CLUSTERED EXEMPLAR-SVM: DISCOVERING SUB-CATEGORIES FOR VISUAL RECOGNITION

Nataliya Shapovalova Greg Mori

School of Computing Science, Simon Fraser University, Canada

ABSTRACT

We present a novel algorithm for image classification that is targeted to capture class variability. A single model is often not sufficient to represent a category since categories can vary from large semantic classes to fine-grained sub-categories. Instead, we develop a representation based on discovering visually similar sub-categories within a given class. We introduce a novel Clustered Exemplar SVM classifier which incorporates data-driven and exemplar focused discovery. Semi-supervised learning is employed for training each C-eSVM classifier. We evaluate our approach on two datasets and demonstrate the efficacy of our method over standard Exemplar SVM.

Index Terms — visual recognition, sub-categories

1. INTRODUCTION

Classification of images is one of the main problems in computer vision. Real-life categories are complex, and often contain large variations. General classifiers are broad and often cannot capture all variabilities in the data. Sub-categorization partially solves this problem. It helps in several cases: to distinguish between different viewpoints (e.g. [1, 2]), and to distinguish fine-grained sub-categories (e.g. [3]). An extreme case of sub-categorization is presented by Malisiewicz et al. [4], where each exemplar forms a sub-category of its own, and a general classifier is replaced by an Ensemble of Exemplar SVMs. However, since they are trained only with one positive example, the resulting eSVMs have difficulty in capturing the details of a class.

Another drawback of general classifiers is a lack of interpretability. Using sub-categories enriches the interpretation of the output. In addition, eSVM allows metadata transfer (e.g., 3D layout, attributes, etc.) from training to test examples. This, however, is more challenging with large sub-categories.

In our work, we extend the eSVM approach and introduce a Clustered Exemplar SVM (C-eSVM) classifier. We believe that each category contains different small groups (a “cluster”) of examples representing either a fine-grained sub-category or a particular viewpoint. These clusters are not as tiny as one exemplar, but also not as all-encompassing as broad category models. The goal is to discover such clusters automatically and learn a separate C-eSVM classifier for each of them. In other words, instead of using just one positive example as in [4], a cluster of positive examples is used for learning each C-eSVM classifier. However, C-eSVM is still exemplar oriented: each cluster originates from one exemplar in the dataset. We design a novel algorithm based on semi-supervised learning to discover such clusters given an initial exemplar. Finally, C-eSVMs are used to form a mid-level representation of images: each image in the dataset is represented by a vector containing the response scores from all C-eSVM classifiers. The new features are used to learn a final classifier for each category in the dataset. During the test we perform not only classification, but also attribute transfer from training examples to a new unseen example.

The paper is organized as follows. In Sec. 2 we review in detail related work. In Sec. 3 we introduce C-eSVMs and demonstrate how we apply semi-supervised techniques to automatically discover clusters. Sec. 4 contains experimental results and analysis. The paper is concluded in Sec. 5.

2. RELATED WORK

Our work contains aspects of sub-categorization, mid-level image representations, and semi-supervised learning. Below, we briefly review each of these areas.

Sub-categorization: The goal is to automatically create a mixture of models that can capture variation of the data. One of the common approaches to this problem is based on Latent SVM [1], where sub-category assignment is modeled by latent variables. Initialization of latent variables is a critical step, and usually clustering with some heuristics is used. Felzenszwalb et al. [1] used bounding box aspect ratio as a criterion for sub-category assignment. Yang and Toderici [3] clustered examples based on co-watch data during learning YouTube category models. Similarly, Gu and Ren [2] used a normalized cut clustering to determine initial viewpoint categories. Another strategy was presented by Hoai and Zisserman [5] where clustering and the learning criteria are combined into one objective function. Finally, as previously mentioned, an extreme case for sub-category learning is exemplar SVM [4], where each sub-category has just one example.

Mid-level features: Mid-level features represent meaningful visual concepts that can describe an object or action.
Farhadi et al. [6] use attributes to represent images and videos. Li et al. [7] introduced an “Object bank”, which consists of thousands of detectors for different object categories. Similarly, an “action bank” citeposelets contains thousands of detectors of primitive actions, and “poselets” [8] is based on detectors for pose parts. As an alternative to supervised learning, mid-level features, unsupervised approaches discover mid-level features automatically [9, 10, 11]. However, these approaches work on a patch-level, resulting in complex procedures for patch selection and pruning.

