PHYS120 Lecture 14 - Kinematics in one dimension

Demonstrations: none *Text*: Fishbane 2-1, 2-2, 2-3, 2-4, 2-5 *Problems*: 15, 26, 27, 45, 48 from Ch. 2

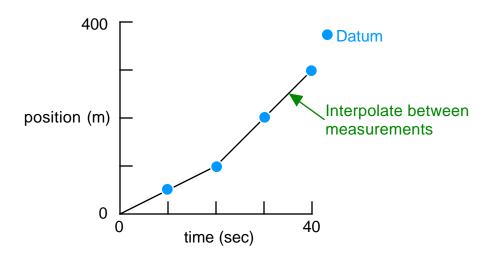
What's important:•relationships between displacement, velocity, acceleration•permutations of two basic equations for motion in one dimension

Position and time

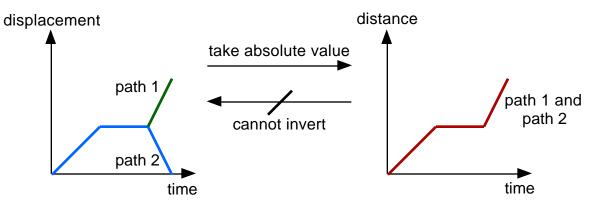
Kinematics deals with movement, the change in position of an object as a function of time. For example, we can use a clock and (very long) meter stick to measure the motion of an object like a car



from which we can construct a position vs. time graph:



From the position, or **displacement**, we can construct the **distance** covered by the moving object. Distance is always positive, and depends upon the path followed in the motion. Although distance can be determined by displacement, the reverse is not true: you **cannot** obtain displacement from distance. Consider two different paths, 1 and 2, on the following position *vs.* time graph:



The paths have the same distance *vs.* time graph, which cannot be uniquely inverted to give the original displacement *vs.* time graph.

Rates of change

Displacement and distance change with time. One can use two crude measures of the rate of change of displacement or distance, namely

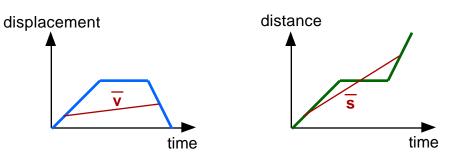
average velocity = $\frac{-}{v} = \frac{x_2 - x_1}{t_2 - t_1}$ (independent of path)

average speed = $\overline{\mathbf{s}}$ = $\frac{\text{change in distance}}{\text{change in time}}$

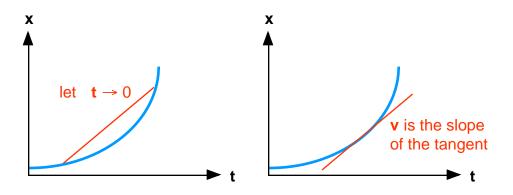
Average speed and average velocity can be obtained from the slope of the line joining the two (position, \mathbf{t}) or (distance, \mathbf{t}) points:

slope =
$$\frac{\mathbf{x}_2 - \mathbf{x}_1}{\mathbf{t}_2 - \mathbf{t}_1} = \frac{\mathbf{x}}{\mathbf{t}}$$

Clearly, the average **v** and **s** can have quite different values:



We can define an instantaneous velocity \mathbf{v} (or instantaneous speed \mathbf{s}) by finding the slope of the tangent to a point on the curve:



Note that \mathbf{v} has a sign (positive or negative), but \mathbf{s} does not: the instantaneous speed is just the absolute value of the instantaneous velocity:

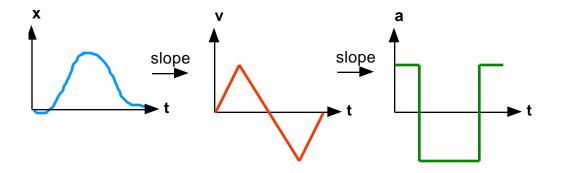
 $\mathbf{s} = |\mathbf{v}|.$

Acceleration

We can go to higher order rates of change by looking at the rate of change of the velocity (since $\mathbf{s} = |\mathbf{v}|$, then we will deal with velocities rather than speeds).

