## Lecture 13 - Rotational kinematics

What's important:

- definitions of angular variables
- angular kinematics

Demonstrations:

- ball on a string, wheel

Text:Walker, Secs. 10.1, 10.2, 10.3
Problems:

We now consider a type of motion in which the Cartesian description is fairly cumbersome. For example, if an object at the end of a string moves in a circular path at constant speed,

Then is has

$$
\begin{aligned}
& s=\text { speed }=\text { constant } \\
& r=\text { radius }=\text { constant } \\
& x, y \text { and } v_{x}, v_{y} \quad \text { vary continuously }
\end{aligned}
$$



Since $s$ and $r$ are constant, independent of the object's position, they do not specify the position or the velocity the object. While $x, y$ and $v_{x}$ and $v_{y}$ do describe the object's motion, they are time-dependent and cumbersome.

We seek a description that makes use of the constancy of $s$ and $r$, yet contains the time dependence in a functionally simple form. We start with uniform circular motion, and work towards general expressions for motion using angular variables.

## Uniform Circular Motion

In two dimensions, the position of an object can be described using the polar coordinates $r$ and $\theta$. If the object is moving in uniform circular motion, then $r$ is constant, and the time dependence of the motion is contained in $\theta$. As a kinematic variable, $\theta$ is the angular analogue of position.


$$
\theta=\frac{\text { arc length }}{\text { radius }} \quad \text { (in radians) }
$$

The sign convention is that $\theta$ increases in a counter-clockwise direction. As a function of time, $\theta$ looks like (for uniform circular motion):


Now, if $\theta$ is the angular analogue of position, then the slope of the $\theta$ vs. $t$ graph is the angular analogue of velocity. We define

## angular speed

or $\quad \omega \equiv \Delta \theta / \Delta t \quad$ as $\Delta t \rightarrow 0$
angular frequency of rotation
(in other words, $\omega$ is the rate of change of $\theta$ with time)


We can go back and forth from $\theta$ to $\omega$ by slopes and areas, just like with $x$ and $v$. For example, from the area under the $\omega$ vs. $t$ curve, we find

$$
\theta=\theta_{0}+\omega t \quad(\text { at constant } \omega)
$$

Two other quantities used to describe uniform circular motion are the period $T$ and the frequency $f$. During the period $T$, the object sweeps through one complete revolution, or $2 \pi$ radians. Hence:

$$
\omega \equiv \Delta \theta / \Delta t=2 \pi / T \quad \text { using } \Delta \theta=2 \pi \text { radians during the period } T
$$

The frequency $f$ is $T^{-1}$, so we also have

$$
\omega=2 \pi f
$$

Note: $\quad \omega=1 \Rightarrow 1$ radian / second

$$
f=1 \Rightarrow 1 \text { revolution } / \text { second }
$$

## Angular and linear links

So far, we have the following equations for linear and angular kinematics

$$
\begin{array}{ll}
\mathbf{x}=\mathbf{x}_{0}+\mathbf{v} t & \theta=\theta_{0}+\omega t \\
\mathbf{v}=\Delta \mathbf{x} / \Delta t & \omega=\Delta \theta / \Delta t \quad \text { as } \Delta t \rightarrow 0
\end{array}
$$

We have a relation between $x$ and $\theta$ already. To obtain a relation between $\mathbf{v}$ and $\omega$, we return to the definition of speed:

$$
\begin{aligned}
& \text { speed }=|\mathbf{v}|=\frac{\Delta \text { distance }}{\Delta \text { time }}=\frac{2 \pi \mathbf{r}}{\mathrm{~T}} \leftarrow \text { circumference } \\
&=\left(\frac{2 \pi}{\mathrm{~T}}\right) \mathbf{r} \\
&=\omega \mathbf{r} \\
& \therefore \quad \mathbf{v}=\omega \mathbf{r} \text { links linear and angular speeds }
\end{aligned}
$$

Another linking relation is through the centripetal acceleration $a_{c}$. From previous work, there is a centripetal acceleration even at constant speed:

$$
\begin{aligned}
\mathbf{a}_{\mathrm{c}} & =\frac{\mathbf{v}^{2}}{\mathbf{r}}=\frac{(\boldsymbol{\omega} \mathbf{r})^{2}}{\mathbf{r}} \\
& \Rightarrow \mathbf{a}_{\mathrm{c}}=\boldsymbol{\omega}^{2} \mathbf{r} \quad\left(\text { or } \mathbf{a}_{\mathrm{c}}=\boldsymbol{\omega} \mathbf{v}\right)
\end{aligned}
$$

## Example

We have a doughnut-shaped space station on which we wish to produce artificial gravity through rotation. What must $\omega$ be so that $a_{c}=g$ at 50 m from the centre of the station?

Using $a_{c}=\omega^{2} r$, we have

$$
\omega^{2}=9.8 / 50
$$

or

$$
\omega=(9.8 / 50)^{1 / 2}=0.44_{3} \mathrm{rad} / \mathrm{s}
$$

(note that the units are OK)


Other quantities which we can calculate in this example are:

$$
T=2 \pi / \omega=2 \cdot 3.142 / 0.443=14.2 \mathrm{~s} .
$$

which is moderately fast and would not encourage the occupants of the space station to look out the windows. The corresponding speed at the perimeter of the station is:

$$
v=\omega r \quad--\gg \quad v=0.44_{3} \cdot 50=22.2 \mathrm{~m} / \mathrm{s}=80 \mathrm{~km} / \mathrm{hr} .
$$

