

# CMPT 310 Midterm 1, Summer 2019

<b>Last name</b> <i>exactly as it appears on student card</i>									
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<b>SFU Student #</b>									
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This is a **closed book exam**: notes, books, computers, calculators, electronic devices, etc. are **not permitted**. Do not speak to any other students during their exam or look at their work. If you have a question, please remain seated and raise your hand and a proctor will come to you.

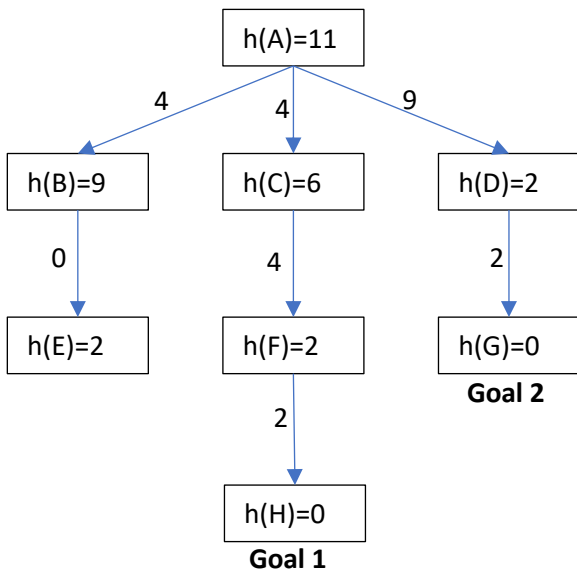
	<b><i>Out of</i></b>	<b><i>Your Mark</i></b>
<i>Agent Architecture</i>	10	
<i>Search</i>	10	
<i>Constraint Satisfaction</i>	10	
<i>Short Answer</i>	10	
<b>Total</b>	40	

## Agent Architecture

a) (5 marks) Give the definition of a **rational agent**.

b) (5 marks) What is a **table-driven agent**, and how does it work? What is one **good** thing about such an agent? What are two different **bad** things about it?

Searching



In the tree on the left, the starting node A is the root. The capital letter in each node is the node's name, and the number is the node's h-value. Altogether, the h-values define a heuristic function h.

Each edge of the tree is labelled with its cost, and the two goal nodes, H and G, are marked.

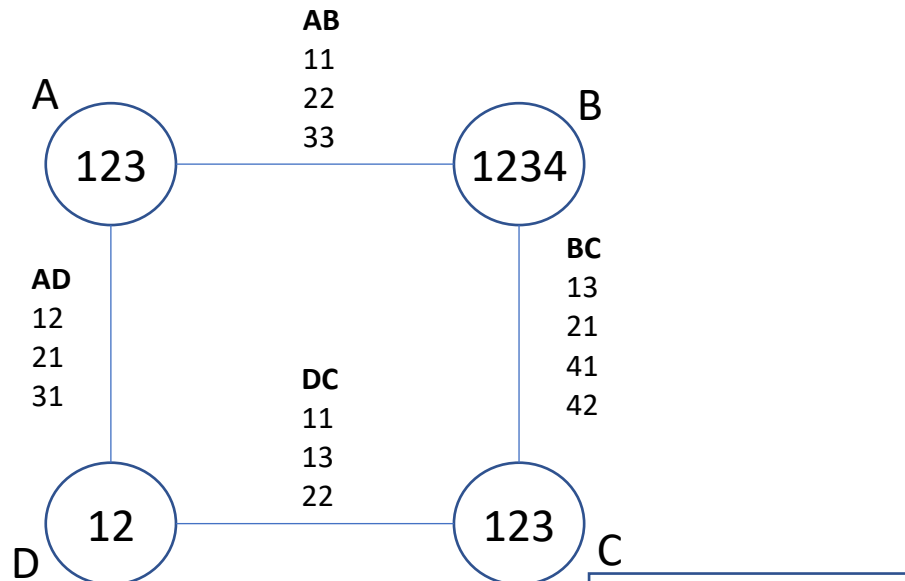
For example, node G has an h-value of 0, and the cost of going from node D to node G is 2.

