

Physics 101.

Lecture 17.

Monday, Feb. 10, 2003.

Topics Covered:

Rotational Dynamics

Static equilibrium of a rigid body.

Ref: 11-1, 2, 3, 4, 5, Dr. Boal's Notes Lec #20. 19.

• Rotational Dynamics

— Newton's 2nd Law for rotation.

$$\tau = I\alpha.$$

τ — Net Torque

I — moment of inertia

α — angular acceleration.

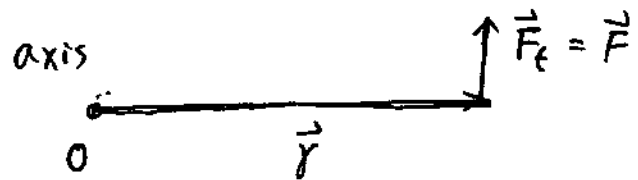
τ , I , α are all about the same axis of rotation.

• Torque of a force

e.g: Opening a Door.

(1). When $\vec{F} \perp \vec{r}$.

(i.e., $\vec{F} = \vec{F}_t$).

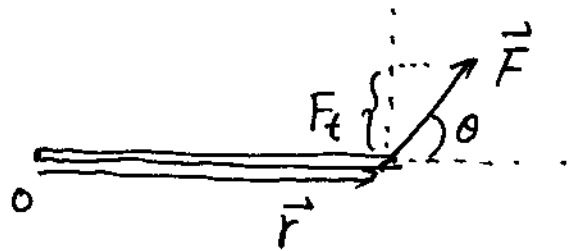


$$\tau = r \cdot F_t$$

F_t — tangential force.

(2). When $\vec{F}$ is not $\perp \vec{r}$.

Only the tangential component
of the force contribute to the torque:



$$\boxed{\tau = r F_t} = r \cdot F \cdot \sin \theta \quad \left(\theta \text{ is the angle between } \vec{F} \text{ and } \vec{r} \right)$$

— Another way to view ~~the~~ $r \cdot F \cdot \sin \theta$

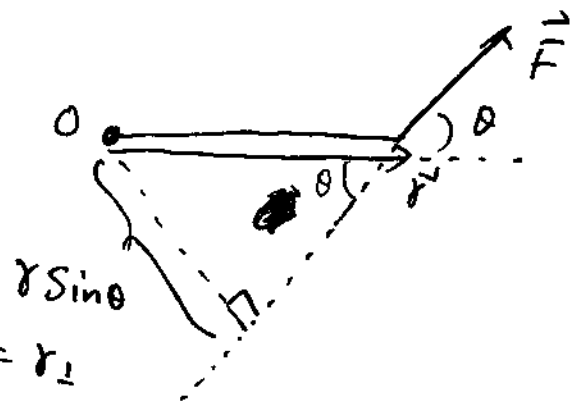
$$\tau = r F \sin \theta$$

$$= F \cdot r \cdot \sin \theta$$

$$\boxed{\tau = r_{\perp} F}$$

$r_{\perp}$ — moment arm.

$= r_{\perp}$



Perpendicular distance from O to the $\vec{F}$ -line.

e.g. #19. of Fall-2002 final exam. (a)

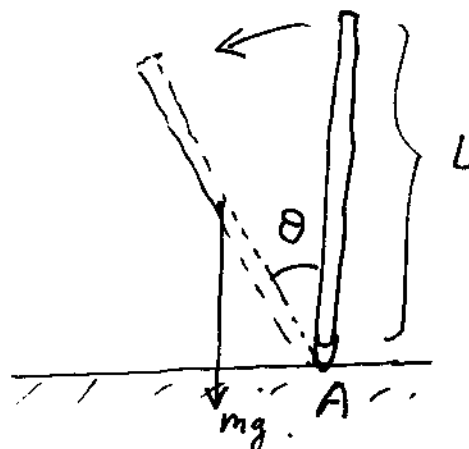
A 16-cm pencil. (uniform rod) is released.

Q:

$\alpha = ?$ when $\theta = 30^\circ$.

$\uparrow$
rotational dynamics problem.

$$\alpha = \frac{\tau}{I}$$



~~Fixed~~ Fixed point: A — axis of rotation.

τ — from gravity only.

(Normal force, frictional force go through A).

$$I = \frac{1}{3} m L^2$$

$$\tau = mg \underbrace{\frac{L}{2} \cdot \sin \theta}_{r_{\perp}}$$

$r_{\perp}$ — moment arm.

