

Lecture 23.

- static equilibrium of a rigid body. ch. 12 (12-1 and 12-2, 12-3)

$$\Sigma \vec{F} = 0 \quad (\because \vec{a}_{cm} = 0)$$

$$\Sigma \tau = 0 \quad (\because \alpha = 0)$$

└ It's important to choose the pivot point.
(axis of rotation)

Try to make many torques = 0.

- Solving statics problems: (Need a lot of practice)

- Free-body diagram (for each object). are important
 - Draw the whole object (shape, size, ...)
 - where the forces act.

- Coordinate system.
 - easy to set components.

$$\textcircled{3} \quad \Sigma \vec{F} = 0$$

$$\Sigma \tau = 0 \quad \text{— choose the axis of rotation (pivot point)}$$

so that as many $\tau = 0$ as possible.
↑ unknown

(make use of $\tau = 0$)

- Solve.

e.g. : 12-3, 12-4, 12-5, 12-6. — you read.

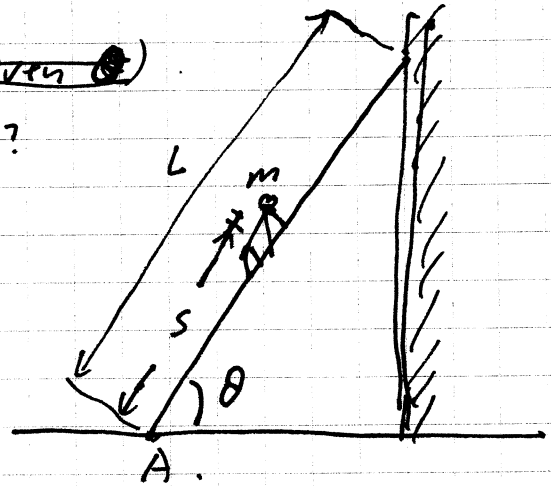
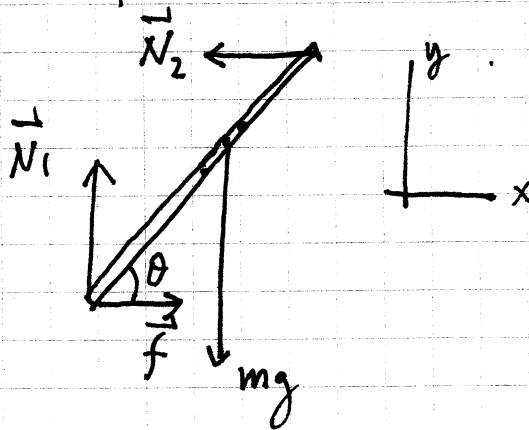
at least one will show
up in written #2.

e.g. A man climbs a massless ladder against a frictionless wall. If the coefficient of friction between the ladder and the floor is μ_s , how far up the ladder can the man climb

before the ladder slips? (~~given~~)

given: θ , L , μ_s . find s ?

①. FBD for the ladder.



$\vec{f}$: when it's about to slip,

$$f = f_{\max} = \mu_s N_1$$

$$\sum \vec{F} = 0 : \quad x\text{-comp:} \quad \mu_s N_1 - N_2 = 0 \quad (1)$$

$$y\text{-comp:} \quad N_1 - mg = 0 \quad (2)$$

$$\sum \tau = 0 : \quad \text{choose axis (pivot point)} : \cdot A.$$

$$N_2 \cdot L \sin \theta - mgs \cos \theta = 0 \quad (3)$$

$$\text{Solve (1), (2), (3) for } s : s = \mu_s \cdot L \cdot \tan \theta.$$

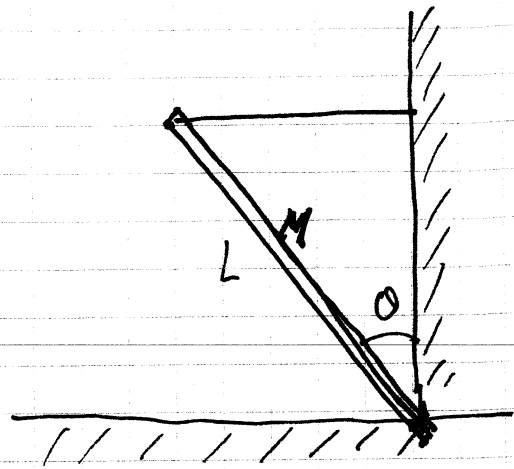
~~Force~~ F.

$$\left(\begin{array}{l} \tau = F \cdot r_{\perp} \\ \tau = F_{\perp} \cdot r \\ \tau = Fr \sin \theta \end{array} \right)$$

— θ is angle between $\vec{F}$ and $\vec{r}$

(because $\vec{f}$ and $\vec{N}_1$ go through A $\tau_f = 0, \tau_{N_1} = 0$)

e.g: A bar of mass M and length L is held against a wall by a horizontal wire. The bottom of the bar is



wedged against the base

of the wall, making an angle θ with respect to the wall.

