

# Agent Communication

Based on, and inspired by slides from:

Michael Wooldridge, Jeff Rosenshein, Jean-Paul Sansonnet

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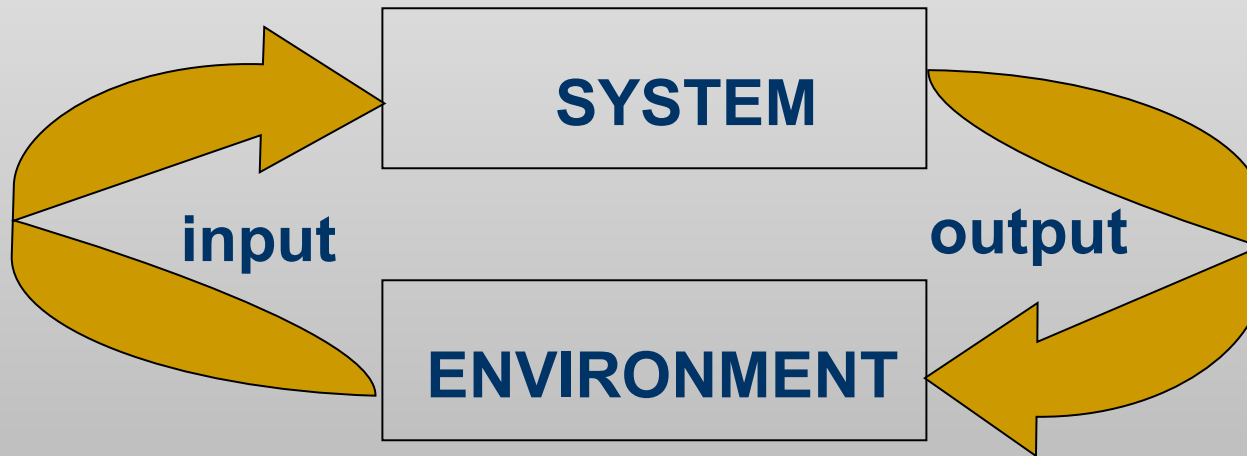
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# Autonomous agents

- An agent is a computer system capable of autonomous action *in some environment* in order to meet its *design objectives*



# BDI agents – basic algorithm

## BDI-interpreter

- (B,D,I):= Initialize-state();
- While true do
  - Update(B,D, I); // perceptions may update beliefs, desires and intentions (ex. Once fulfilled, an intention is dropped)
  - Options:= option-generator(B,D,I);
  - Selected-options:=deliberate(B,D,I);
  - Update-intentions(Selected-options,I);
  - Plan:=Planing(I,B);
  - Execute(Plan);
  - Get-new-perceptions();
- End While

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# Summary

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- An agent is a computer system capable of **flexible autonomous** action in some environment.
- **Situatedness**: peceiving the environment via sensors and being abble to affect the environment via effectors
- **Autonomy**: capability of action without intervention, and control over internal state
- **Flexibility**:
  - Responsiveness: respond in a timely fashion to change in the environment
  - Pro-activity: actions which go beyond simple response to stimulus
  - **Sociability**: ability to interact with other agents and humans for mutual benefit

# Agent Communication

- Designing MAS:
  - Agent design
  - Society design
- In this lecture, we cover *macro-aspects* of intelligent agent technology: issues relating to the agent *society*, rather than the individual
- Address the sociability of the agent

# Outline of the presentation

- **Introduction:**
  - What is cooperation?
  - Cooperative *versus* non-cooperative encounters
- **Early systems:**
  - Methode invocation
  - The blackboard architecture
- ***Agent Communication Languages (ACL):***
  - KQML & KIF;
  - FIPA ACL
- **Protocols and agent conversations:**
  - The contract net protocol
  - Argumentation
  - Negotiation protocols: Bargaining and Interest based negotiation (IBN)

# Working Together

- **Cooperation** is: the practice of working in common with mutually agreed-upon goals and possibly methods, instead of working separately in competition, and in which the success of one is dependent and contingent upon the success of another.
  - E.g. I can't play a quintet alone!
- **When agents are working together, it is important to make a distinction between:**
  - ***Benevolent agents***
  - ***Self-interested agents: it does not mean that they want to cause harm to other agents or that they care only about themselves. It means that it follows its interest as represented by a utility function (representing the agent preferences)***

# Benevolent Agents

- If we “own” the whole system, or are in a cooperative environment, we can design agents that help each other whenever asked (if possible)
- In this case, we can assume agents are *benevolent*: others best interest is their best interest
- Problem-solving in benevolent systems is called *cooperative distributed problem solving* (CDPS)
- *Benevolence simplifies the system design task enormously!*



# Self-Interested Agents

- If agents represent individuals or organizations, (the more general case), then we cannot make the benevolence assumption
- Agents will be assumed to act to further their own interests, possibly at expense of others
- Potential for *conflict*.
- *E.g. Competitive environment (sport, war, ...)*
- May complicate the design task enormously

# Task Sharing and Result Sharing

- Two main modes of cooperative problem solving:
  - **Task sharing**: components of a task are distributed to various agents
  - **Result sharing**: information (partial results, etc.) is distributed
- Both benevolent and self-interested agents have to work together and need to cooperate.
- Cooperation requires **coordination**
- Coordination of multiple independent autonomous agent require **communication** (of some sort).
- *E.g. Lifting a table*
- *E.g. I can't play a quintet with the others if I can't ear them!*

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# Blackboard Systems

- One of the first scheme introduced for cooperative problem solving
- Introduce in a system called HEARSAY-II (1975, Carnegie Mellon) as results sharing system via shared data structure (BB)
- Multiple agents can read and write to BB
- Agents write partial solutions to BB
- BB can be structured into hierarchy
- Problems:
  - Mutual exclusion of access to the BB required  
⇒ bottleneck
  - Not concurrent activity
- Compare: JavaSpaces  
(<http://java.sun.com/developer/technicalArticles/tools/JavaSpaces/>)

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# Introduction to agent communication

- Here, we will focuss on message-based **communication between cognitive agents** (e.g. BDI). We will see next week that other type of communication (low level, signal oriented) are possible
- Like for the agent architecture, a strong anthropomorphism will be noticed.
- We have presented ideas that holds for human communication and are used for artificial agents
- This is usefull since agents and humans are meant to communicate:
  - Human-human communication
  - Human-machine communication
  - Machine-machine communication

# Based on Speech Act Theory

- Most treatments of communication in cognitive (multi)agent systems borrow their inspiration from the *speech act theory*
- Utterances are treated like ‘physical actions’ that aim (goal, intention) to *change the state of the world*
- The speech act theory is a theory of how utterances are used to achieve **intentions**
- Agent communication languages only consider two direction of fit:
  - The direction from the words to the world (assertive)
  - The direction from world to the words (directive)

