

*Demonstrations:* none

*Text:* Fishbane 1-6, 3-1, 3-2, 3-3

*Problems:* 4, 7, 13, 24, 27 from Ch. 3

*What's important:*

- vectors and their components
- vector addition, products

### Kinematics in Two and Three Dimensions

The kinematics of 1-dimensional motion that we discussed in the previous two lectures can be generalized to more than one dimension through the use of vectors.

Scalar: magnitude only, no direction

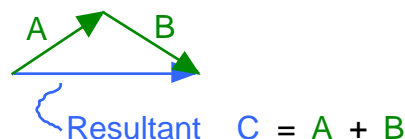
Vector: magnitude and one direction

Tensor: magnitude and more than one direction.

The length of vector  $A$  is denoted by  $|A|$ . In Cartesian component notation, vector  $A$  is represented by  $(A_x, A_y, A_z)$ . Here, we consider addition, multiplication and functional operations on vectors.

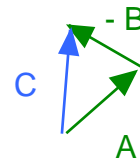
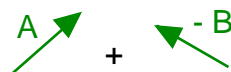
#### Addition and subtraction:

Addition rule: put tip of  $A$  to tail of  $B$ , **resultant** runs from tail of  $A$  to tip of  $B$ .



In components:  $A + B = C = (A_x+B_x, A_y+B_y, A_z+B_z)$ .

$A - B$       Form negative of  $B$ ,  
then add as usual.



In components:  $A - B = C = (A_x-B_x, A_y-B_y, A_z-B_z)$ .

Scalar times vector:

$$a\mathbf{A} = \mathbf{A} + \mathbf{A} + \mathbf{A} \dots \quad \text{"a" times.}$$

In components:  $a\mathbf{A} = (aA_x, aA_y, aA_z)$ .

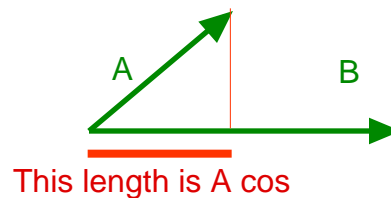
Multiplication:

There are three products that one can form from vectors, two of which (the **dot** and **cross** product) are needed in this course. The **dot product** of two vectors is a scalar quantity, and hence the dot product also is called the **scalar product**. The notation for the dot product, and its operation, are:

$$\mathbf{A} \cdot \mathbf{B} = |\mathbf{A}| |\mathbf{B}| \cos \theta$$

↑  
here's the dot
↑  
this is the angle  
between the vectors

This operation is equivalent to taking the projection of one vector times the length of the other:



Note that the dot product of a vector with itself is just the square of the vector's length

$$\mathbf{A} \cdot \mathbf{A} = |\mathbf{A}| |\mathbf{A}| \cos 0 = A^2$$

In components:

$$\mathbf{A} \cdot \mathbf{B} = A_x B_x + A_y B_y + A_z B_z$$

The other product of vectors needed for this course is the **cross product**. Because the cross product results in a vector, it is also referred to as the **vector product**.

$$\mathbf{C} = \mathbf{A} \times \mathbf{B}$$

↑  
here's the cross

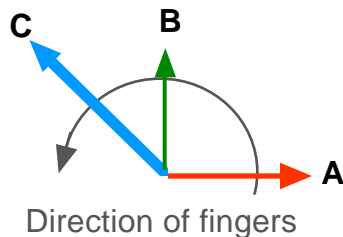
The magnitude of the cross product is

$$|C| = |A| |B| \sin$$

↑ this is the angle  
between the vectors

Finally, the direction of the cross product is given by the right hand rule:

- the new vector is perpendicular to the plane of the vectors **A** and **B** in the product
- the direction of the vector **C** can be found by curling the fingers of your right hand from **A** to **B** (through the smaller angle). Your thumb points in the direction of **C**.



Use fingers of right hand to move from **A** to **B**. Thumb points along **C = A x B**.

In components:

$$\mathbf{A} \times \mathbf{B} = (a_y b_z - a_z b_y, a_z b_x - a_x b_z, a_x b_y - a_y b_x)$$

### Derivatives of vectors

Our kinematic quantities **v** and **a** are vectors, just as is the displacement:

$$\mathbf{v} = \text{velocity vector} \quad \mathbf{a} = \text{acceleration vector}$$

We can write vector equations for **v**, **a** :

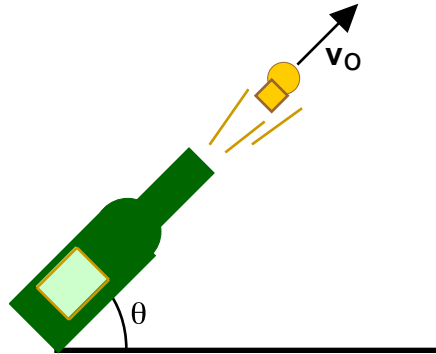
$$\mathbf{v} = \frac{d\mathbf{R}}{dt} \quad \mathbf{a} = \frac{d\mathbf{v}}{dt}$$

What does the derivative  $d./dt$  mean in these equations? In Cartesian coordinates

$$\begin{aligned}\frac{d\mathbf{R}}{dt} &= \left( \frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \right) \\ &= \left( \frac{x}{t}, \frac{y}{t}, \frac{z}{t} \right) \quad \text{as } t \rightarrow 0\end{aligned}$$

## Projectile Motion

An age-old problem in kinematics is the motion of projectiles. Consider a bullet from a gun, or, as shown here, a cork from a bottle of champagne:



The initial velocity is  $\mathbf{v}_0$ . Once the projectile leaves the bottle, it is subject only to forces from gravity and air resistance. We neglect the latter. The initial velocity has components

$$\text{horizontal (x)} \quad \mathbf{v}_{0,x} = \mathbf{v}_0 \cos \theta$$

$$\text{vertical (y)} \quad \mathbf{v}_{0,y} = \mathbf{v}_0 \sin \theta$$

Only the vertical component is subject to change because of the acceleration due to gravity:

$$\mathbf{a}_x = 0 \quad \mathbf{a}_y = -\mathbf{g} \quad (\mathbf{g} = -9.8 \text{ m/s}^2)$$

The kinematic equations become:

$$\mathbf{x} = \mathbf{v}_{0,x} \mathbf{t} = \mathbf{v}_0 \cos \theta \mathbf{t}$$

$$\mathbf{y} = \mathbf{v}_{0,y} \mathbf{t} + \frac{1}{2} \mathbf{a}_y \mathbf{t}^2 = \mathbf{v}_0 \sin \theta \mathbf{t} - \frac{1}{2} \mathbf{g} \mathbf{t}^2.$$