STAT 830 Likelihood Asymptotics

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Purposes of These Notes

- Discuss the behaviour of mles in large samples.
- Show log-likelihood is nearly quadratic.
- Emphasize local rather than global behaviour.
- Give sequence of examples.



Large Sample Theory

- Study approximate behaviour of $\hat{\theta}$ by studying the function U.
- Notice U is sum of independent random variables.

Theorem

If Y_1, Y_2, \ldots are iid with mean μ then

$$\frac{\sum Y_i}{n} \to \mu$$

• Law of large numbers. Strong law

$$P(\lim \frac{\sum Y_i}{n} = \mu) = 1$$

and the weak law that

$$\lim P(|\frac{\sum Y_i}{n} - \mu| > \epsilon) = 0$$

• For iid *Y_i* the stronger conclusion holds; for our heuristics ignore differences between these notions.



Score function at true value of $\boldsymbol{\theta}$

• Now suppose θ_0 is true value of θ .

Then

$$U(\theta)/n
ightarrow \mu(\theta)$$

where

$$\mu(\theta) = E_{\theta_0} \left[\frac{\partial \log f}{\partial \theta} (X_i, \theta) \right]$$
$$= \int \frac{\partial \log f}{\partial \theta} (x, \theta) f(x, \theta_0) dx$$



Normal example

• Example: $N(\mu, 1)$ data:

$$U(\mu)/n = \sum (X_i - \mu)/n = \bar{X} - \mu$$

• If the true mean is μ_0 then $ar{X} o \mu_0$ and

$$U(\mu)/n \rightarrow \mu_0 - \mu$$

- Consider μ < μ₀: derivative of ℓ(μ) is likely to be positive so that ℓ increases as μ increases.
- For μ > μ₀: derivative is probably negative and so ℓ tends to be decreasing for μ > 0.
- Hence: ℓ is likely to be maximized close to μ_0 .



Same ideas in more general case

Study rv

$$\log[f(X_i,\theta)/f(X_i,\theta_0)].$$

• You know the inequality

$$E(X)^2 \leq E(X^2)$$

(difference is $Var(X) \ge 0$.)

• Generalization: Jensen's inequality: for g a convex function ($g'' \ge 0$ roughly) then

$$g(E(X)) \leq E(g(X))$$



- Inequality above has $g(x) = x^2$.
- Use $g(x) = -\log(x)$: convex because $g''(x) = x^{-2} > 0$. We get

 $-\log(E_{\theta_0}[f(X_i,\theta)/f(X_i,\theta_0)] \le E_{\theta_0}[-\log\{f(X_i,\theta)/f(X_i,\theta_0)\}]$

But

$$E_{\theta_0}\left[\frac{f(X_i,\theta)}{f(X_i,\theta_0)}\right] = \int \frac{f(x,\theta)}{f(x,\theta_0)} f(x,\theta_0) dx$$
$$= \int f(x,\theta) dx$$
$$= 1$$

• Reassemble the inequality and this calculation to get

 $E_{\theta_0}[\log\{f(X_i, \theta)/f(X_i, \theta_0)\}] \leq 0$



- Fact: inequality is strict unless the θ and θ_0 densities are actually the same.
- Let $\mu(\theta) < 0$ be this expected value.
- Then for each θ we find

$$\frac{\ell(\theta) - \ell(\theta_0)}{n} = \frac{\sum \log[f(X_i, \theta) / f(X_i, \theta_0)]}{n} \to \mu(\theta)$$

- This proves likelihood probably higher at θ_0 than at any other single θ .
- Idea can often be stretched to prove that the mle is consistent; need uniform convergence in θ.



- Definition A sequence θ̂_n of estimators of θ is consistent if θ̂_n converges weakly (or strongly) to θ.
- **Proto theorem**: In regular problems the mle $\hat{\theta}$ is consistent.
- More precise statements of possible conclusions.
- Use notation

$$N(\epsilon) = \{\theta : |\theta - \theta_0| \le \epsilon\}.$$

- Suppose: $\hat{\theta}_n$ is global maximizer of ℓ .
- $\hat{\theta}_{n,\delta}$ maximizes ℓ over $N(\delta) = \{ |\theta \theta_0| \le \delta \}.$

$$\begin{aligned} A_{\epsilon} &= \{ |\hat{\theta}_n - \theta_0| \leq \epsilon \} \\ B_{\delta,\epsilon} &= \{ |\hat{\theta}_{n,\delta} - \theta_0| \leq \epsilon \} \\ C_L &= \{ \exists ! \theta \in N(L/n^{1/2}) : U(\theta) = 0, U'(\theta) < 0 \} \end{aligned}$$