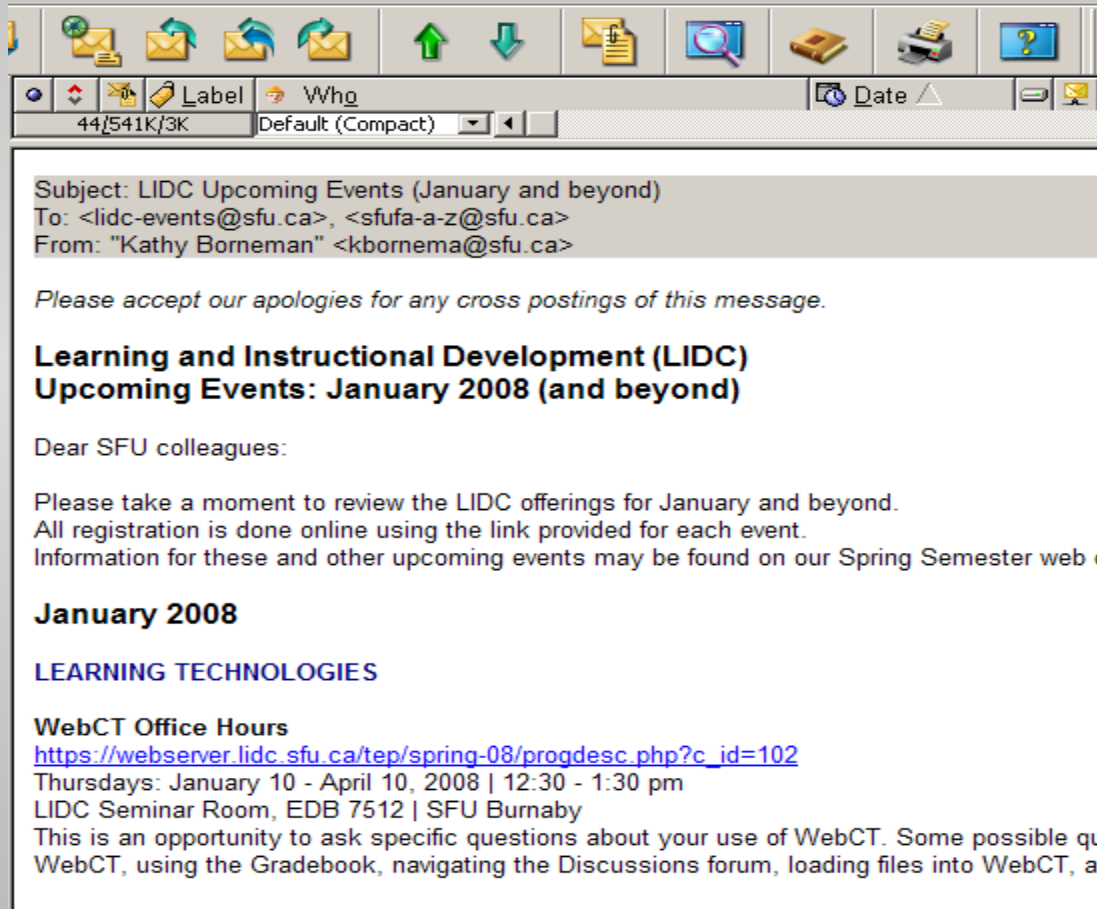


# Speech Acts

- In general, a speech act can be seen to have two components:
  - a **performative verb**: request, inform, inquire, ...
  - **propositional content**: e.g., “the video is played”
- Examples:
  - performative = request  
content = “the door is closed”  
speech act = “please close the door”
  - performative = inform  
content = “the door is closed”  
speech act = “the door is closed!”
  - performative = inquire  
content = “the door is closed”  
speech act = “is the door closed?”

# ACLs: Agent Communication Languages

- The e-mail metaphor



Underlying  
Communication  
Infrastructure

Message

Header

Message Content

# KQML and KIF

- We now consider *agent communication languages* (ACLs) — standard formats for the exchange of messages
- The best known ACL is **KQML**, developed by the ARPA knowledge sharing initiative  
KQML is comprised of two parts:
  - **Message format**: the knowledge query and manipulation language (KQML)
  - **Content**: the knowledge interchange format (KIF)

# KQML and KIF

- KQML is an ‘outer’ language, that defines various acceptable ‘communicative verbs’, or *performatives*  
Example performatives:
  - `ask-if` (‘is it true that. . . ’)
  - `perform` (‘please perform the following action. . . ’)
  - `tell` (‘it is true that. . . ’)
  - `reply` (‘the answer is . . . ’)
- KIF is a language for expressing message *content*

# **KIF – Knowledge Interchange Format**

**Used to state and represent:**

- **Properties of things in a domain (e.g., “Noam is chairman”)**
- **Relationships between things in a domain (e.g., “Amnon is Yael’s boss”)**
- **General properties of a domain (e.g., “All students are registered for at least one course”)**

# KIF – Knowledge Interchange Format

- “The temperature of m1 is 83 Celsius”:  
(= (temperature m1) (scalar 83 Celsius))
- “An object is a bachelor if the object is a man and is not married”:  
(defrelation bachelor (?x) :=  
 (and (man ?x) (not (married ?x))))
- “Any individual with the property of being a person also has the property of being a mammal”:  
(defrelation person (?x) => (mammal ?x))

# KQML and KIF

- In order to be able to communicate, agents must have agreed on a common set of terms
- A formal specification of a set of terms is known as an *ontology*
- The knowledge sharing effort has associated with it a large effort at defining common ontologies — software tools like Ontolingua for this purpose
- Example KQML/KIF dialogue...

```
A to B: (ask-if (> (size chip1) (size chip2)))  
B to A: (reply true)  
B to A: (inform (= (size chip1) 20))  
B to A: (inform (= (size chip2) 18))
```

# Semantics of the Performative

## Plan Based Semantics

- Action: <precond> Body <Postcond>
- Cohen & Perrault (1979) defined semantics of speech acts using the *precondition-delete-add* list formalism of planning research
- Note that a speaker cannot (generally) *force* a hearer to accept some desired mental state
- In other words, there is a separation between the *illocutionary act* and the *perlocutionary act*



# Plan-Based Semantics

- Here is their semantics for *request*:

*request*( $s, h, \phi$ )

pre:

- $s$  believe  $h$  can do  $\phi$   
(you don't ask someone to do something unless you think they can do it)
- $s$  believe  $h$  believe  $h$  can do  $\phi$   
(you don't ask someone unless *they* believe they can do it)
- $s$  believe  $s$  want  $\phi$   
(you don't ask someone unless you want it!)

