

## Metric Spaces

**Definition:** A *metric space* is an ordered pair  $(S, d)$  where  $S$  is a set and  $d$  a function on  $S \times S$  with the properties of a *metric*, namely:

1.  $d(x, y) = d(y, x) \geq 0$ .

2.  $d(x, y) = 0$  iff  $x = y$ .

3. The triangle inequality holds:

$$d(x, z) \leq d(x, y) + d(y, z)$$

for all  $x, y, z$  in  $S$ .

**Definition:** For  $r > 0$  the set

$$B_r(x) = \{y \in S : d(x, y) < r\}$$

is the *open ball* of radius  $r$  centered at  $x$ .

**Definition:** A subset  $O$  of  $S$  is *open* if, for every  $x \in O$  there is a  $r > 0$  such that  $B_r(x) \subset O$ .

Notice that the empty set  $\emptyset$  and  $S$  are open.

**Definition:** A subset  $C$  of  $S$  is *closed* if its complement  $C^c$  is open.

Notice that the empty set  $\emptyset$  and  $S$  are closed.

Fact: an arbitrary union of open sets is open; an arbitrary intersection of closed sets is closed.

**Definition:** The closure in  $S$  of a set  $A$  (denoted  $\overline{A}$ ) is the intersection of all closed subsets of  $S$  containing  $A$ .

**Definition:** A set  $D$  is *dense* in  $S$  if  $\overline{D} = S$ .

**Definition:** A metric space  $S, d$  is *separable* if it has a countable dense subset.

## Limits

**Definition:** We say

$$\lim_{x \rightarrow y} f(x) = a$$

if, for each  $\epsilon > 0$  there exists  $\delta > 0$  such that

$$d_1(x, y) \leq \delta \Rightarrow d_2(f(x), a) \leq \epsilon$$

Closed is equivalent to containing all its *limit points*.

**Definition:** We say  $x$  is a limit point of  $A$  if there is a sequence  $x_n$  of points in  $A$  converging to  $x$ .

## Continuous Functions on Metric Spaces

In the following  $S_1, d_1$  and  $S_2, d_2$  are two metric spaces.

**Definition:** A function  $f : S_1 \mapsto S_2$  is *continuous* if whenever  $O_2$  is open in  $S_2$  the inverse image

$$f^{-1}(O_2) = \{x \in S_1 : f(x) \in O_2\}$$

is open in  $S_1$ .

**Theorem 1** *A map  $f : S_1 \mapsto S_2$  is continuous iff*

$$\lim_{x \rightarrow y} f(x) = f(y)$$

*for all  $y \in S_1$ .*

**Proof of Theorem:** Suppose  $f$  is continuous. Fix  $y$  and  $\epsilon > 0$ . Take  $O_2 = B_{f(y)}(\epsilon)$ . Then  $O_1 = f^{-1}(O_2)$  is an open set containing  $y$ . This means there is a  $\delta > 0$  such that  $d_1(x, y) \leq \delta$  implies  $x \in O_1$  which means  $f(x) \in O_2$ .

Conversely suppose  $f$  satisfies the given condition. Suppose  $O_2$  is open in  $S_2$  and let  $y \in f^{-1}(O_2)$ . Let  $z$  denote  $f(y)$  and note  $z \in O_2$ . As such there exists  $\epsilon > 0$  such that  $d_2(v, z) \leq \epsilon$  implies  $v \in O_2$ . Let  $\delta_y$  be the corresponding  $\delta$  from the condition.

Notice that if  $x \in B_{\delta_y}(y)$  then  $f(x) \in O_2$ . That is  $x \in f^{-1}(O_2)$ . Thus

$$\begin{aligned} f^{-1}(O_2) &= \cup_{y \in f^{-1}(O_2)} \{y\} \\ &\subset \cup_{y \in f^{-1}(O_2)} B_{\delta_y}(y) \\ &\subset f^{-1}(O_2) \end{aligned}$$

Thus  $f^{-1}(O_2) = \cup_{y \in f^{-1}(O_2)} B_{\delta_y}(y)$  is a union of open balls, so open.

## Compactness

**Definition:** A family  $\{O_\alpha; \alpha \in A\}$  of open subsets of  $S$  is an *open cover* of a set  $K$  if

$$K \subset \cup_{\alpha} O_{\alpha}$$

**Definition:** A subset  $K$  of  $S$  is compact if every open cover of  $K$  has a finite sub cover.

Every compact set is closed.

**Example proof:** Suppose  $x \notin K$ . For each  $y$  in  $K$  let  $O_y = B_\epsilon(y)$  with  $\epsilon = d(x, y)/2$ . The family  $O_y, y \in K$  is an open cover of  $K$ . Let  $O_{y_1}, \dots, O_{y_n}$  be a finite subcover. Let

$$\epsilon = \min\{d(x, y_j); 1 \leq j \leq n\}$$

and see that  $B_\epsilon(x)$  has an empty intersection with each  $O_{y_i}$  by the triangle inequality. So  $K \cap B_\epsilon = \emptyset$ . The union of all these  $B_\epsilon$  is the complement of  $K$ .

**Definition:** A subset  $K$  is totally bounded if, for each  $\epsilon > 0$ ,  $K$  is contained in a finite union of balls of radius  $\epsilon$ .

**Theorem 2**  $K$  is compact iff  $K$  is closed and totally bounded.

**Homework Problem:** If  $f$  is a continuous map between  $S_1$  and  $S_2$  then the image  $f(K)$  of a compact set  $K$  in  $S_1$  is compact in  $S_2$ .



**Definition:** A norm, usually written  $\|\cdot\|$  is a function on a vector space such that

1. For all  $x$ ,  $\|x\| \geq 0$
2.  $\|x\| = 0$  iff  $x = 0$ .
3.  $\|ax\| = |a| \|x\|$  for each  $x$  and scalar  $a$ .
4.  $\|x + y\| \leq \|x\| + \|y\|$ .

**Example:** The set  $S = \mathbb{R}^p$  with

$$d(x, y) = \|x - y\|,$$

the usual Euclidean norm, is a separable metric space.

Every closed bounded set in  $\mathbb{R}^p$  is compact.

**Example:** The set  $\mathcal{C}$  consisting of all continuous functions from  $[0, 1]$  to  $\mathbb{R}$  can be made into a metric space by taking

$$d(x, y) = \sup\{|x(t) - y(t)|; t \in [0, 1]\}$$

$\mathcal{C}$  is separable.

Use Weierstrass theorem to show that the set of polynomials is dense in  $\mathcal{C}$ .

Then show that polynomials with rational coefficients are dense in the set of all polynomials.

**Definition:** A sequence  $x_n$  is **Cauchy** in  $S, d$  if: for each  $\epsilon > 0$  there is an  $N$  such that  $n \geq N$  and  $m \geq N$  implies

$$d(x_n, x_m) \leq \epsilon$$

**Definition:** A metric space  $S, d$  is **complete** if every Cauchy sequence in  $S$  has a limit in  $S$ .

**Fact:** Ordinary Euclidean spaces  $\mathbb{R}^p$  are complete.

**Fact:**  $\mathcal{C}([0, 1])$  is complete for the uniform distance.