Some precision

Theorem

- **1** Under (unspecified) conditions $P(A_{\epsilon}) \rightarrow 1$ for each $\epsilon > 0$.
- **2** Under conditions **II** there is a $\delta > 0$ such that for all $\epsilon > 0$ we have $P(B_{\delta,\epsilon}) \rightarrow 1$.
- 3 Under conditions III for all $\delta > 0$ there is an L so large and an n_0 so large that for all $n \ge n_0$, $P(C_L) > 1 \delta$.
- Under conditions III there is a sequence L_n tending to ∞ so slowly that $P(C_{L_n}) \rightarrow 1$.

Point: conditions get weaker as conclusions get weaker. Many possible conditions in literature. See book by Zacks for some precise conditions.



Asymptotic Normality

- Study shape of log likelihood near the true value of θ .
- Assume $\hat{\theta}$ is a root of the likelihood equations close to θ_0 .
- Taylor expansion (1 dimensional parameter θ):

$$egin{aligned} U(\hat{ heta}) =& 0 \ &= U(heta_0) + U'(heta_0)(\hat{ heta} - heta_0) \ &+ U''(ilde{ heta})(\hat{ heta} - heta_0)^2/2 \end{aligned}$$

for some $\tilde{\theta}$ between θ_0 and $\hat{\theta}$.

 WARNING: This form of the remainder in Taylor's theorem is not valid for multivariate θ.



Asymptotic normality continued

- Derivatives of U are sums of n terms.
- So each derivative should be proportional to *n* in size.
- Second derivative is multiplied by the square of the small number $\hat{\theta} \theta_0$ so should be negligible compared to the first derivative term.
- Ignoring second derivative term get

$$-U'(heta_0)(\hat{ heta}- heta_0)pprox U(heta_0)$$

• Now look at terms U and U'.



Asymptotic normality continued

Normal case:

$$U(\theta_0) = \sum (X_i - \mu_0)$$

has a normal distribution with mean 0 and variance n (SD \sqrt{n}). • Derivative is

$$U'(\mu)=-n$$
 .

- Next derivative U'' is 0.
- Notice: both U and U' are sums of iid random variables.

Let

$$U_i = \frac{\partial \log f}{\partial \theta}(X_i, \theta_0)$$

and

$$V_i = -\frac{\partial^2 \log f}{\partial \theta^2}(X_i, \theta)$$



- In general, $U(\theta_0) = \sum U_i$ has mean 0 and approximately a normal distribution.
- Here is how we check that:

$$E_{\theta_0}(U(\theta_0)) = nE_{\theta_0}(U_1)$$

$$= n \int \frac{\partial \log(f(x,\theta_0))}{\partial \theta} f(x,\theta_0) dx$$

$$= n \int \frac{\partial f(x,\theta_0)}{\partial \theta} f(x,\theta_0) dx$$

$$= n \int \frac{\partial f}{\partial \theta} (x,\theta_0) dx$$

$$= n \frac{\partial}{\partial \theta} \int f(x,\theta) dx \Big|_{\theta=\theta_0}$$

$$= n \frac{\partial}{\partial \theta} 1$$

$$= 0$$



- Notice: interchanged order of differentiation and integration at one point.
- This step is usually justified by applying the dominated convergence theorem to the definition of the derivative.
- Differentiate identity just proved:

$$\int \frac{\partial \log f}{\partial \theta}(x,\theta) f(x,\theta) dx = 0$$

• Take derivative of both sides wrt θ ; pull derivative under integral sign:

$$\int \frac{\partial}{\partial \theta} \left[\frac{\partial \log f}{\partial \theta} (x, \theta) f(x, \theta) \right] dx = 0$$

• Do the derivative and get

$$-\int \frac{\partial^2 \log(f)}{\partial \theta^2} f(x,\theta) dx = \int \frac{\partial \log f}{\partial \theta}(x,\theta) \frac{\partial f}{\partial \theta}(x,\theta) dx$$
$$= \int \left[\frac{\partial \log f}{\partial \theta}(x,\theta)\right]^2 f(x,\theta) dx$$

• Definition: The Fisher Information is

$$I(\theta) = -E_{\theta}(U'(\theta)) = nE_{\theta_0}(V_1)$$

- We refer to $\mathcal{I}(heta_0) = E_{ heta_0}(V_1)$ as the information in 1 observation.
- The idea is that *I* is a measure of how curved the log likelihood tends to be at the true value of *θ*.
- Big curvature means precise estimates.
- Our identity above is

$$I(\theta) = Var_{\theta}(U(\theta)) = n\mathcal{I}(\theta)$$

• Now we return to our Taylor expansion approximation

$$-U'(heta_0)(\hat{ heta}- heta_0)pprox U(heta_0)$$

and study the two appearances of U.