post:

- $h$  believe  $s$  believe  $s$  want  $\phi$   
(the effect is to make them aware of your desire)

# FIPA-ACL

- More recently, the Foundation for Intelligent Physical Agents (FIPA) started work on a program of agent standards — the centerpiece is an ACL
- Basic structure is quite similar to KQML:
  - *performative*  
20 performatives in FIPA-ACL
  - *housekeeping*  
e.g., sender, content language, etc.
  - *content*  
the actual content of the message

# FIPA

- **Example:**  
(inform  
    : sender           agent1  
    : receiver         agent5  
    : content         (price good200  
150)  
    : language        sl  
    : ontology        hpl-auction  
)

# FIPA

performative	passing info	requesting info	negotiation	performing actions	error handling
accept-proposal			X		
agree				X	
cancel		X		X	
cfp			X		
confirm	X				
disconfirm	X				
failure					X
inform	X				
inform-if	X				
inform-ref	X				
not-understood					X
propose			X		
query-if		X			
query-ref		X			
refuse				X	
reject-proposal			X		
request				X	
request-when				X	
request-whenever				X	
subscribe		X			

# “Inform” and “Request”

- “Inform” and “Request” are the two basic performatives in FIPA. All others are *macro* definitions, defined in terms of these.
- The meaning of inform and request is defined in two parts:
  - pre-condition  
what must be true in order for the speech act to succeed
  - “rational effect”  
what the sender of the message hopes to bring about

# “Inform” and “Request”

- For the “inform” performative...  
The content is a *statement*.  
Pre-condition is that sender:
  - believe that the content is true
  - intends that the recipient believe the content
  - does not already believe that the recipient is aware of whether the content is true or not

# “Inform” and “Request”

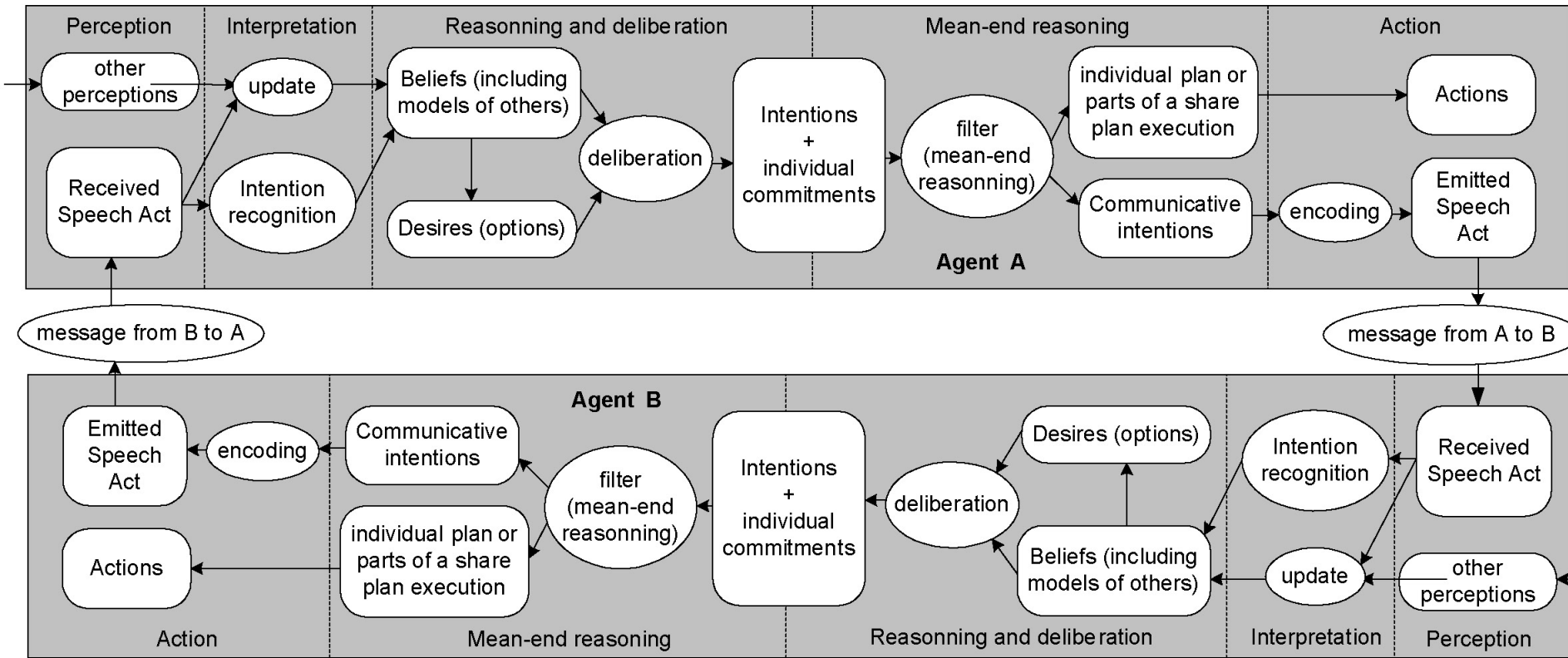
- For the “request” performative...  
The content is an *action*.  
Pre-condition is that sender:
  - intends action content to be performed
  - believes recipient is capable of performing this action
  - does not believe that receiver already intends to perform action

# Using ACLs in Open Systems

- **Open systems** are made of heterogeneous agents (hence the use of keeping the content language flexible and handle the not-understood performative)
- Agents can get in and out at any time:
  - **White pages**: register agents physical address
  - **Yellow pages**: register agents capabilities



# Application: artificial agents, ...



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# Communication Protocols

- **Protocols** are structured ways to encode a type of conversation.
- Often formalised as finite state machines (state, transitions) with an initial and a final state
- Protocols simplify the computation by restricting the agent to a limited set of performative at any given point.
- Protocols also allow a build-in **turn-taking mechanism**
- Protocols capture the **conventional aspects of conversations**

# The Contract Net Protocol

- A well known task-sharing protocol for *task allocation* is the **contract net**:
  1. Recognition
  2. Announcement
  3. Bidding
  4. Awarding
  5. Expediting

# Recognition

- In this stage, an agent recognizes it has a problem it wants help with.
- The agent has a goal, and either:
  - Realizes it cannot achieve the goal in isolation — does not have capability (no plan for it)
  - Realizes it would prefer not to achieve the goal in isolation (typically because of solution quality, deadline, etc.)

