## Rotation as Translational Motion

For a particle of mass $m$ moving in 3-D space

$$
\hat{\mathrm{H}}=\hat{\mathrm{T}}+\hat{\mathrm{V}}=-\frac{\hbar^{2}}{2 m} \nabla^{2}+V(r, \theta, \phi)=-\frac{\hbar^{2}}{2 m}\left(\frac{\partial^{2}}{\partial r^{2}}+\frac{2}{r} \frac{\partial}{\partial r}+\frac{1}{r^{2}} \Lambda^{2}\right)+V(r, \theta, \phi)
$$

where $\quad \Lambda^{2}=\frac{\partial^{2}}{\partial \theta^{2}}+\frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \theta}+\frac{1}{\sin ^{2} \theta} \frac{\partial^{2}}{\partial \phi^{2}}$ Legendrian
Suppose the particle is confined to the surface of a sphere, i.e. $r=R$.

$$
\hat{\mathrm{H}}=-\frac{\hbar^{2}}{2 m R^{2}} \Lambda^{2} \quad \text { a function of } \theta \text { and } \phi \text { only }
$$

A rigid rotator is a pair of masses at a fixed distance apart $(R)$, freely rotating

$$
\begin{aligned}
\hat{\mathrm{H}}=-\frac{\hbar^{2}}{2 \mu R^{2}} \Lambda^{2}=-\frac{\hbar^{2}}{2 I} \Lambda^{2} \quad I & =\mu R^{2} \\
\mu & =\frac{m_{1} m_{2}}{m_{1}+m_{2}}
\end{aligned}
$$

If the particle is confined to a ring (the equator), $\theta=\pi / 2$.

$$
\hat{\mathrm{H}}=-\frac{\hbar^{2}}{2 I} \frac{\mathrm{~d}^{2}}{\mathrm{~d} \phi^{2}}=-\frac{\hbar^{2}}{2 \mu} \frac{\mathrm{~d}^{2}}{\mathrm{ds}^{2}} \quad s \text { is the distance along the circumference }
$$

## Laplacian in Various Coordinate Systems Enrichment

$$
\begin{aligned}
\nabla^{2} & =\frac{\partial^{2}}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{2}}+\frac{\partial^{2}}{\partial z^{2}} & & \text { cartesian } \\
& =\frac{\partial^{2}}{\partial r^{2}}+\frac{1}{r} \frac{\partial}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2}}{\partial \theta^{2}}+\frac{\partial^{2}}{\partial z^{2}} & & \text { cylindrical } \\
& =\frac{\partial^{2}}{\partial r^{2}}+\frac{2}{r} \frac{\partial}{\partial r}+\frac{1}{r^{2}} \Lambda^{2} & & \text { spherical } \\
\text { where } \quad \Lambda^{2} & =\frac{\partial^{2}}{\partial \theta^{2}}+\frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \theta}+\frac{1}{\sin ^{2} \theta} \frac{\partial^{2}}{\partial \phi^{2}} & & \text { Legendrian }
\end{aligned}
$$

## Spherical Polar Coordinates

$$
\int d \tau=\int_{0}^{R} \int_{0}^{2 \pi} \int_{0}^{\pi} r^{2} \sin \theta d \theta d \phi d r=\int_{0}^{R} r^{2} d r \int_{0}^{2 \pi} d \phi \int_{0}^{\pi} \sin \theta d \theta=\int_{0}^{R} 4 \pi r^{2} d r=\frac{4}{3} \pi R^{3}
$$

volume

of sphere

## Internal Coordinates and Reduced Mass

If the potential energy of a system depends only on the internal coordinates of the system, then the motion of the centre of mass can always be separated from the internal motion.