average acceleration = $\overline{\mathbf{a}} = \frac{\mathbf{v}_2 - \mathbf{v}_1}{\mathbf{t}_2 - \mathbf{t}_1}$ (independent of path)

instantaneous acceleration =
$$\frac{\mathbf{v}}{\mathbf{t}}$$
 as \mathbf{t} 0

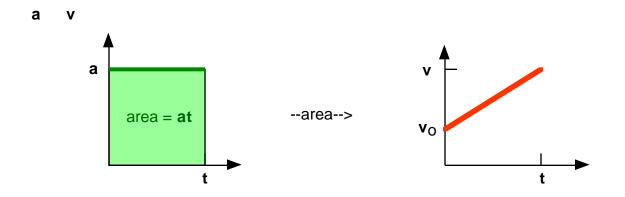


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Constant acceleration

We showed above that one takes the slopes of time-evolution graphs to obtain rates of change:

To obtain **x** from **v**, or **v** from **a** (that is, to proceed in the opposite direction from the rates), one takes areas under the curves of time-evolution graphs. For example, a car travelling at a constant speed of 100 km/hr (**s**) covers a distance of 100 km (**st**) in a time of 1 hour (**t**). The distance is the product of **s** and **t**, and is the area under the **s** *v*s **t** graph. We apply this to constant acceleration.

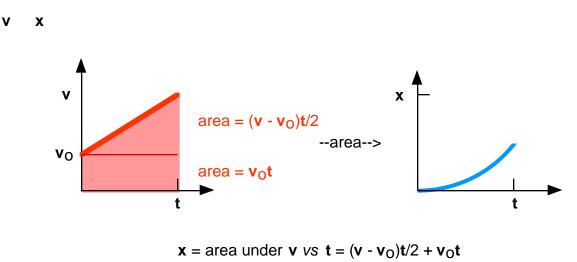


The area under the curve gives the change in **v** (that is, $\mathbf{v} = \mathbf{v} - \mathbf{v}_0$), NOT **v** itself.

From the graph of constant acceleration vs t,

$$\mathbf{v}$$
 = area under $\mathbf{a} v \mathbf{s} \mathbf{t}$ = $\mathbf{a}\mathbf{t}$
 $\mathbf{v} - \mathbf{v}_0 = \mathbf{a}\mathbf{t}$
 $\mathbf{v} = \mathbf{v}_0 + \mathbf{a}\mathbf{t}$ (1)

Equation (1) shows that the v vs t curve should be a straight line with a y-intercept of v_0 .



 $\mathbf{x} - \mathbf{x}_{O} = (\mathbf{v} + \mathbf{v}_{O})\mathbf{t}/2$ $\mathbf{x} = (\mathbf{v} + \mathbf{v}_{O})\mathbf{t}/2 \qquad (\text{if } \mathbf{x}_{O} = 0) \qquad (2)$

Although (2) looks like a linear equation in time (whereas the x vs. t is anything but linear), in fact v contains time dependence. Substituting (1) into (2) to show the explicit time-dependence gives

$$\mathbf{x} = (\mathbf{v}_{O} + \mathbf{at} + \mathbf{v}_{O})\mathbf{t}/2 = (2\mathbf{v}_{O} + \mathbf{at})\mathbf{t}/2$$
$$\mathbf{x} = \mathbf{v}_{O}\mathbf{t} + (1/2)\mathbf{at}^{2}$$
(3)

Equations (1) and (2) can be written in other ways as well. For example, since the plot of **v** *vs.* **t** is linear, then the average velocity \mathbf{v}_{av} is just $(\mathbf{v} + \mathbf{v}_0)/2$. Hence, equation (2) also can be written as

$$\mathbf{x} = \mathbf{v}_{av}\mathbf{t}$$
 (4)

Alternatively, one could invert (1) to find t,

$$t = (v - v_0)/a$$

and substitute the result into (2) to obtain

$$\mathbf{x} = (\mathbf{v}^2 - \mathbf{v}_0^2) / 2\mathbf{a}$$
 (5)