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# Announcement

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- In this stage, the agent with the task sends out an *announcement* of the task which includes a *specification* of the task to be achieved
- Specification must encode:
  - description of task itself (maybe executable)
  - any constraints (e.g., deadlines, quality constraints)
  - meta-task information (e.g., “bids must be submitted by...”)
- The announcement is then *broadcasted*

# Bidding

- Agents that receive the announcement decide for themselves whether they wish to *bid* for the task
- Factors:
  - Agent must decide whether it is capable of expediting task
  - Agent must determine quality constraints & price information (if relevant)
- If they do choose to bid, then they submit a *tender* (*completely specified offer*)

# Awarding & Expediting

- The agent that sent task announcement must choose between bids & decide who to “award the contract” to
- The result of this process is communicated to all the agents that submitted a bid
- The successful *contractor* then expedites the task
- May involve *sub-contracting* (eventually using contract net)



# Implementing Contract Net

As simple as it looks, implementing the contract net raises a number of issues:

- How to...
  - ...specify *tasks*?
  - ...specify *quality of service*?
  - ...select between competing offers?
  - ...differentiate between offers based on multiple criteria?

# The Contract Net

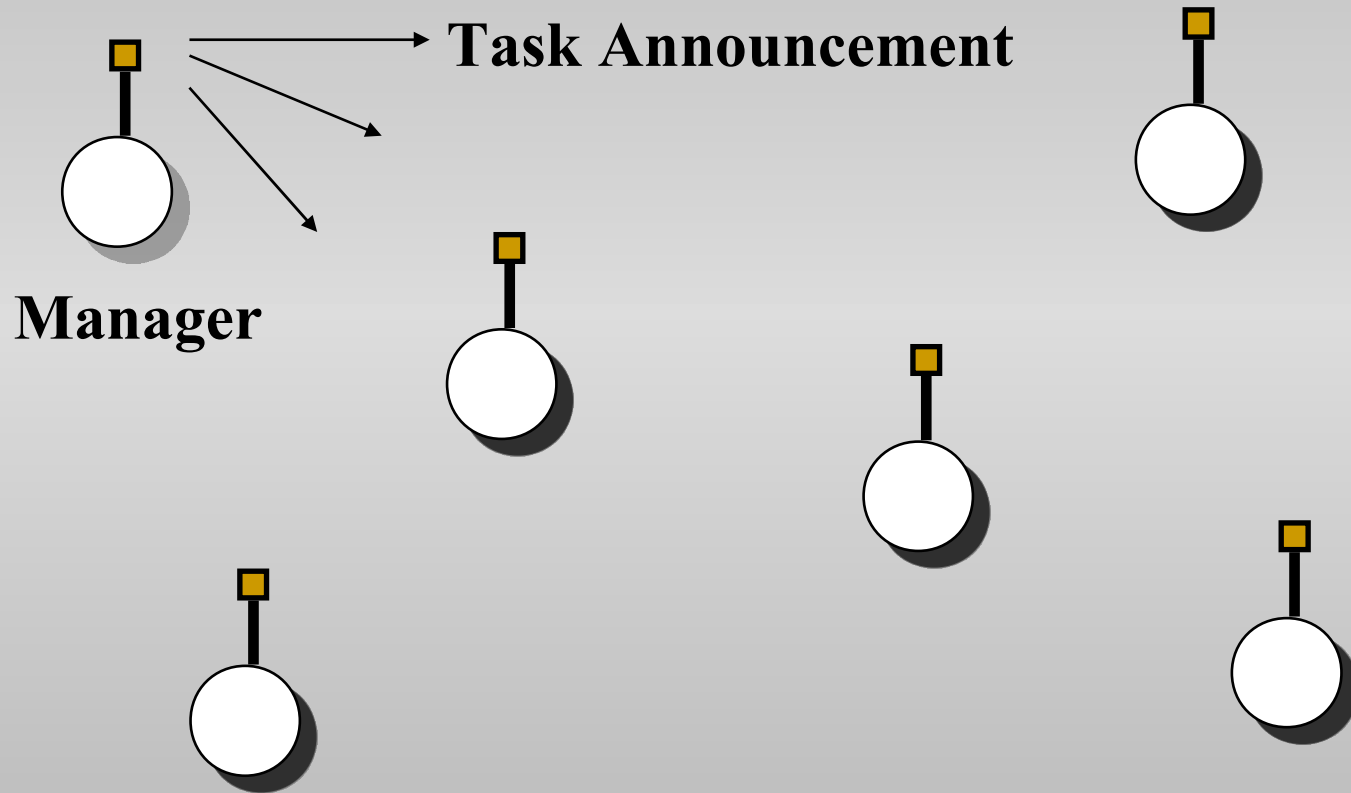
- An approach to *distributed problem solving*, focusing on task distribution
- Task distribution viewed as a kind of **contract negotiation**

Four Phases to Solution in cooperative Problem solving, as Seen in Contract Net:

