Experiment 1a: Fundamentals of Temperature Measurement

Objective
To introduce several temperature measurement techniques.

Apparatus
The apparatus is equipped with a variety of temperature measuring devices including: bimetallic thermometer, several electrical temperature sensors, liquid thermometer, and gas thermometers, see Fig. 1. Three temperature sensors are fitted to the unit, these convert the temperature into electrical signals. These signals are indicated on digital displays.

**Pt-100 sensor:** As in principle, a Pt-100 sensor is only a temperature dependent resistor, specific temperatures can be simulated by connecting the input of the display to the built-in resistors.
- 100 Ohm corresponds to 0°C,
- 110 Ohm corresponds to 25.7°C

**NTC thermistors:** In the case of NTC thermistors, a semiconductor is prepared in such a manner that its resistance reduces with increasing temperature. The thermistor supplied has an approximately linear characteristic only in the range from 20 - 55°C. The value that is indicated on the display is also output as an analogue signal (0 - 10V = 0 - 100°C) for recording the change in the measured value over time.

**Thermocouple type K:** At a specific voltage, every thermocouple outputs an associated voltage. This voltage varies with the metals used. The parameters stored in the display are set up for the voltages from type K thermocouples. The relevant temperature is then indicated on the display. At the same time, the voltage signal is amplified and is output as a scaled standardized signal (0-10V = 0-1000°C). The technical exploitation of the thermoelectric effect for temperature measurement began with Seebeck and Peltier. The development and testing of new materials for thermocouples is still not complete. In general, any combination of two conductor materials can be utilized to manufacture a thermocouple.

**Glass thermometer:** In a glass thermometer, the relative expansion of a liquid compared to the contents of the bulb is measured. The majority of the liquid is in a spherical or cylindrical-shaped bulb that forms
the thermometer’s actual sensing element and the bulb opens into the long, thin glass capillary tube. The volume of the medium in liquid thermometers changes with temperature as follows:

\[ V_t = V_0 (1 + \gamma \Delta T) \]  

where \( V_t \) is the volume at temperature \( T \), \( V_0 \) is the volume at 0°C, and \( \gamma \) is the coefficient of thermal expansion.

\[ V_t = V_0 (1 + \gamma \Delta T) \] 

**Bimetallic thermometers** exploit the differential expansion of two different materials to indicate the temperature. Two or more layers of different materials are rolled together, see Fig. 2. During this process, different shapes can be manufactured depending on the application. One end of the sensor is firmly anchored; the other is coupled to a transmission gear or directly to a display device. Variation of the temperature results in expansion of the metallic coil which itself leads to rotation of the free end.

![Figure 1: Details of the experimental setup.](image)
The gas thermometer is one of the most important devices used to realize the thermodynamic temperature scale over a very wide temperature range almost down to absolute zero. Using this method, the change in the pressure or volume of a gas is measured as a function of temperature in accordance with the ideal gas equation:

\[ P V = m R T \]  

(2)

Procedure

In order to compare the accuracy and the required time for getting accurate reading in different two known temperatures should be measured with all different thermometers. Here you have to measure the temperatures of water-ice mixture and boiling water. Therefore, put some ice cubes in the insulated flask and fill it with water. Insert thermometers inside the flask and wait until the steady state condition is reached. Measure the time required for reaching the steady state condition in each case.

Next, fill the small vessel with water and put it on top of the heater. Once the water comes to complete boiling, insert the thermometers and measure the steady state temperature and the required time. Compare the measured temperatures with the values reported in thermodynamic tables and comment on the accuracy and settling time (required time to reach to steady state) of each thermometer.
**Discussions**

1) Explain different types of thermocouples and discuss on the range of applicability.
2) What are the Seebeck and Peltier effects?
3) According to the experiment which thermometer do you recommend? Why?
4) Some thermometer shows deviation from expected data. Why?

<table>
<thead>
<tr>
<th>Table 1: Water-ice and boiling-water temperature data</th>
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<tbody>
<tr>
<td>water-ice mixture</td>
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<tr>
<td>Pt-100 sensor</td>
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<tr>
<td>NTC thermistors</td>
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<tr>
<td>Thermocouple type K</td>
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<tr>
<td>Glass thermometer</td>
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<td>Bimetallic thermometers</td>
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<td>The gas thermometer</td>
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ENSC 388: Engineering Thermodynamics and Heat Transfer

Experiment 1 b: Fundamentals of Pressure Measurement

Objective
To introduce several pressure measurement techniques.

