

Lecture 5: Systems of Equations

1. **(SUR)** So, you've got a model with more than one equation: eg, consumer demand is about modelling how *all* expenditure shares vary with prices, expenditure and demographic characteristics.

a. $Y_i^j = X_i^j \mathbf{b}^j + \mathbf{e}_i^j, j = 1, \dots, M, i = 1, \dots, N.$

- i. $i=1, \dots, N$ indexes people, and $j=1, \dots, M$ indexes equations. Note that the X 's can differ across equations, as well as, of course, the parameters \mathbf{b}^j .
- ii. We will assume the normal things about the error terms: mean zero for each equation, homoskedastic for each equation.
- iii. We will allow for cross-equation correlations in the error terms, but no correlations across people i .

$$(1) \quad \begin{aligned} \mathbf{e}_i &= [\mathbf{e}_i^1, \dots, \mathbf{e}_i^M]' \\ E[\mathbf{e}_i] &= \mathbf{0}_M \quad \forall i, \\ E[\mathbf{e}_i \mathbf{e}_i'] &= \Sigma \quad \forall i, \quad E[\mathbf{e}_i \mathbf{e}_j'] = 0 \quad \forall i \neq j \end{aligned}$$

- b. Write out the regression equations as a stack of observations for each equations

$$c. \quad Y = \begin{bmatrix} Y^1 \\ \vdots \\ Y^M \end{bmatrix} = \begin{bmatrix} Y_1^1 \\ \vdots \\ Y_N^1 \\ \vdots \\ Y_1^M \\ \vdots \\ Y_N^M \end{bmatrix}, \quad X = \begin{bmatrix} X^1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & X^M \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} \mathbf{b}^1 \\ \dots \\ \mathbf{b}^M \end{bmatrix}, \quad \mathbf{e} = \begin{bmatrix} \mathbf{e}^1 \\ \vdots \\ \mathbf{e}^M \end{bmatrix} = \begin{bmatrix} \mathbf{e}_1^1 \\ \vdots \\ \mathbf{e}_N^1 \\ \vdots \\ \mathbf{e}_1^M \\ \vdots \\ \mathbf{e}_N^M \end{bmatrix}$$

$$E[\mathbf{e}] = \mathbf{0}_{MN}, \quad E[\mathbf{e} \mathbf{e}'] = \Omega$$

$$\Omega = \Sigma \otimes I_N = \begin{pmatrix} \mathbf{s}_{11} I_N & \cdots & \mathbf{s}_{M1} I_N \\ \vdots & \ddots & \vdots \\ \mathbf{s}_{M1} I_N & \cdots & \mathbf{s}_{MM} I_N \end{pmatrix}, \quad \Sigma = \begin{pmatrix} \mathbf{s}_{11} & \cdots & \mathbf{s}_{M1} \\ \vdots & \ddots & \vdots \\ \mathbf{s}_{M1} & \cdots & \mathbf{s}_{MM} \end{pmatrix}$$

- i. If we knew Σ then, this could be estimated by GLS: premultiply everything by $\Omega^{-1/2}$ and run OLS on the stack. We would have all the small sample properties of OLS if we assumed normality.

- d. In contrast, if we didn't know Σ , then we could find a consistent estimate of it, construct $\hat{\Omega}$, and then premultiply everything by $\hat{\Omega}^{-1/2}$, and run OLS on the stack. This is called feasible GLS (FGLS), and we can use only asymptotics (though we don't need to assume normality).
- e. What is a consistent estimator for Ω ? How about do OLS on the stack, collect the big vector of sample errors $e = [e^1' \dots e^M']'$ (which is a vector of length $MN - N$ errors in each of M equations), and then calculate
- $$\Omega = \{w^{jk}\}, w^{jk} = E[e^j e^k],$$
- $$\hat{\Omega} = \{\hat{w}^{jk}\}, \hat{w}^{jk} = \frac{1}{N} \sum_{i=1}^N e_i^j e_i^k$$
- f. This FGLS strategy is called "seemingly unrelated regression" (SUR) because the only connection across equations is in the disturbance terms—they are otherwise seemingly unrelated.
- g. **Cool thing: If $X^j = X^k \forall j, k$, then FGLS is identical to eq-by-eq OLS.**