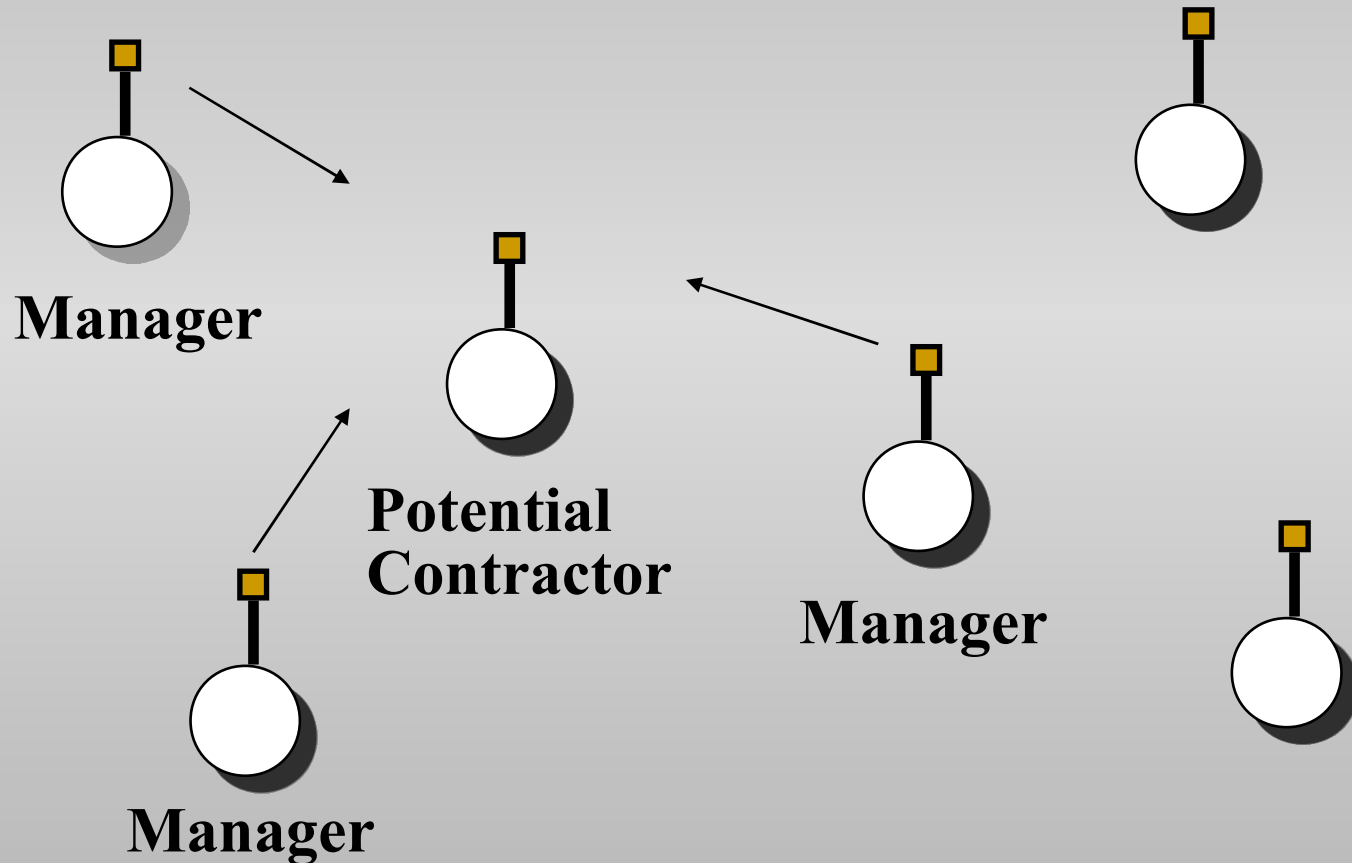
1. Problem Decomposition
2. Sub-problem distribution
3. Sub-problem solution
4. Answer synthesis

The contract net protocol deals with phase 2.