**Semi-supervised learning:** A comprehensive overview of Semi-Supervised Learning (SSL) from the machine learning perspective is presented in [12] and [13]. The broad goal of SSL is to include unlabeled data into the training process. Here we focus on work that uses SSL for the problem of sub-categoryization and attributes in computer vision.

Gu and Ren [2] combine semi-supervised learning with mixture models for viewpoint categorization. Since only partial labeling of viewpoints is known, self-training is applied to infer all the labels initially. Parikh and Grauman [14] use SSL to discover a set of discriminative and semantically meaningful attributes. Active learning is employed to get the necessary labels for the discovered attributes. Choi et al. [15] select unlabeled examples based on the attributes. Unlabeled images that are likely to have the same attributes as images in the training data are added to the training set. Similarly, Chen and Grauman [16] augments training data by selecting frames from unlabeled videos based on the poses of actions in training images.

3. CLUSTERED EXEMPLAR SVM

Our goal is to learn a classifier for each exemplar in the dataset, such that these classifiers hold two properties: (i) they represent a cluster of examples from one category (in other words, a sub-category) and (ii) be exemplar oriented. Further, these classifiers are used to form a new mid-level representation of images based on their response scores. Given a new representation of training examples, a final binary classifier is learnt for each category. An overview of our approach is presented in Fig. 1.

We build our C-eSVMs by augmenting eSVMs with extra positive examples, which are selected from the dataset in a semi-supervised manner. In the end of this section we demonstrate how to apply C-eSVMs to new images. Due to the lack of space we omit description of the Exemplar SVM, please refer to Malisiewichz et al. [4] instead.

3.1. Collection of Clustered Exemplar SVMs

The intuition behind the Clustered eSVM is the following. We believe that one example is not enough to form a solid representation of a classifier; instead using a cluster of exemplars that are visually similar to each other will help to build a stronger classifier.

**Learning C-eSVMs:** In contrast to eSVM, where a classifier is learnt only from one positive exemplar, we use a cluster of examples for each classifier. In other words, we use each exemplar as a seed to form a cluster of examples from the the same category, and then train a separate classifier per each cluster. This approach mimics sub-category detection while staying focused on the specific example from the training set.

Given a set of training images and their labels \( \{(x_i, y_i)\}_{i=1}^n \) for each exemplar \( x_i \) we form a negative set \( N_i \) by taking all images from categories that are different from \( x_i \), and a cluster \( P_i \) containing examples from the same category as \( x_i \). We learn a SVM classifier for each positive cluster \( P_i \):

\[
\begin{align*}
\min_{w_i, b_i} & \|w_i\|^2 + C^+ \sum_{x_i \in P_i} \xi_i^+ + C^- \sum_{x_i \in N_i} \xi_i^- \\
\text{s.t.} & \quad w_i^T \phi(x_i) + b_i \geq 1 - \xi_i^+, \quad \forall x_i \in P_i, \quad \xi_i^+ \geq 0 \\
& \quad -(w_i^T \phi(x_j) + b_i) \geq 1 - \xi_j^-, \quad \forall x_j \in N_i, \quad \xi_j^- \geq 0
\end{align*}
\]

We call resulting classifier a C-eSVM classifier.

Note that even though we reuse negative data for training classifiers for clusters from the same category \( (N_k = N_l) \text{ iff } y_k = y_l \), the impact of negative data is different since different negative examples can be selected as support vectors.

**Selecting positive clusters:** We pose the problem of cluster discovery as the problem of semi-supervised learning. For each example \( (x_i, y_i) \) we form two sets: \( N_i \) and \( Q_i \). As we previously mentioned, \( N_i \) is a set of negative examples. Meanwhile, \( Q_i \) is a set of so called “semipositive examples”: examples of \( Q_i \) has the same category as \( (x_i, y_i) \), but we do not know which examples from \( Q_i \) belong to the same cluster as \( (x_i, y_i) \). This is a classical problem of SSL: we have a set of labeled examples (original exemplar \( x_i, y_i \)) and negative examples \( N_i \), and a set of unlabeled examples \( Q_i \). The goal is to estimate labels of examples in \( Q_i \). In our approach...
we do not aim to find the best global clustering of all examples in the same category. Instead we solve a local problem: given $x_i$, we want to find a subset in $Q_i$ of the most confident examples that belong to the same cluster as $(x_i, y_i)$.