In the first few questions, a node is **visited** when it is removed from the frontier. **If there is a tie** about what node to visit next, always choose the node that comes first alphabetically.

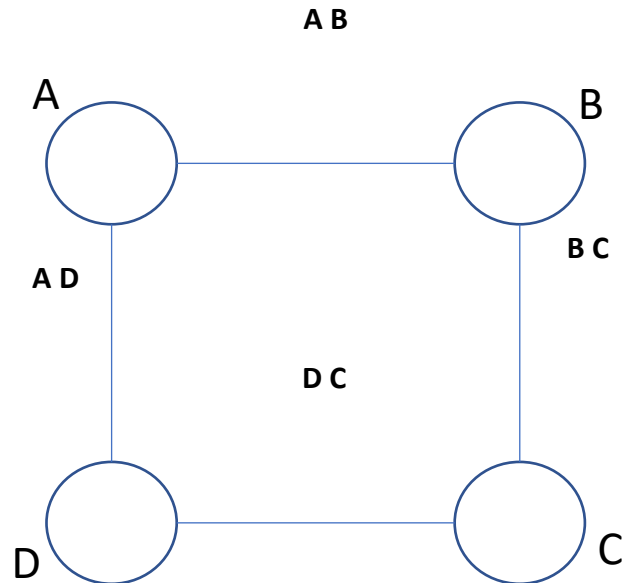
- a) (2 marks) If you start at node A, in what order will the nodes be visited by **uniform-cost search**?
  
- b) (2 marks) If you start at node A, in what order will the nodes be visited by **greedy best-first search**?
  
- c) (2 marks) Is the heuristic function h **admissible**? If not, why not?
  
- d) (2 marks) If you start at node A, in what order will the nodes be visited by **A\* search**?
  
- e) (2 marks) If you start at node A, what nodes (and in what order) will basic **hill-climbing** visit? The value of a node n is  $f(n)=11-h(n)$ , and the higher the value of f the better.

Constraint Satisfaction

(8 marks) Consider the following CSP, where the constraints are all represented as “good lists”:



- a) (1 mark) What is the size of the search space of the above CSP?
- b) (8 marks) Create an **arc consistent** version of the above CSP. Fill in the domains (in the circles) and constraints (under the corresponding letter pairs) here:



c) (1 mark) What is the size of the search space of the arc consistent CSP in b)?

## Short Answer

a) (1 mark) What is the name of the main algorithm that most of the best traditional chess-playing programs used?	
b) (1 mark) What is the name of the search algorithm used by the AlphaZero chess playing program?	
c) (1 mark) <i>True or False</i> : AlphaZero learned to play chess by playing games against itself.	
d) (1 mark) <i>True or False</i> : in practice, the major problem with A*-search when solving is that it runs out of memory.	
e) (1 mark) <i>True or False</i> : A*-search with an <b>inadmissible</b> heuristic on a finite graph sometimes may not find a goal node even though one exists.	
f) (1 mark) <i>True or False</i> : If you run the AC3 algorithm on an arc consistent CSP, then the CSP will not be changed.	
g) (1 mark) <i>True or False</i> : In CSP backtracking search, the <b>minimum remaining values (MRV)</b> heuristic says that you should choose to next assign the node whose domain is the smallest.	
h) (1 mark) <i>True or False</i> : When solving CSPs, <b>forward checking</b> is <b>not</b> useful with backtracking search, but <b>is</b> useful when making a CSP arc consistent.	
i) (1 mark) <i>True or False</i> : The <b>min-conflicts</b> algorithm for solving CSPs is both incomplete and non-optimal.	
j) (1 mark) <i>True or False</i> : An agent can't be truly intelligent unless it is conscious.	