

Lecture 4 - Centripetal acceleration

What's important:

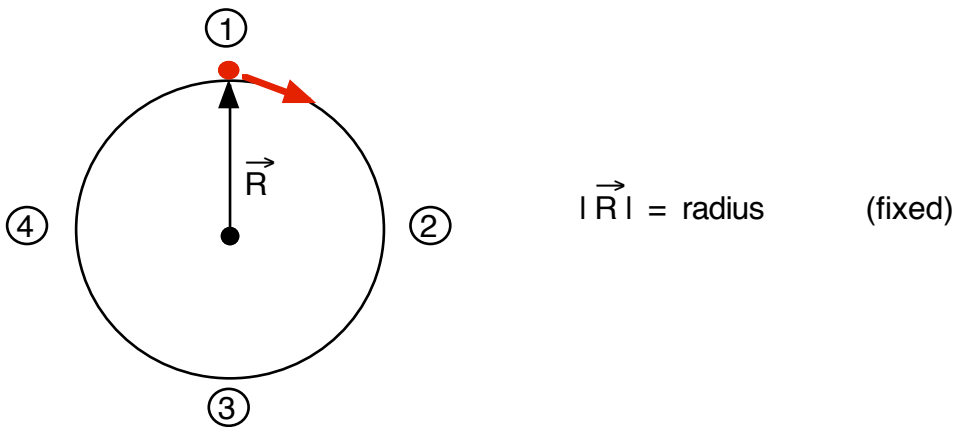
- uniform circular motion
- centripetal acceleration

Demo: Tennis ball on string

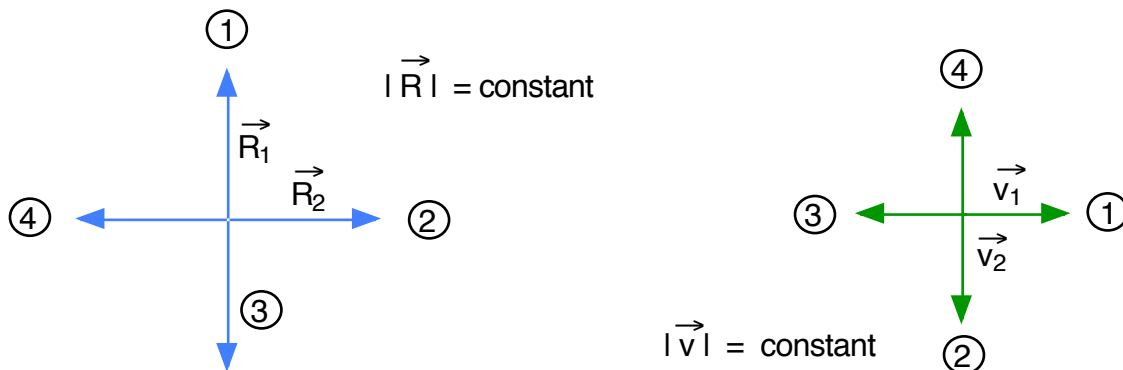
This material does not take a full lecture; combine with adjacent lectures.

Circular Motion

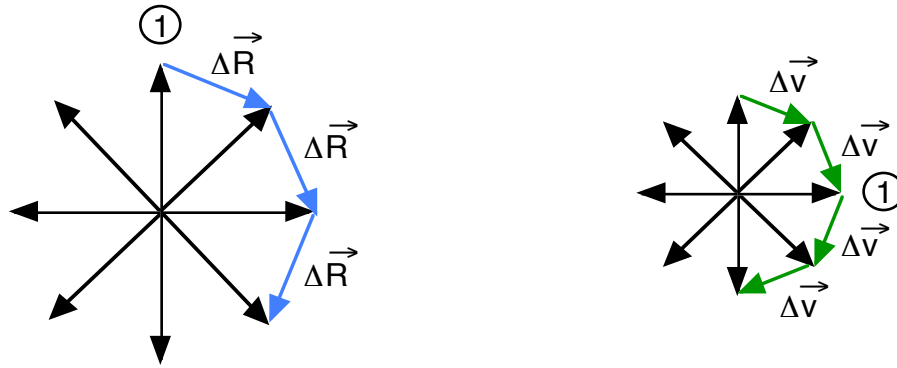
As a simple, but often confusing, application of vectors, we consider circular motion. In the diagram, an object moves in a circular path with radius R , in a clockwise direction (as indicate by the red arrow):



Let's look at the displacement and velocity vectors at four different positions, labelled 1 ... 4 in the diagram.



We can fill in the various intermediate positions to see how the **change in position** and **change in velocity** themselves change in time.



During the period T for one complete revolution,

$$\begin{aligned} \text{Total distance covered} &= \sum |\Delta \mathbf{R}| \\ &= 2\pi R \end{aligned}$$

$$\therefore \text{speed} = |\vec{v}| = \text{distance} / \text{time} = 2\pi R / T$$

$$\begin{aligned} \text{Total change in velocity} &= \sum |\Delta \mathbf{v}| \\ &= 2\pi v \end{aligned}$$

$$\therefore \text{acceleration} = 2\pi v / T$$

$$= 2\pi v \left(\frac{v}{2\pi R} \right) = \frac{v^2}{R}$$

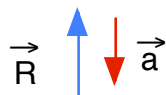
At first sight, this may be a surprising result: the speed is constant, but there is an acceleration $\mathbf{a} = v^2 / R$. Of course, even though the speed is not changing, the velocity does change because it is changing direction.

Demo: use tennis ball on a string to illustrate how v varies inversely with R .

Finally, note that $\Delta \vec{v}$ is in the opposite direction to \vec{R} .



Further, since \vec{a} is parallel to $\Delta \vec{v}$, then \vec{a} must be in the opposite direction to \vec{R} as well:



We call \vec{a} the centripetal (or centre - seeking) acceleration.