bounded ftn then every distribution has value for parameter

$$\phi \equiv \mathbb{E}_F(r(X)) \equiv \int r(x) dF(x).$$

- Most distributions have a mean, variance and so on.
- A ftn from set of all cdfs to real line is called a *statistical functional*.
- Example:  $\mathbb{E}_F(X^2) - [\mathbb{E}_F(X)]^2$ .



# Statistical functionals

- The statistical functional

$$T(F) = \int r(x)dF(x)$$

is linear.

- The sample variance is not a linear functional.
- Statistical functionals are often estimated using plug-in estimates so

$$T(\hat{F}) = \int r(x)d\hat{F}_n(x) = \frac{1}{n} \sum_1^n r(X_i).$$

- This estimate is unbiased and has variance

$$\sigma_{T(\hat{F})}^2 = n^{-1} \left[ \int r^2(x)dF(x) - \left\{ \int r(x)dF(x) \right\}^2 \right].$$

- This can in turn be estimated using a plug-in estimate:

$$\hat{\sigma}_{T(\hat{F})}^2 = n^{-1} \left[ \int r^2(x)d\hat{F}_n(x) - \left\{ \int r(x)d\hat{F}_n(x) \right\}^2 \right].$$



## Plug-in estimates of functionals; bootstrap standard errors

- When  $r(x) = x$  we have  $T(T) = \mu_F$  (the mean)
- The standard error is  $\sigma/\sqrt{n}$ .
- Plug-in estimate of SE replaces  $\sigma$  with sample SD (with  $n$  not  $n - 1$  as the divisor).
- Now consider a general functional  $T(F)$ .
- The plug-in estimate of this is  $T(\hat{F}_n)$ .
- The plug-in estimate of the standard error of this estimate is

$$\sqrt{\text{Var}_{\hat{F}_n}(T(\hat{F}_n))}.$$

which is hard to read and seems hard to calculate in general.

- The solution is to simulate, particularly to estimate the standard error



# Basic Monte Carlo

- To compute a probability or expected value can simulate.
- **Example:** To compute  $P(|X| > 2)$  use software to generate some number, say  $M$ , of replicates:  $X_1^*, \dots, X_M^*$  all having same distribution as  $X$ .
- Estimate desired probability using sample fraction.
- R code: `x=rnorm(1000000) ; y =rep(0,1000000) ; y[abs(x) >2] =1 ; sum(y)`
- Produced 45348 when I tried it. Gives  $\hat{p} = 0.045348$ .
- Correct answer is 0.04550026.
- Using a million samples gave 2 correct digits, error of 2 in third digit.
- Using  $M = 10000$  is more common. I got  $\hat{p} = 0.0484$ .
- SE of  $\hat{p}$  is  $\sqrt{p(1-p)}/100 = 0.0021$ . So error of up to 4 in second significant digit is likely.





# The bootstrap

- In bootstrapping  $X$  is replaced by the whole data set.
- Generate new data sets ( $X^*$ ) from distribution  $F$  of  $X$ .
- Don't know  $F$  so use  $\hat{F}_n$ .
- **Example:** Interested in distribution of  $t$  pivot:

$$t = \frac{\sqrt{n}(\bar{X} - \mu)}{s}$$

- Have data  $X_1, \dots, X_n$ . Don't know  $\mu$  or cdf of  $X$ s.
- Replace these by quantities computed from  $\hat{F}_n$ .
- Call  $\mu^* = \int x d\hat{F}_n(x) = \bar{X}$ .
- Draw  $X_{1,1}^*, \dots, X_{1,n}^*$  an iid sample from the cdf  $\hat{F}$ .
- Repeat  $M$  times computing  $t$  from  $*$  values each time.



# Bootstrapping the $t$ pivot

- Here is R code:

```
x=runif(5)
mustar = mean(x)
tv=rep(0,M)
tstarv=rep(0,M)
for( i in 1:M){
  xn=runif(5)
  tv[i]=sqrt(5)*mean(xn-0.5)/sqrt(var(xn))
  xstar=sample(x,5,replace=TRUE)
  tstarv[i]=sqrt(5)*mean(xstar-mustar)/sqrt(var(xstar))
}
```



