Pretty Theorems on Vertex Transitive Graphs

Growth

For a graph G a vertex x and a nonnegative integer n we let B(x, n) denote the ball of radius n around x (i.e. the set $\{u \in V(G) : dist(u, v) \leq n\}$. If G is a vertex transitive graph then |B(x, n)| = |B(y, n)| for any two vertices x, y and we denote this number by f(n).

Example: If $G = Cayley(\mathbb{Z}^2, \{(0, \pm 1), (\pm 1, 0)\})$ then $f(n) = (n + 1)^2 + n^2$.



Our first result shows a property of the function f which is a relative of log concavity.

Theorem 1 (Gromov) If G is vertex transitive then $f(n)f(5n) \leq f(4n)^2$

Proof: Choose a maximal set Y of vertices in B(u, 3n) which are pairwise distance $\geq 2n + 1$ and set y = |Y|. The balls of radius n around these points are disjoint and are contained in B(u, 4n) which gives us $yf(n) \leq f(4n)$. On the other hand, the balls of radius 2n around the points in Y cover B(u, 3n), so the balls of radius 4n around these points cover B(u, 5n), giving us $yf(4n) \geq f(5n)$. Combining our two inequalities yields the desired bound.

Isoperimetric Properties

Here is a classical problem: Given a small loop of string in the plane, arrange it to maximize the enclosed area. Perhaps not surprisingly, the best you can do is to arrange your string as a circle. So, the real problem amounts to proving that any region in the plane with area greater than that of a circle also has a larger boundary. Such inequalities (relating area to boundary) are called isoperimetric inequalities, and are of great interest in a variety of contexts, in particular for vertex transitive graphs. The diameter of a subset of vertices X, denoted diam(X) is the maximum distance between a pair of points in X. For a set X of vertices we let $\partial(X) = \{v \in V(G) \setminus X : v \text{ is adjacent to a point in } X\}.$

Example: We again consider the Cayley graph on \mathbb{Z}^2 from the previous subsection. If we take X = B(0, n) then $|X| = (n + 1)^2 + n^2$ and $|\partial(X)| = |B(0, n + 1) \setminus B(0, n)| = (n + 2)^2 - n^2 = 2n + 4$, so just as in the plane, the size of the boundary is proportional to n while the size of the set (i.e. area) is proportional to n^2 .

Theorem 2 (Babai Szegedy) If G is vertex transitive and $X \subseteq V(G)$ with diam(X) < diam(G) then

$$\frac{|\partial(X)|}{|X|} \ge \frac{1}{diam(X) + 1}$$

Proof: Let N denote the number of geodesic paths of length d = diam(X) + 1 which pass through an arbitrary vertex of G (since G is vertex transitive this number is the same for any two vertices). Let \mathcal{P} denote the set of geodesic paths of length d which intersect the set X. The key observation for this proof is just that every $P \in \mathcal{P}$ meets the set $\partial(X)$. It follows instantly from this that

$$\mathcal{P}| \le N|\partial(X)|.$$

On the other hand, we have

$$N|X| = \sum_{P \in \mathcal{P}} |V(P) \cap X| \le d|\mathcal{P}|$$

(here there is a small subtlety that every path in \mathcal{P} has d + 1 points, at most d of which are in X). Combining our two inequalities yields the result. \Box

Long Cycles

There are only 4 connected vertex transitive graphs with ≥ 3 vertices known not to have a Hamiltonian cycle: *Petersen's Graph*, *Coxeter's Graph*, and the graphs obtained form these by truncation (blowing up each vertex to a triangle). In particular, this leaves open the following famous question.

Our next theorem shows that vertex transitive graphs must have long cycles (although what we can show is still well short of Hamiltonicity). But first we need a little notation and a couple simple facts. If the group Γ acts transitively on the set X and $x \in X$ we let $\Gamma_x = \{g \in \Gamma : g(x) = x\}$ and we call this the *stabilizer* of x. The orbit stabilizer theorem tells us that $|\Gamma| = |X| \cdot |\Gamma_x|$.

Lemma 4 Let Γ act transitively on the set X and let $S \subseteq X$. If $|S \cap g(S)| \ge c$ for every $g \in \Gamma$ then $|S| \ge \sqrt{c|X|}$.

Proof: Let N be the number of pairs (g, x) so that $g \in \Gamma$, $x \in X$ and $x \in S \cap g(S)$. For every $x \in S$ we have that (x, g) will contribute to N if and only if $g^{-1}(x) \in S$. Since there are exactly $|\Gamma_x|$ ways to map g to a given point, it follows that there are exactly $|S| \cdot |\Gamma_x|$ terms containing x which contribute to N. This gives us

$$|S|^2 \cdot |\Gamma_x| = N$$

On the other hand, by assumption, for every group element g we have that there exist at least c points x so that (x, g) contributes to N. This gives us

$$N \ge c|\Gamma|$$

Combining our inequalities gives us $|S|^2 \cdot |\Gamma_x| \leq c |\Gamma|$ and then dividing through by $|\Gamma_x|$ (and applying the Orbit Stabilizer Theorem yields $|S|^2 \leq c |X|$ as desired. \Box

Theorem 5 (Babai) If G = (V, E) is a connected vertex transitive graph with n = |V| then G has a cycle of length $\geq \sqrt{3n}$

Proof: Every finite connected vertex transitive graph is 2-connected, and must be 3-connected if it is not a cycle (a fact we leave without proof here). Thus, we may assume that G is 3-connected. Now, choose a longest cycle C of G and consider the set $S = V(C) \subseteq V$. It follows from the 3-connectivity of G that $|S \cap g(S)| \ge 3$ for every automorphism g. So, the previous lemma gives us $|S| \ge \sqrt{3n}$ as desired. \Box