What is the magnitude of the force exerted on the bar at the corner?

given: M, θ, L .

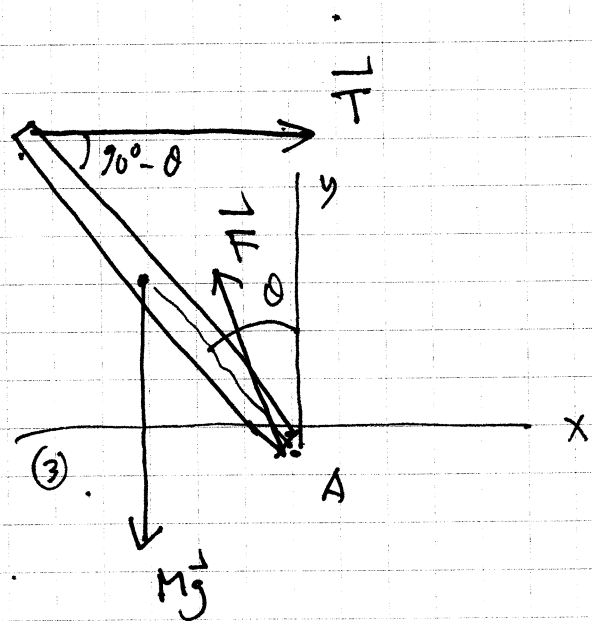
FBD:

$$\sum \vec{F} = 0 \quad T + F_x = 0 \quad (1)$$

$$F_y - Mg = 0 \quad (2)$$

$\sum \tau = 0$ about the corner A

$$Mg \frac{L}{2} \sin \theta - T L \cos \theta = 0 \quad (3)$$



Solve (1), (2), (3) for T, F_x, F_y .

$$(3): \cos \theta T = \frac{Mg}{2} \sin \theta \quad \Rightarrow \quad T = \frac{Mg}{2} \tan \theta$$

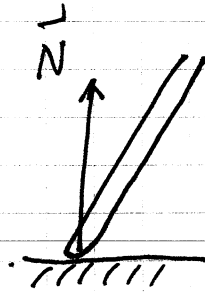
$$F_x = T = \frac{Mg}{2} \tan \theta$$

$$F_y = Mg$$

$$F = \sqrt{F_x^2 + F_y^2} = \sqrt{\left(\frac{Mg}{2} \tan \theta\right)^2 + (Mg)^2} = Mg \sqrt{1 + \left(\frac{\tan \theta}{2}\right)^2}$$

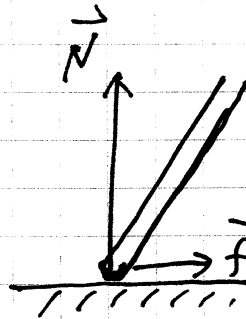
• Different kinds of supports .

1. { Rigid body
can slide .
No friction



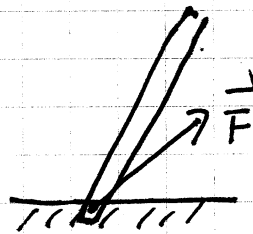
Normal force only .
(simplest)

2. { Rigid body
can slide .
with friction

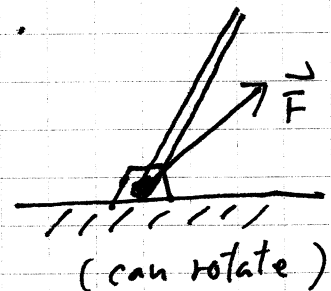


Normal force .
and friction .
(more complicated ,
but : $f \leq \mu N$
(or $f_{\max} = \mu N$)

3. { Rigid body .
can not slide



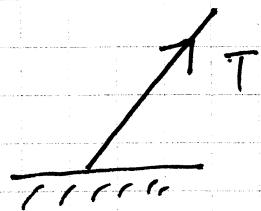
OR:



$\vec{F}$ — with an unknown direction !
(can rotate)

(usually, $\vec{F}$ is NOT along the beam !

4. { Cable (flexible)



Tension $\vec{T}$ is
always along the
cable .

(flexible — NOT transverse force)