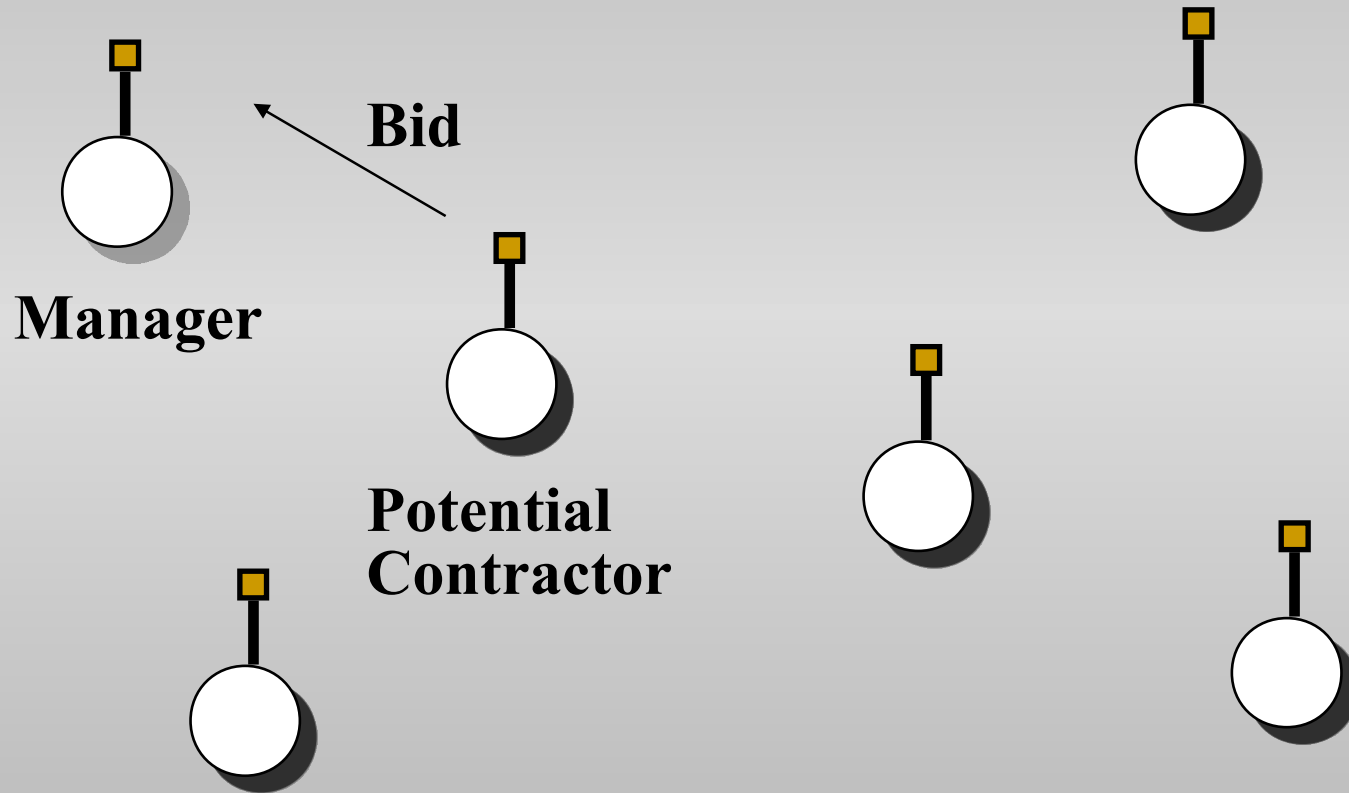
# Manager Issues Task Announcement



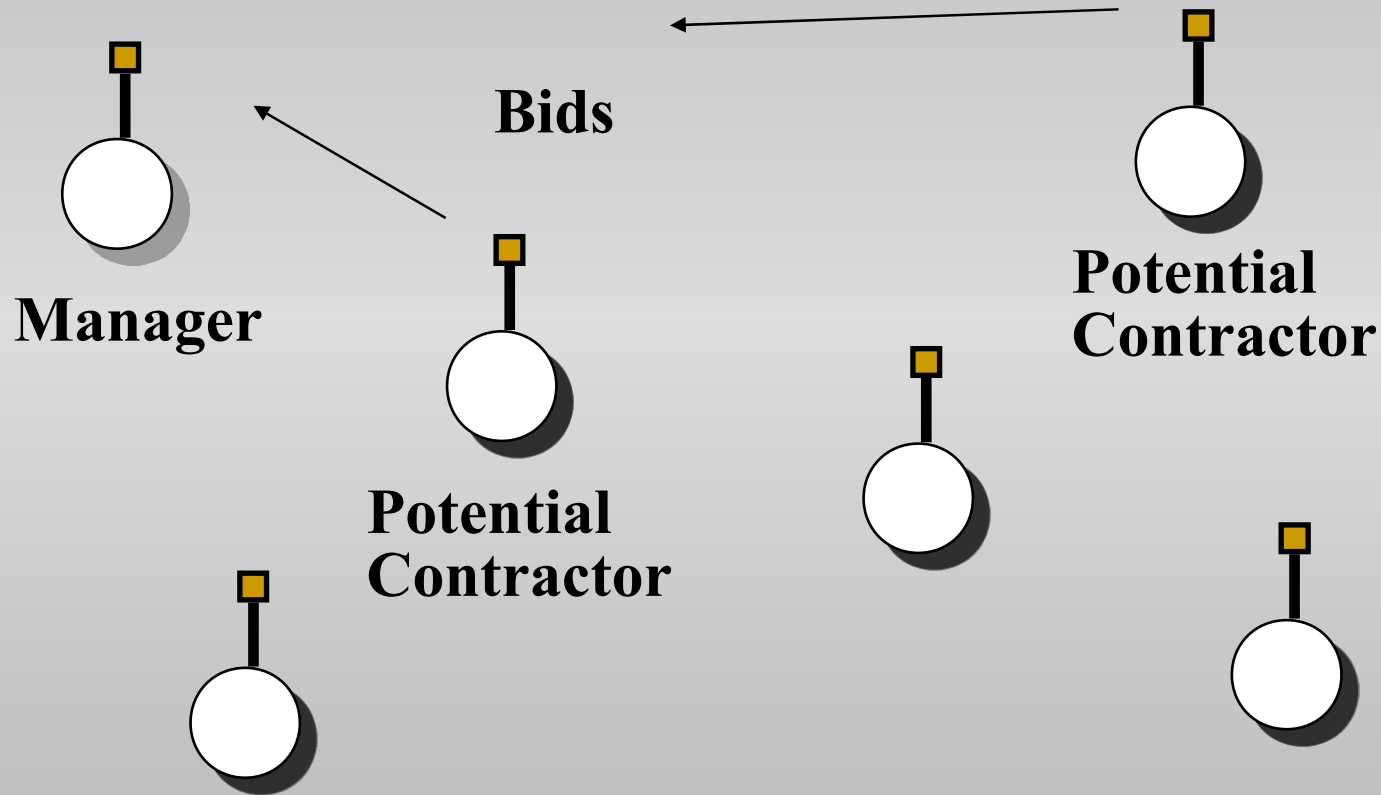
# Idle Agents Listening to Task Announcements