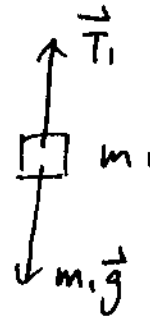
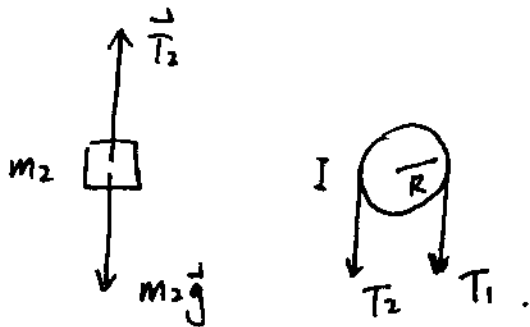
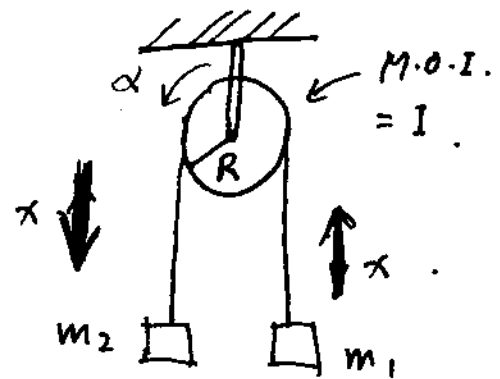
$$\therefore \alpha = \frac{mg \frac{L}{2} \cdot \sin \theta}{\frac{1}{3} m L^2}$$

$$= \frac{3g \sin \theta}{2L}$$

$$= 46 \text{ rad/s}^2$$

e.g: Atwood's Machine

A string with a mass at each end runs without slipping over a pulley.



Typically.

Given: m_1, m_2, R, I .

find: T_1, T_2, a, α .

~~$T_2 = m_2 g = m_2 a$~~

$$m_2 g - T_2 = m_2 a \quad (1)$$

$$T_1 - m_1 g = m_1 a \quad (2)$$

$$T_2 R - T_1 R = I \alpha \quad (3)$$

$$\text{kinematics relation: } a = \alpha \cdot R \quad (4)$$

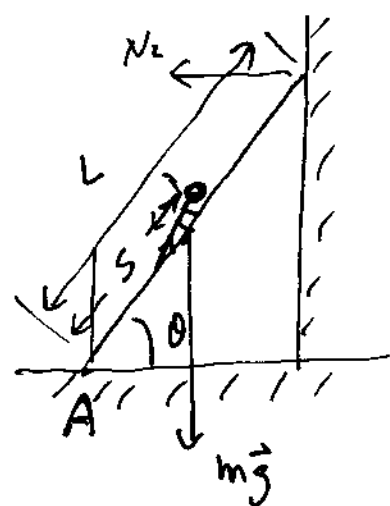
solve $\{1, 2, 3, 4\}$ for a, T_1, T_2, α .

- static equilibrium of a rigid body.

$$\Sigma \vec{F} = 0 \quad (\because \vec{a}_{c.m.} = 0)$$

$$\Sigma \tau = 0 \quad (\because \alpha = 0)$$

e.g. A man climbs a massless ladder against a frictionless wall. If the coefficient of friction between the ladder and the floor is μ_s , How far up the ladder can the man climb before the ladder slips?

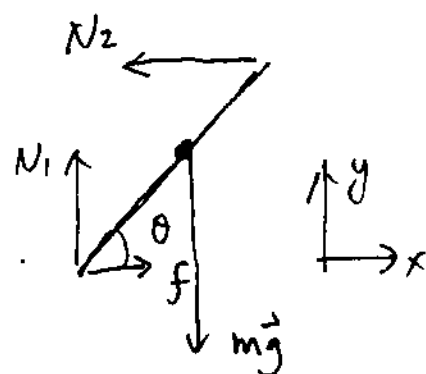


static equilibrium:

$$\Sigma F_i = 0.$$

$$\Sigma \tau_i = 0 \quad \left\{ \begin{array}{l} \text{choose the axis} \\ \text{so that many unknown} \\ \text{forces don't have } \tau \end{array} \right.$$

e.g.: about A.



$$\begin{cases} f - N_2 = 0 \\ N_1 - mg = 0 \end{cases}$$

$$N_1 = mg$$

$$N_2 = f = \mu_s N_1 = \mu_s mg$$

about to slip.

$$N_2 L \sin \theta - mg s \cos \theta = 0$$

$$s = \mu_s L \tan \theta$$

↑ max.

when the man climb higher.
 large cw torque. $\rightarrow$ it will slip.