Consider two point masses $m_{1}$ and $m_{2}$, both in motion and interacting with each other.

$$
E=\frac{1}{2} m_{1}\left(\dot{x}_{1}^{2}+\dot{y}_{1}^{2}+\dot{z}_{1}^{2}\right)+\frac{1}{2} m_{2}\left(\dot{x}_{2}^{2}+\dot{y}_{2}^{2}+\dot{z}_{2}^{2}\right)+V\left(x_{1}, y_{1}, z_{1}, x_{2}, y_{2}, z_{2}\right)
$$

Define centre of mass coordinates: $\quad X=\frac{m_{1} x_{1}+m_{2} x_{2}}{m_{1}+m_{2}} \quad Y=\frac{m_{1} y_{1}+m_{2} y_{2}}{m_{1}+m_{2}} \quad Z=\frac{m_{1} z_{1}+m_{2} z_{2}}{m_{1}+m_{2}}$ and internal coordinates: $x=x_{1}-x_{2} \quad y=y_{1}-y_{2} \quad z=z_{1}-z_{2}$
then

$$
E=\underbrace{\frac{1}{2}\left(m_{1}+m_{2}\right)\left(\dot{X}^{2}+\dot{Y}^{2}+\dot{Z}^{2}\right)}_{\text {translational energy }}+\underbrace{\frac{1}{2} \mu\left(\dot{x}^{2}+\dot{y}^{2}+\dot{z}^{2}\right)+V(x, y, z)}_{\mu=\frac{m_{1} m_{2}}{m_{1}+m_{2}}}
$$

## The Particle on a Ring

$$
\hat{\mathrm{H}} \Phi=E \Phi \quad \text { where } \quad \hat{\mathrm{H}}=-\frac{\hbar^{2}}{2 I} \frac{\mathrm{~d}^{2}}{\mathrm{~d} \phi^{2}}
$$

The Schrödinger Equation looks like that of the free particle, so the solutions are similar:

$$
\Phi_{m}=\frac{1}{\sqrt{2 \pi}} \mathrm{e}^{i m \phi} \quad E_{m}=\frac{\hbar^{2}}{2 I} m^{2} \quad m=0, \pm 1, \pm 2, \ldots
$$ not mass!

Quantization is due to a cyclic boundary condition: $\quad \Phi(\phi)=\Phi(\phi+2 m \pi)$
Except for $m=0$ the states are twofold degenerate.
Real functions can be constructed by taking linear combinations:

$$
\begin{aligned}
& \Phi_{m}^{+}=\frac{1}{\sqrt{2}}\left[\Phi_{m}+\Phi_{-m}\right]=\frac{1}{\sqrt{\pi}} \cos (|m| \phi) \\
& \Phi_{m}^{-}=\frac{-i}{\sqrt{2}}\left[\Phi_{m}-\Phi_{-m}\right]=\frac{1}{\sqrt{\pi}} \sin (|m| \phi)
\end{aligned}
$$

## The Particle on a Ring - 2

$$
\begin{aligned}
& \Phi_{m}^{+}=\frac{1}{\sqrt{\pi}} \cos (|m| \phi) \\
& \Phi_{m}^{-}=\frac{1}{\sqrt{\pi}} \sin (|m| \phi)
\end{aligned}
$$

Except for $m=0$ the states are twofold degenerate.

$$
\Phi(\phi)=\Phi(\phi+2 m \pi)
$$

m



## The Particle on a Sphere

$$
\Lambda^{2} \Psi(\theta, \phi)=-\frac{2 I}{\hbar^{2}} E \Psi(\theta, \phi)
$$

This type of equation is "well known" (to applied mathematicians):

$$
\Lambda^{2} \mathrm{Y}_{l m}(\theta, \phi)=-l(l+1) \mathrm{Y}_{l m}(\theta, \phi) \quad\left\{\begin{array}{c}
l=0,1,2, \ldots \\
m=0, \pm 1, \pm 2, \ldots, \pm l
\end{array}\right.
$$

The solutions are the
spherical harmonics: $\quad \mathrm{Y}_{l m}(\theta, \phi)=\frac{1}{\sqrt{2 \pi}} \Theta_{l m}(\theta) \mathrm{e}^{\mathrm{im} \mathrm{\phi}}$

| $l$ | $m$ | $\Theta_{l m}$ |
| :--- | :--- | :--- |
| 0 | 0 | $\sqrt{1 / 2}$ |
| 1 | 0 | $\sqrt{3 / 2} \cos \theta$ |
| 1 | $\pm 1$ | $\sqrt{3 / 4} \sin \theta$ |
| 2 | 0 | $\sqrt{5 / 8}\left(3 \cos ^{2} \theta-1\right)$ |
| 2 | $\pm 1$ | $\sqrt{15 / 4} \sin \theta \cos \theta$ |
| 2 | $\pm 2$ | $\sqrt{15 / 16} \sin ^{2} \theta$ |