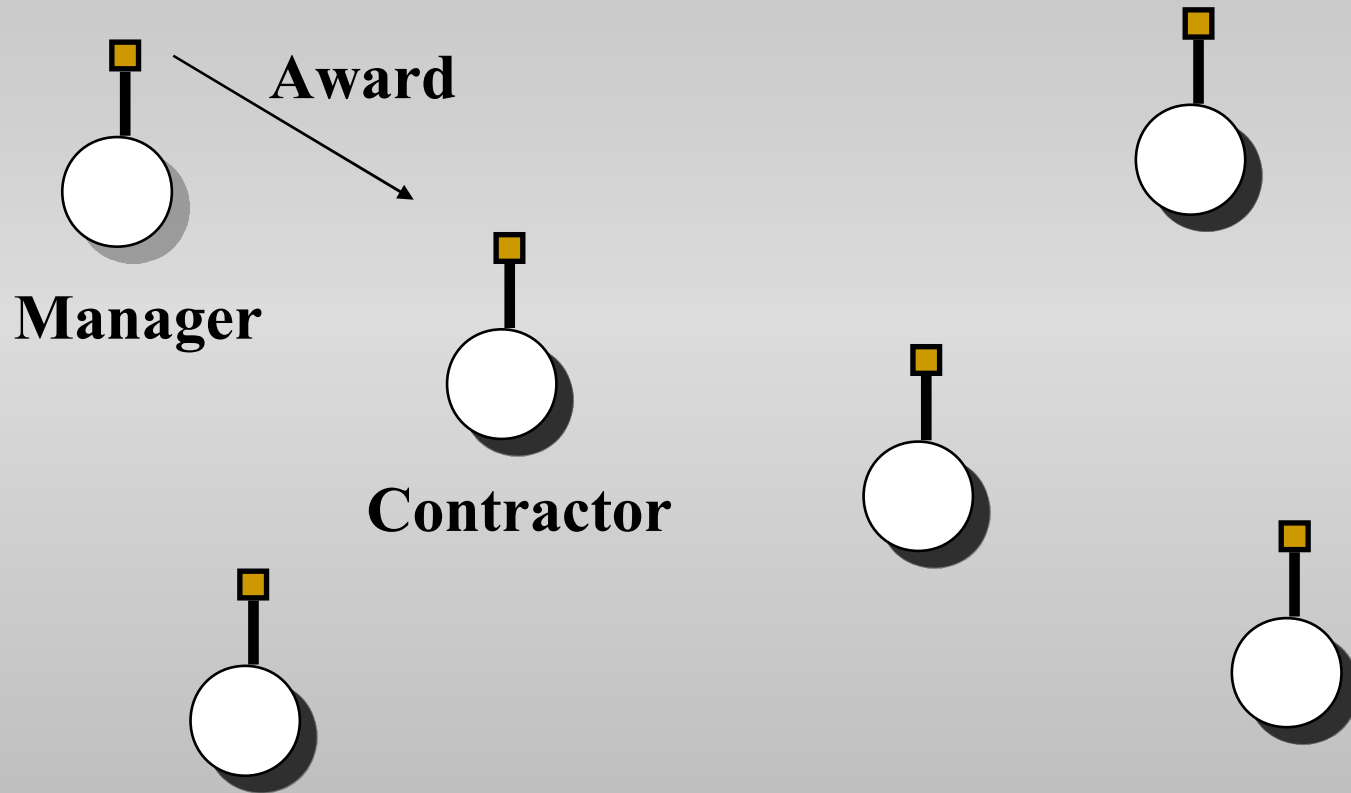
# Contractor Submitting a Bid



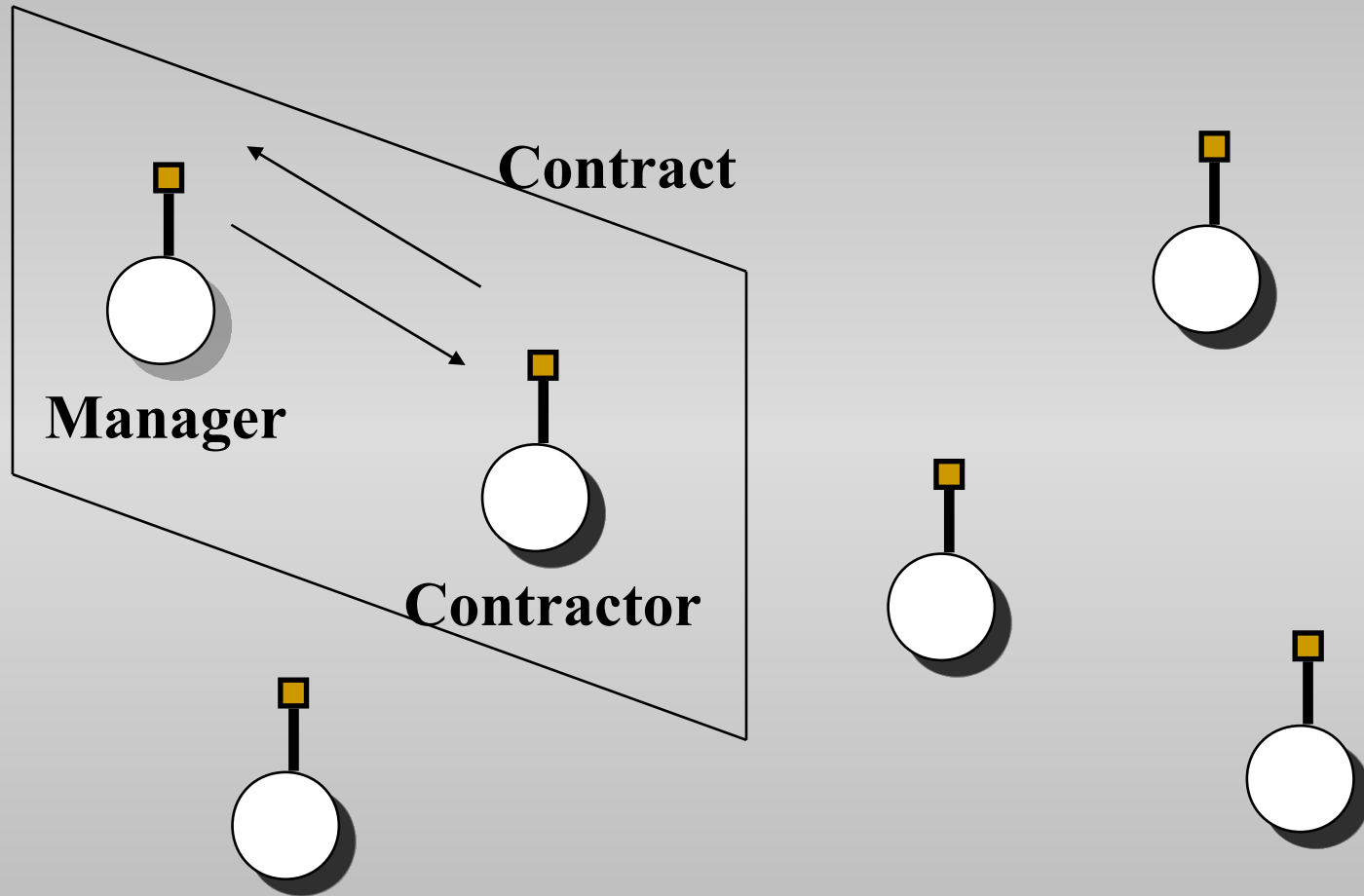
# Manager listening to Bids



# Manager Making an Award



# Contract Established





# Types of Messages

- **Task announcement messages, with the following slots:**
  - Eligibility specification
  - Task abstraction
  - Bid specification
  - Expiration time
- **Bid (following the Bid specification)**
- **Award**
- **Interim report (on progress)**
- **Final report (including result description)**
- **Termination message (if manager wants to terminate contract)**

# Efficiency Modifications

- Depending on the MAS and the problem, many variations are possible:
  - Focused addressing — when general broadcast isn't required
  - Directed contracts — when manager already knows which node is appropriate
  - Request-response mechanism — for simple transfer of information without overhead of contracting

# Other Protocols

- **There is a variety of protocols:**
  - **Negotiation protocols:**
    - **One-to-one negotiation (Monotonic Bargaining, interest-based negotiation),**
    - **Multilateral negotiation (Auctions)**
  - **Argumentation**
- **There is also hybrid approaches:**
  - **Micro-protocols**
  - **Dialogue games**
  - ...

# Argumentation

- Argumentation can be defined as an activity aimed at convincing of the acceptability of a standpoint by putting forward propositions justifying or refuting the standpoint.
  - Numerous works:
    - Dialectic: structure of argumentation (acceptable arguments vs. fallacies)
    - Social psychology: attitude change and persuasion
    - Artificial Intelligence **formalize** those approaches in the aim to:
      - Provide formal theoretical results about particular models
      - Automate agent or multi-agent argumentation capabilities
- } **Syntax, structure and semantics**
- } **Pragmatics**

# Argumentation

- **Argument: Reasons / justifications supporting a conclusion**
- **Represented as: support → conclusion**
  - **Informational arguments: Beliefs → Belief**  
e.g. If it is cloudy, it might rain.
  - **Motivational args: Beliefs, Desires → Desire**  
e.g. If it is cloudy and you want to get out then you don't want to get wet.
  - **Practical arguments: Belief, Sub-Goals → Goal**  
e.g. If it is cloudy and you own a raincoat then put the raincoat.
  - **Social arguments: Social commitments → Goal, Desire e.g.**  
I will stop at the corner because the law say so.  
e.g I can't do that, I promise to my mother that I won't.

# Argumentation

- Interactions (binary or collective) between arguments:
  - Conflict (defeat): e.g. attacks
    - Rebut (symmetrical):
      - support1 → conclusion1
        - » e.g. Tweety is a bird → tweety flies
      - support2 → (not) conclusion1
        - » e.g. Tweety is a small bird → tweety does not fly
    - Undercut (asymmetrical): defeat the assumptions or their link to the conclusion
      - support2 → (not) support1
        - » e.g. no Tweety is not a bird, it is just a cartoon
  - Support-type interactions

# Computational Models of Argumentation

- Given the definition of arguments over a content language (and its logic), the models allow to:
    - Compute interactions between arguments: attacks, defeat, support, ...
    - Valuation of arguments: assign weights to arguments in order to compare them.
      - Intrinsic value of an argument
      - Interaction-based value of an argument
    - Selection of acceptable argument (conclusion)
      - Individual acceptability
      - Collective acceptability
- Computing the status of arguments according to various semantics

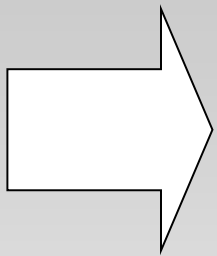
# Applied Models of Argumentation

- Automating the argumentation processes and their effects
- Number of formal characterizations (along with their implementation) has been proposed for:
  - Inference (non monotonic reasoning): OSCAR, IACAS, BDKT, Nathan, DeLP, ABEL, ...
  - Practical reasoning and decision making: PROforma, gIBIS, SIBYL, ZENO, HERMES
  - Argumentation dialogues in MAS: Artikis, Homey, PARMA, ...
  - Argumentation and Machines learning: HYPO, IBP, ...