We solve this problem by using the self-training technique. In a nutshell, the idea of self-training is to build a classifier to estimate labels of unlabeled examples. Note that other approaches from SSL could be used instead.

We use $\tau$ iterations to build a cluster $P_i$; this results in a set of intermediate clusters $\{P_i^0,...,P_i^\tau\}$. Initially, given $P_i^0 = \{\emptyset, x_i \}$ and $N_i$, we first train eSVM. Next, we apply the eSVM classifier to all the examples from $Q_i$. The most confident examples $\{x_1,...,x_M\}$ from $Q_i$ are then removed from $Q_i$. We repeat the procedure: a new C-eSVM classifier is trained for cluster $P_i^t$, semipositive set $Q_i$ is reevaluated based on the scores from a new classifier, and then a new cluster is formed. Self-training is terminated when $t = \tau$ and a final cluster $P_i = P_i^\tau$ is returned.

The algorithm for learning C-eSVMs and inference of cluster are presented in Alg. 1. We argue that a collection of C-eSVMs has two advantages. First, it will result in a model that naturally clusters all the images of one category in subcategories. Second, similar to eSVM, given a new example we are able to correspond it with specific example(s) from the training data.

### 3.2. Classification of Test Examples

We use mid-level features to classify test examples. Given an image, we apply all C-eSVM classifiers to it. The outputs of classifiers are then transformed into a feature vector, which corresponds to a new representation. We use this representation for all images from the training data. Then, we learn a final binary SVM classifier for each category. On the test stage, first we apply C-eSVM classifiers to get a mid-level representation, and then the final classifier is applied to infer the label of a test example.

### 4. EXPERIMENTAL RESULTS

We analyze how a collection of C-eSVMs performs on the task of classification and how unseen examples correspond to examples from the training dataset. We first present the experimental setup, and then discuss results.

#### 4.1. Experimental Setup

**Datasets and parameter selection:** We test our approach on two different datasets: aPascal [6] and aYahoo [6]. We use the same train/test split for the aYahoo as in [17]. Each object in the image is represented with a 9751-dimensional feature vector that contains BoW histograms on color, texture, visual words, and edges [6]. In addition, on all the datasets we use approximated kernels [18] for all our experiments (baseline, C-eSVMs and the final classifier).

We fix $C^- = 1$ and set $C^+ = N_{neg}/N_{pos}$ for learning C-eSVMs, where $N_{pos}$ is number of examples in a cluster and $N_{neg}$ is a number of negative examples. For the final classifier, we use 3-fold cross-validation to choose a $C$ parameter for each category. We vary $\tau$ and $M$ in our experiments.

**Baselines and experiments:** We conduct two baseline experiments to better evaluate our model. First, we learn a general SVM classifier original feature vectors. Second, we learn a collection of eSVMs and use them to produce mid-level representation and then train a final classifier. As for our model, we learn a collection of C-eSVMs with $\tau = 1$ and different values of $M = \{0.2, 1, 2, 5\}$ and show performance of our model for different $M$. A value of $M = 0.2$ indicates that we add 20% of total positive examples to form a cluster. If $M = 5$, we simply add 5 examples at each step. In addition, we also evaluate our model for fixed $M = 5$ and different values of $\tau = \{1, 2, 3\}$.

**Data transfer:** For each discovered cluster in the training data, we infer its attributes. When given a new test example with determined category label, we associate it with the cluster from the training set and transfer attributes.

#### 4.2. Results Discussion

**Classification performance:** Classification results on the aPascal and aYahoo datasets are presented in Table 1. For both datasets we can observe that creating larger clusters is beneficial, in particular adding 20% of positive examples helps improve classification performance for nearly all categories for all datasets. Furthermore, forming small clusters by adding only a few examples, e.g. 2 or 5 leads to a positive shift in performance. To better evaluate our approach, for the
### 5. CONCLUSION

In this work we have introduced a novel collection of C-eSVM classifiers which incorporates automatic cluster discovery in a semi-supervised setting. The key feature of our method is that it is still exemplar oriented and allows direct association between test and train examples. The experimental results on two datasets demonstrate that Clustered Exemplar SVM creates meaningful clusters and has superior performance to the original Exemplar SVM.
6. REFERENCES