- Have shown $U = \sum U_i$ is a sum of iid mean 0 random variables.
- The central limit theorem thus proves that

$$n^{-1/2}U(\theta_0) \Rightarrow N(0,\sigma^2)$$

where $\sigma^2 = \operatorname{Var}(U_i) = E(V_i) = \mathcal{I}(\theta)$.



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Next observe that

$$-U'(heta) = \sum V_i$$

where again

$$V_i = -\frac{\partial U_i}{\partial \theta}$$

• The law of large numbers can be applied to show

$$-U'(heta_0)/n o E_{ heta_0}[V_1] = \mathcal{I}(heta_0)$$

Now manipulate our Taylor expansion as follows

$$n^{1/2}(\hat{\theta}-\theta_0)\approx\left[\frac{\sum V_i}{n}\right]^{-1}\frac{\sum U_i}{\sqrt{n}}$$

• Apply Slutsky's Theorem to conclude that the right hand side of this converges in distribution to $N(0, \sigma^2/\mathcal{I}(\theta)^2)$ which simplifies, because of the identities, to $N\{0, 1/\mathcal{I}(\theta)\}$.

Summary

In regular families: assuming θ̂ = θ̂_n is a consistent root of U(θ) = 0.
 n^{-1/2}U(θ₀) ⇒ MVN(0, *I*) where

$$\mathcal{I}_{ij} = \mathrm{E}_{\theta_0} \left\{ V_{1,ij}(\theta_0) \right\}$$

and

$$V_{k,ij}(heta) = -rac{\partial^2 \log f(X_k, heta)}{\partial heta_i \partial heta_j}$$

• If $\mathbf{V}_k(\theta)$ is the matrix $[V_{k,ij}]$ then

$$\frac{\sum_{k=1}^{n} \mathbf{V}_{k}(\theta_{0})}{n} \to \mathcal{I}$$

• If $\mathbf{V}(\theta) = \sum_{k} \mathbf{V}_{k}(\theta)$ then $\{\mathbf{V}(\theta_{0})/n\} n^{1/2} (\hat{\theta} - \theta_{0}) - n^{-1/2} U(\theta_{0}) \rightarrow 0$

in probability as $n \to \infty$.

Summary Continued

Also

$$\{\mathbf{V}(\hat{\theta})/n\}n^{1/2}(\hat{\theta}-\theta_0)-n^{-1/2}U(\theta_0)\to 0$$

in probability as $n \to \infty$.

• $n^{1/2}(\hat{\theta} - \theta_0) - \{\mathcal{I}(\theta_0)\}^{-1}U(\theta_0) \to 0$ in probability as $n \to \infty$. • $n^{1/2}(\hat{\theta} - \theta_0) \Rightarrow MVN(0, \mathcal{I}^{-1}).$

In general (not just iid cases)

$$egin{aligned} &\sqrt{I(heta_0)}(\hat{ heta}- heta_0) \Rightarrow \textit{N}(0,1) \ &\sqrt{I(\hat{ heta})}(\hat{ heta}- heta_0) \Rightarrow \textit{N}(0,1) \ &\sqrt{V(heta_0)}(\hat{ heta}- heta_0) \Rightarrow \textit{N}(0,1) \ &\sqrt{V(\hat{ heta})}(\hat{ heta}- heta_0) \Rightarrow \textit{N}(0,1) \end{aligned}$$

where $V = -\ell''$ is the so-called *observed information*, the negative second derivative of the log-likelihood.

 Note: If the square roots are replaced by matrix square roots we c let θ be vector valued and get MVN(0, I) as the limit law.