# Negotiation

The challenge of negotiation:

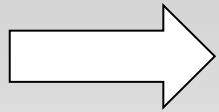


**How to allocate scarce resources among agents representing self-interested parties?**

- ✦ Resources: bandwidth, commodities, money, processing power, ...
- ✦ Scarce: competing claims cannot be simultaneously satisfied

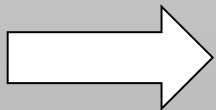
# Models of Negotiation

- Various models of negotiation have been proposed, based on:
  - Heuristic approaches (domain dependent formalization by experts)
  - Game theoretic approaches



Accommodate the agents preferences

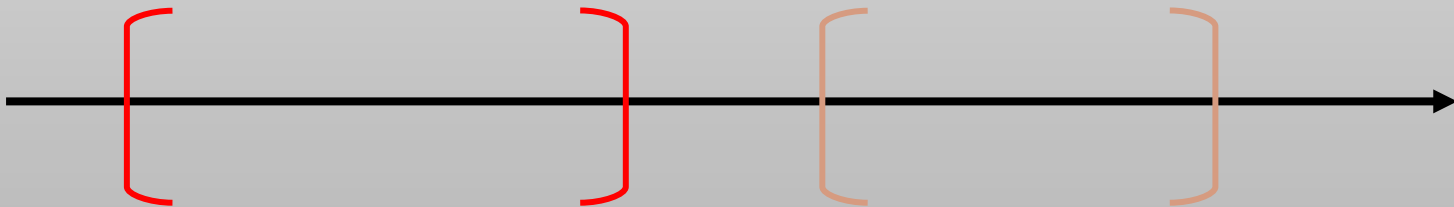
- Argumentation based approaches:
  - Argue about negotiation-related issues (beliefs, goals, social aspects, ...)
  - Interest Based Negotiation: argue about the underlying interests (making underlying goals explicit and discussing them)



Agent preferences may change

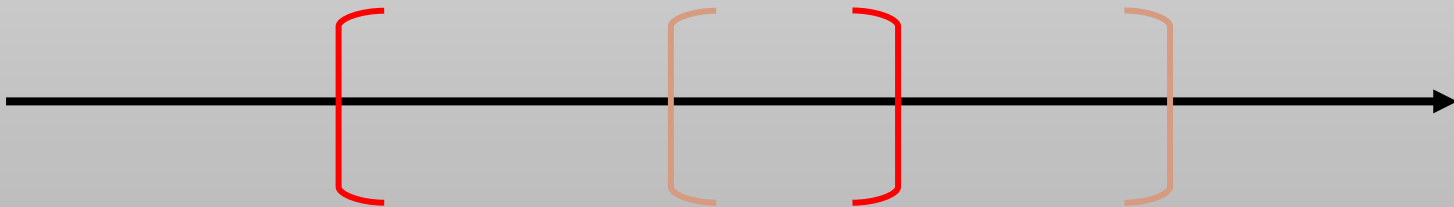
# Example: non-IBN 1

- No deal!
  - B: I would like to rent a car for 4 days please.
  - S: I offer you one for \$400.
  - B: I reject! How about \$200?
  - S: I reject!



## Example: non-IBN 2

- Deal after price concession
  - B: I would like to rent a car for 4 days please.
  - S: I offer you one for \$400.
  - B: I reject! How about \$200?
  - S: I reject! How about \$300 then?
  - B: I guess that's the best I can do! I accept!



# Example: IBN

- Deal after discussion of interests
  - B: I would like to rent a car for 4 days please.
  - S: I offer you one for \$400.
  - B: I reject! How about \$200?
  - S: I reject! Why do you need the car?
  - B: I want to drive to Sydney to attend a conference.
  - S: You can also fly to Sydney! I can book you a ticket with Qantas airlines for \$200.
  - B: I didn't know flights were so cheap! I accept!

# Auctions

- **Single good auctions:**
  - **English auctions:** auctioneer set starting price, agents announce raising bids. Auctions ends after a fixed time or a fixed period without bids.
  - **Japanese auctions:** ascending auction in which the agents decide to stay in or not at each step. The last agent in gets the good.
  - **Dutch auctions:** descending auction. The auction ends when an agents stops the auctioneer
  - **Sealed-bid auctions:** unlike open-outcry auctions, agent submit secret bid to the auctioneer. The agent with the highest bid can purchase the good (for the announced price, first price auction or second price auction – Vickrey auction)



*“Inform all the troops that communications have completely broken down”*

*Ashleigh Brilliant*

# Assignments

- Possible topics for **final project**:
  - Developing a new metacreation
  - Developing a metacreative module in an existing application
  - Conducting experiments for the validation of an existing system
  - Theoretical topic
  - State of the art (including classification and review of existing work and underlying technics used):
    - Cognitive Agents in musical metacreation
    - Reactive Agents in visual metacreation
    - Metacreation in Dance
    - Metacreation in Architecture...



# Assignments: for next Week

- **Readings:**

- Brooks, R. A. "A Robust Layered Control System for a Mobile Robot" , IEEE Journal of Robotics and Automation, Vol. 2, No. 1, March 1986, pp. 14–23;
- OPTIONAL, Brooks, R. A., "Elephants Don't Play Chess" , Robotics and Autonomous Systems (6), 1990, pp. 3–15. (Available from the authors Web Page).
- OPTIONAL, Luc Steels: Fifty Years of AI: From Symbols to Embodiment - and Back. In 50 Years of Artificial Intelligence, Lecture Notes in Computer Science, Volume 4850, 2006: 18-28
- Hutzler, G., Gortais, B. From Computer Art to Ambient Displays. Machine GRAPHICS & VISION (MGV), Volume 13, Number 1/2, page 181--191 - 2004 (available online).

- **Thoughts about the final project:**

- One page about your final project (PDF)
- We will use the ACM format.



*“Before we work on artificial intelligence why don't we do something about natural stupidity?”*

*Steve Polyak*