## Bootstrapping a pivot continued

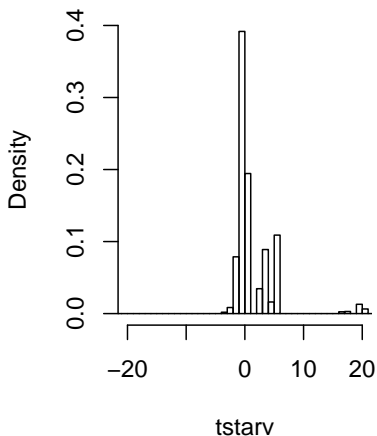
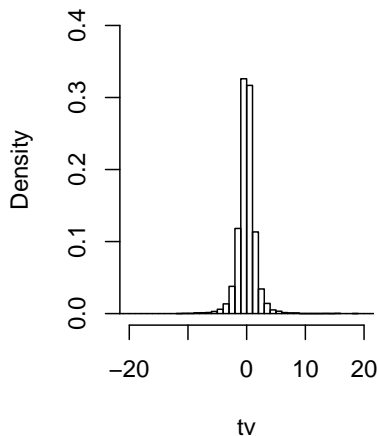
- Loop does two simulations.
- in  $x_n$  and  $t_v$  we do *parametric bootstrapping*: simulate  $t$ -pivot from parametric model.
- $x_{star}$  is bootstrap sample from population  $x$ .
- $t_{starv}$  is  $t$ -pivot computed from  $x_{star}$ .
- Original data set is

(0.7432447, 0.8355277, 0.8502119, 0.3499080, 0.8229354)

- So  $mustar = 0.7203655$
- Side by side histograms of  $t_v$  and  $t_{starv}$  on next slide.



# Bootstrap distribution histograms



## Using the bootstrap distribution

- Confidence intervals: based on  $t$ -statistic:  $T = \sqrt{n}(\bar{X} - \mu)/s$ .
- Use the bootstrap distribution to estimate  $P(|T| > t)$ .
- Adjust  $t$  to make this 0.05. Call result  $c$ .
- Solve  $|T| < c$  to get interval

$$\bar{X} \pm cs/\sqrt{n}.$$

- Get  $c = 22.04$ ,  $\bar{x} = 0.720$ ,  $s = 0.211$ ; interval is -1.36 to 2.802.
- Pretty lousy interval. Is this because it is a bad idea?
- Repeat but simulate  $\bar{X}^* - \mu^*$ .
- Learn

$$P(\bar{X}^* - \mu^* < -0.192) = 0.025 = P(\bar{X}^* - \mu^* > 0.119)$$

- Solve inequalities to get (much better) interval

$$0.720 - 0.119 < \mu < 0.720 + 0.192$$

- Of course the interval missed the true value!



# Monte Carlo Study

- So how well do these methods work?
- Theoretical analysis: let  $C_n$  be resulting interval.
- Assume number of bootstrap reps is so large that we can ignore simulation error.
- Compute

$$\lim_{n \rightarrow \infty} P_F(\mu(F) \in C_n)$$

- Method is *asymptotically valid* (or calibrated or accurate) if this limit is  $1 - \alpha$ .
- Simulation analysis: generate many data sets of size 5 from Uniform.
- Then bootstrap each data set, compute  $C_n$ .
- Count up number of simulated uniform data sets with  $0.5 \in C_n$  to get coverage probability.
- Repeat with (many) other distributions.



## R code

```
tstarint = function(x,M=10000){  
  n = length(x)  
  must=mean(x)  
  se=sqrt(var(x)/n)  
  xn=matrix(sample(x,n*M,replace=T),nrow=M)  
  one = rep(1,n)/n  
  dev= xn%*%one - must  
  tst=dev/sqrt(diag(var(t(xn)))/n)  
  c1=quantile(dev,c(0.025,0.975))  
  c2=quantile(abs(tst),0.95)  
  c(must-c1[2],must-c1[1], must -c2*se,must+c2*se)  
}
```



## R code

```
lims=matrix(0,1000,4)
count=lims
for(i in 1:1000){
x=runif(5)
lims[i,]=tstarint(x)
}
count[,1][lims[,1]<0.5]=1
count[,2][lims[,2]>0.5]=1
count[,3][lims[,3]<0.5]=1
count[,4][lims[,4]>0.5]=1
sum(count[,1]*count[,2])
sum(count[,3]*count[,4])
```





# Results

- 804 out of 1000 intervals based on  $\bar{X} - \mu$  cover the true value of 0.5.
- 972 out of 1000 intervals based on  $t$  statistics cover true value.
- This is the uniform distribution.
- Try another distribution. For exponential I get 909, 948.
- Try another sample size. For uniform  $n = 25$  I got 921, 941.