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- Why all these different forms?
- Use limit laws to test hypotheses and compute confidence intervals.
- Test $H_o: \theta = \theta_0$ using one of the 4 quantities as test statistic.
- Find confidence intervals using quantities as *pivots*.
- E.g.: second and fourth limits lead to confidence intervals

$$\hat{ heta} \pm z_{lpha/2} / \sqrt{I(\hat{ heta})}$$

and

$$\hat{ heta} \pm z_{lpha/2} / \sqrt{V(\hat{ heta})}$$

respectively.

• The other two are more complicated.



• For iid $N(0, \sigma^2)$ data we have

$$V(\sigma) = \frac{3\sum X_i^2}{\sigma^4} - \frac{n}{\sigma^2}$$

and

$$I(\sigma) = \frac{2n}{\sigma^2}$$

 The first line above then justifies confidence intervals for σ computed by finding all those σ for which

$$\left|\frac{\sqrt{2n}(\hat{\sigma}-\sigma)}{\sigma}\right| \leq z_{\alpha/2}$$

- Similar interval can be derived from 3rd expression, though this is much more complicated.
- Usual summary: mle is consistent and asymptotically normal with an asymptotic variance which is the inverse of the Fisher information.



Problems with maximum likelihood

- Many parameters lead to poor approximations. MLEs can be far from right answer.
- See homework for Neyman Scott example where MLE is not consistent.
- Multiple roots of the likelihood equations: you must choose the right root.
- Start with different, consistent, estimator; apply iterative scheme like Newton Raphson to likelihood equations to find MLE.
- Not many steps of NR generally required if starting point is a reasonable estimate.



Finding (good) preliminary Point Estimates

Method of Moments

- Basic strategy: set sample moments equal to population moments and solve for the parameters.
- **Definition**: The *r*th sample moment (about the origin) is

$$\frac{1}{n}\sum_{i=1}^n X_i^r$$

• The r^{th} population moment is

 $E(X^r)$

• (Central moments are

$$\frac{1}{n}\sum_{i=1}^n (X_i - \bar{X})^r$$

 $\mathbb{E}[(X-\mu)^r]$.

and

Method of moments continued

 If we have p parameters we can estimate the parameters θ₁,..., θ_p by solving the system of p equations:

$$\mu_1 = \bar{X}$$
$$\mu'_2 = \overline{X^2}$$

and so on to

$$\mu'_p = \overline{X^p}$$

• Remember that population moments μ_k^\prime are formulas involving the parameters.



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Gamma Example

• The Gamma (α, β) density is

$$f(x; \alpha, \beta) = \frac{1}{\beta \Gamma(\alpha)} \left(\frac{x}{\beta}\right)^{\alpha - 1} \exp\left[-\frac{x}{\beta}\right] \mathbb{1}(x > 0)$$

and has

$$\mu_1 = \alpha\beta$$

and

$$\mu_2' = \alpha(\alpha + 1)\beta^2.$$

• This gives the equations

$$\alpha\beta = \overline{X}$$
$$\alpha(\alpha+1)\beta^2 = \overline{X^2}$$

or

$$\alpha\beta = \overline{X}$$
$$\alpha\beta^2 = \overline{X^2} - \overline{X}^2$$



Gamma continued

• Divide the second equation by the first to find the method of moments estimate of β is

$$\tilde{eta} = (\overline{X^2} - \overline{X}^2)/\overline{X}$$
.

• Then from the first equation get

$$\tilde{\alpha} = \overline{X}/\tilde{\beta} = (\overline{X})^2/(\overline{X^2} - \overline{X}^2).$$

• Method of moments equations much easier to solve than likelihood equations which involve *digamma* ftn

$$\psi(\alpha) = \frac{d}{d\alpha} \log(\Gamma(\alpha))$$

• Score function has components

$$U_{\beta} = \frac{\sum X_i}{\beta^2} - n\alpha/\beta$$

and

$$U_{\alpha} = -n\psi(\alpha) + \sum \log(X_i) - n\log(\beta).$$



Gamma continued

• You can solve for β in terms of α to leave you trying to find a root of the equation

$$-n\psi(\alpha) + \sum \log(X_i) - n\log(\sum X_i/(n\alpha)) = 0$$

• To use Newton Raphson on this you begin with the preliminary estimate $\hat{\alpha}_1 = \tilde{\alpha}$ and then compute iteratively

$$\hat{\alpha}_{k+1} = \frac{\overline{\log(X)} - \psi(\hat{\alpha}_k) - \log(\overline{X}) / \hat{\alpha}_k}{1 / \alpha - \psi'(\hat{\alpha}_k)}$$

until the sequence converges.