## Spherical Harmonics: Real Wavefunctions

$$
\begin{aligned}
& \mathrm{Z}_{l, m}^{+}=(1 / \sqrt{2})\left[\mathrm{Y}_{l, m}+\mathrm{Y}_{l,-m}\right]=(1 / \sqrt{\pi}) \cos (|m| \phi) \Theta_{l m}(\theta) \\
& \mathrm{Z}_{l, m}^{-}=(-i / \sqrt{2})\left[\mathrm{Y}_{l, m}-\mathrm{Y}_{l,-m}\right]=(1 / \sqrt{\pi}) \sin (|m| \phi) \Theta_{l m}(\theta)
\end{aligned}
$$

$l=2$


$$
l=1
$$

$l=0$

$m=-2$
$m=-1$
$m=0$
$m=+1$
$m=+2$

## Rotational/Orbital Angular Momentum

The energy of a rotating body (or particle in orbit) is quantized.

$$
E_{l m}=\frac{\hbar^{2}}{2 I} l(l+1)
$$

$$
\left\{\begin{array}{c}
l=0,1,2, \ldots \\
m=0, \pm 1, \pm 2, \ldots, \pm l
\end{array}\right.
$$

There are $(2 l+1)$ degenerate states which have the same energy determined by the quantum number $l$.
The different states, labelled by quantum numbers $m$, are related by simple symmetry transformations, i.e. they correspond to different orientations in space.

The orientation of a rotating body is quantized.

Example for $l=2$ :

$+{ }^{+|m| \hbar}$


## Rotational Spectra of Diatomic Molecules

$$
\begin{aligned}
& \text { have a dipole moment. }
\end{aligned}
$$

Transitions: $\quad \Delta E=E_{J+1}-E_{J}=2 B(J+1)=2 B, 4 B, 6 B, \ldots$


## The Moment of Inertia of a Rotating Molecule



## Moments of Inertia - Principal Axes

Consider a molecule as a system of point masses whose positions are fixed relative to each other.

Centre of gravity: $\quad \overrightarrow{r_{0}}=\frac{\sum_{k} m_{k} \vec{r}_{k}}{\sum_{k} m_{k}}$
Put a Cartesian coordinate system at this centre and define the three moments of inertia.

$$
I_{x}=\sum_{k} m_{k} r_{k x}^{2} \text { etc. } \quad \begin{aligned}
& r_{k x} \text { is the perpendicular distance } \\
& \text { of nucleus } k \text { from the } x \text { axis }
\end{aligned}
$$

If $\quad I_{x y}=m_{k} r_{k x} r_{k y} \neq 0 \quad$ etc. rotate the coordinate system until $\quad I_{x^{\prime} y^{\prime}}=I_{y^{\prime} z^{\prime}}=I_{z^{\prime} x^{\prime}}=0$ etc.

It is always possible to find unique principal axes and thus calculate principal moments of inertia $\left(I_{a} I_{b} I_{c}\right)$.

| Linear Rotator | $I_{a}=I_{b} \neq 0$ | $I_{c}=0$ |
| :---: | :--- | :---: |
| Spherical Top | $I_{a}=I_{b}=I_{c}$ | $I_{c} \neq 0$ |
| Symmetric Top | $I_{a}=I_{b} \neq I_{c}$ | $I_{c} \neq 0$ |
| prolate top | $I_{a}=I_{b}>I_{c}$ |  |
| oblate top | $I_{a}=I_{b}<I_{c}$ |  |
| Asymmetric Top | $I_{a} \neq I_{b} \neq I_{c}$ |  |

## Moments of Inertia

Linear Molecules




$I=\frac{8}{3} m_{1} r^{2}$

Symmetric Tops