Apparatus
Three different devices shown in Figs. 3, 4, and 5 are used in the experiment: dial manometer, pressure transducer, manometer panel.

The dial manometer shown in Fig. 3 consists of two units:

1. The pressure gauge unit: For experimental purposes, the unit is supplied with a Bourdon spring manometer already screwed in.
2. The load unit: The load unit consists of several weights and a cylinder with a piston. An increase in the load results in an increase in pressure. The load unit is connected to the pressure gauge unit via an oil-filled line, enabling the manometer to display the increase in pressure.

![Figure 3: Details of the apparatus.](image)
The pressure transducer system is similar to the dial manometer device except the measuring part which is a pressure transducer with a digital display, see Fig. 4. The connection between the load unit and pressure measurement unit is shown in Fig. 5.

![Diagram of experimental setup](image)

1. Table-top housing
2. Manual spindle for the compensation cylinder
3. Digital display
4. Cylinder with covering cap
5. Pressure transducer
6. Connection cable
7. Weights holder
8. Compensation cylinder
9. On/off switch

Figure 4: Details of the experimental setup.

A cutaway model of pressure sensor is also available. On the cutaway model the entire arrangement, can be seen.

The manometer panel shown in Fig. 6 includes a U-shaped manometer, a slanted manometer, and two dial manometers. The manometer tubes have quick action connections on the ends that enable one to connect them to each other. The test pressures are generated using a plastic syringe.
1. Load mechanism with piston, weight carrier  
2. Pipe work  
3. Pressure transducer  
4. Compensation cylinder

Figure 5: Plan view of the setup.

Figure 6: Manometer panel device.
**Procedure**

To check the zero point of the dial manometer or pressure transducer, proceed as follows:

- Press the piston out of the cylinder using the hand wheel (Fig 7a).
- Remove the piston and the weight support (Fig 7b).
- Adjust the oil level in the open cylinder until the cylinder is filled up to the edge (Fig 7c).

The tested manometer or pressure transducer should now indicate zero, as it is only subjected to ambient pressure. If the cylinder is not quite filled, despite the fact that the hand wheel has been screwed in completely, the oil should be topped up. For this purpose, unscrew the hand wheel approximately 10 - 15 mm and pour oil into the cylinder until it is totally full.

![Figure 7: Steps for checking zero point of manometer.](a) (b) (c)

Once the zero point of the manometer or pressure transducer has been tested, the weight support is re-inserted into the cylinder of the pressure gauge unit. The piston is then slowly lowered by unscrewing the counterbalance cylinder until it is freely suspended. In order to avoid static friction, set the weight support in gentle rotation. The mass of the support is 385 g. Taking into account the piston diameter of 12 mm, it is now possible to determine the increase in pressure according to the following basic equation:

\[
F = mg, \quad P = \frac{F}{A}
\]  

where \( g \) is the gravitational acceleration. This produces the following results:

\[
F = m \times g \left[ \frac{m^2}{s^2} \right] = 0.385 \times 9.81 = 3.78 \ [N]
\]

\[
A = \frac{\pi d^2}{4} = 113.1 \ mm^2
\]

\[
P = \frac{F}{A} = \frac{3.78}{113.1} = 0.334 \ bar
\]
Other pressure values occurring when the weight on the support is increased can be calculated in exactly the same way. First weigh the four loads and test the apparatus for four different weights and then compare the calculated results with the values shown by the pressure gauge. Using the results determine the accuracy of the setup.

**Discussion**

1. Why should the pressure at the bottom of the piston be the same as the value measured by the pressure gauge?
2. What is the difference between slanted and regular U-shape manometers?
3. Can you discuss on the accuracy of different pressure sensors? Which one do you recommend?
4. Calculate the linear regression and square of the correlation coefficient ($R^2$), using the formula and software (e.g. MS excel) and compare the results. What does $R^2$ mean?

<table>
<thead>
<tr>
<th>Load</th>
<th>Dial Manometer Pressure</th>
<th>Pressure transducer pressure</th>
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<tbody>
<tr>
<td>1. Weight support</td>
<td>(                       )[bar]</td>
<td>(                       )[bar]</td>
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<tr>
<td>2. (                   )[gr]</td>
<td>(                       )[bar]</td>
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<td>3. (                   )[gr]</td>
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<td>4. (                   )[gr]</td>
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