- Computation of ψ' , the trigamma function, requires special software.
- Web sites like netlib and statlib are good sources for this sort of things

Estimating Equations

- Same large sample ideas arise whenever estimates derived by solving some equation.
- Example: large sample theory for Generalized Linear Models.
- Suppose *Y_i* is number of cancer cases in some group of people characterized by values *x_i* of some covariates.
- Think of x_i as containing variables like age, or a dummy for sex or average income or
- Possible parametric regression model: Y_i has a Poisson distribution with mean μ_i where the mean μ_i depends somehow on x_i.
- Typically assume $g(\mu_i) = \beta_0 + x_i\beta$; g is **link** function.
- Often g(μ) = log(μ) and x_iβ is a matrix product: x_i row vector, β column vector.



GLM: "Linear regression model with Poisson errors"

- Special case $log(\mu_i) = \beta x_i$ where x_i is a scalar.
- The log likelihood is simply (ignoring irrelevant factorials)

$$\ell(\beta) = \sum (Y_i \log(\mu_i) - \mu_i).$$

• The score function is, since $log(\mu_i) = \beta x_i$,

$$U(\beta) = \sum (Y_i x_i - x_i \mu_i) = \sum x_i (Y_i - \mu_i).$$

- Notice again that the score has mean 0 when you plug in the true parameter value.
- Key observation: no need to believe Y_i has Poisson distribution to make solving equation U = 0 sensible.
- Suppose only that $\log(E(Y_i)) = x_i\beta$.
- Then we have assumed that $E_{\beta}(U(\beta)) = 0$.
- Key condition to prove existence of consistent root of likelihood equations; here needed, roughly, to prove equation $U(\beta) = 0$ has consistent root $\hat{\beta}$.



• Ignoring higher order terms in a Taylor expansion will give

$$V(\beta)(\hat{\beta}-\beta) \approx U(\beta)$$

where V = -U'.

- In mle case had identities relating expectation of V to variance of U.
- In general here we have

$$\operatorname{Var}(U) = \sum x_i^2 \operatorname{Var}(Y_i).$$

• If Y_i is Poisson with mean μ_i (and so $Var(Y_i) = \mu_i$) this is

$$\operatorname{Var}(U) = \sum x_i^2 \mu_i$$
.

Moreover we have

$$V_i = x_i^2 \mu_i$$

and so

$$V(\beta) = \sum x_i^2 \mu_i \, .$$



• The central limit theorem (the Lyapunov kind) will show that $U(\beta)$ has an approximate normal distribution with variance $\sigma_U^2 = \sum x_i^2 \operatorname{Var}(Y_i)$ and so

$$\hat{\beta} - \beta \approx N(0, \sigma_U^2 / (\sum x_i^2 \mu_i)^2)$$

If Var(Y_i) = μ_i, as it is for the Poisson case, the asymptotic variance simplifies to 1/∑x_i²μ_i.



Other estimating equations

 If w_i is any set of deterministic weights (possibly depending on μ_i) then could define

$$U(\beta) = \sum w_i(Y_i - \mu_i).$$

- Can still conclude that U = 0 probably has a consistent root which has an asymptotic normal distribution.
- Idea widely used:
- Example: Generalized Estimating Equations, Zeger and Liang.
- Abbreviation: GEE.
- Called by econometricians Generalized Method of Moments.

Definition: An estimating equation is unbiased if

 $E_{\theta}(U(\theta))=0$



Unbiased estimating equations

Theorem

Suppose $\hat{\theta}$ is a consistent root of the unbiased estimating equation

$$U(\theta)=0.$$

Let V = -U'. Suppose there is a sequence of constants $B(\theta)$ such that

V(heta)/B(heta)
ightarrow 1

and let

$$\mathsf{A}(heta) = \mathsf{Var}_{ heta}(\mathsf{U}(heta))$$
 and $\mathsf{C}(heta) = \mathsf{B}(heta)\mathsf{A}^{-1}(heta)\mathsf{B}(heta).$

Then

$$egin{aligned} &\sqrt{C(heta_0)}(\hat{ heta}- heta_0) \Rightarrow \textit{N}(0,1) \ &\sqrt{C(\hat{ heta})}(\hat{ heta}- heta_0) \Rightarrow \textit{N}(0,1) \end{aligned}$$



- Other ways to estimate A, B and C lead to same conclusions.
- There are multivariate extensions using matrix square roots.

